



GNX Assembler

Version 4

Series 32000[®]

GNX — Version 4.4 Assembler Reference Manual

REVISION RECORD

VERSION	RELEASE DATES	SUMMARY OF CHANGES
4.0	May 1990	First Release. Introduction of the new macro and conditional assembler. Introduction of procedure support. <i>Series 32000/EP</i> support.
4.1	Sep 1990	Enhanced macro listing control and symbolic debugging of assembly programs.
4.2	Feb 1991	Synchronization revision. No changes.
4.3	Aug 1991	Minor manual corrections.
4.4	June 1992	MS-DOS support added.

PREFACE

This document describes the GNX Series 32000 Assembler, a support program that assembles Series 32000 Assembly language source programs. This manual defines the syntax, format, and function of the following:

- Series 32000 Assembly Language Elements
- Assembly Language Programs
- Instructions and Instruction Operands
- Assembler Directives
- Assembler Procedure Support
- · Macro and Conditional Assembly
- Series 32000 Assembler Invocation

The GNX Assembler is intended for use as a component in the *Series 32000* GNX tools family to create assembly language programs for *Series 32000*-based systems. It may be used in either a native or a cross environment.

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INTRODUCTION AND OVERVIEW

1.1 INTRODUCTION

The GNX Assembler is a support program that assembles Series 32000 Assembly Language source programs and generates relocatable object modules. Relocatable object modules may be linked to create executable load modules which may be run on Series 32000 microprocessor-based systems that support the Common Object File Format (COFF) as implemented by National Semiconductor. The Series 32000 GNX (GENIX Native and Cross-Support) language tools provide linkage and library maintenance programs.

This manual describes the GNX Assembler in detail and is organized as follows:

Chapter 1. Introduction and Overview

Introduces the GNX Assembler, summarizes its features, and describes the Series 32000 registers.

Chapter 2, Elements of the GNX Assembly Language

Describes the format of the GNX Assembly Language statements, constants, values, symbols, and expressions.

Chapter 3, GNX Assembler Programs

Describes program segments, linkage, and relocation.

Chapter 4, Instruction Operands

Describes the syntax of the GNX Assembly Language instruction operands.

Chapter 5, Series 32000 Instruction Set

Lists the syntax of the Series 32000 instruction set.

Chapter 6, GNX Assembler Directives

Defines the syntax and function of the GNX Assembler directives.

Chapter 7, Procedure Support

Provides a review of the GNX procedure support.

Chapter 8, Macro and Conditional Assembly

Describes the new macro-assembler.

Chapter 9. Invocation and Operation

Describes the GNX Assembler, assembly options, output formats, error messages, and the Symbol Table.

Appendix A, Directive Summary

Summarizes the GNX Assembler directive syntax and function.

Appendix B, Reserved Symbols

Lists the GNX Assembler reserved symbols.

Appendix C, Program Examples

Provides GNX Assembly Language program examples.

Appendix D, Initialization of Interrupts

Illustrates interrupt initialization for a Series 32000 system.

Appendix E, Series 32000 Standard Calling Conventions

Describes elements of the Series 32000 standard calling sequence.

Appendix F, Compatibly-Supported Macros

Describes the Version 2.0 macro-assembler.

Appendix G, Glossary

Provides a glossary of GNX terms.

1.2 OVERVIEW OF THE GNX ASSEMBLER FEATURES

The GNX Assembler provides a number of features for efficient assembly language programming.

Input and Output Files. The GNX Assembler generates an object code file, an optional listing file, an optional cross-reference listing, and an optional symbol table dump from an assembler source file. The object code file consists of assembled statements suitable for execution after the appropriate linking process. The listing file consists of the source file statements, and the assembled code, if the source file assembles successfully; otherwise, the listing file consists of error messages and source file statements that caused the error. Input and output files, listing file format, cross-reference listing symbol table dump, and error messages are described in Chapter 9.

Instruction Set. The GNX Assembler supports the complete *Series 32000* instruction set, including the integer, quick integer, extended integer, bit, bit field, Boolean, string, packed decimal, array, block, processor control, and processor service instructions. The GNX Assembler also supports memory management and floating-point instruction sets for systems with the optional NS32082 or NS32382 Memory Management Unit, NS32081, NS32181, NS32381 or NS32580 Floating-Point Unit, and NS32CG16, NS32CG160 and NS32FX16 High Performance Graphic Instructions. Chapter 5 defines the syntax of all *Series 32000* instructions. Instruction operation is described in detail in the *Series 32000* and *Series 32000/EP Programmer's Reference Manual*.

Addressing Modes. The GNX Assembler supports eight general addressing modes: register, register relative, memory, memory relative, immediate, absolute, top of stack, external, and also provides scaled indexing for all of these modes except immediate.

Data Types. The GNX Assembler recognizes a variety of operand data types including integers (byte, word, double-word), single- and double-precision floating-point numbers, packed decimal numbers, bits, and bit fields.

GNX Assembler Directives. The GNX Assembler provides directives to create symbolic labels, generate data, allocate storage, control program listings, control linkage, control line number table, control program segments, define module table entry, define symbol table entry, define macros, and define file name.

1.3 SERIES 32000 REGISTERS

The Series 32000 system has four sets of registers; these are described in Sections 1.3.1 through 1.3.4.

- General Purpose registers
- Dedicated registers
- Floating-Point registers
- Memory Management registers

1.3.1 General Purpose Registers

There are eight General Purpose registers. The register names are: r0, r1, r2, r3, r4, r5, r6, and r7. The General Purpose registers provide temporary storage for address computation, arithmetic operations, and parameter passing.

Each register is 32 bits long and may be used in byte, word, and double-word operations. Byte operations affect the register's low-order eight bits only; word operations affect the low-order 16 bits, and double-word operations affect all 32 bits.

General Purpose registers may be combined to form even/odd register pairs: r0/r1, r2/r3, r4/r5, r6/r7. A register pair is 64 bits in length and may hold word, double-word, and quad-word data. The odd register holds the high-order byte(s); the even register holds low-order byte(s). Register pair names are: r0, r2, r4, and r6.

1.3.2 Dedicated Registers

The eight Dedicated registers store memory addresses and status information needed for CPU operation:

Register	Name	Contents
Program Counter	pc	address of current instruction
Static Base	sb	address of current Static Base Area
User Stack Pointer	sp1	address of top of User Stack
Interrupt Stack Pointer	sp0	address of top of Interrupt Stack
Frame Pointer	fp	address of current Frame
Interrupt Base	intbase	address of Interrupt Dispatch Table
Module	mod	address of current Module Descriptor
Processor Status	psr	Processor Status flags
	r	

The pc, sb, sp1, sp0, fp, and intbase registers are each 32 bits long; however, these registers contain memory addresses in which the number of bits used for address representation and calculation depends on the actual CPU used. 24 bits are used for address representation in the NS32Oxx and the NS32CG16 CPUs. These CPUs will be referred to as 24-pin address processors. 32 bits are used for address representation in the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and NS32GX320 CPUs. These CPUs will be referred to as 32-pin address processors. The mod register contains a memory address, and the psr register contains the processor status flags. A program can work only with one of the hardware stack registers at any given time: sp0 or sp1. The CPU selects sp0 as the current stack pointer if the s bit in the psr is zero, and sp1 if the s bit is one. The GNX Assembler uses the symbol sp to refer to the currently selected stack. A program has no control over which stack will be accessed, except by changing the s bit. Consequently, the GNX Assembler does not support the symbols sp0 and sp1, and any reference to "stack" in this manual refers to the currently selected stack.

The psr status flags define the current operational mode of the CPU and the execution results of the previous instruction(s). The psr has the following form:

	Supervisor Flags				User Flags											
	x	x	х	x	i	р	s	u	n	z	f	хх	1	t	С	
,	15							8	7			<u> </u>			0	

x - reserved for future use

The status flags have the following functions:

User Flags (available to all programs)

- c is the Carry flag. On execution of an add or subtract instruction, c flag is set to 1 on a carry or a borrow and is set to 0 when neither occur.
- t is the Trace-Trap flag. The Trace-Trap flag enables/disables the system Trace-Trap (TRC). The TRC stops program execution on completion of each program instruction and permits program single-stepping. When t is 1, the trace trap is enabled. Also see p flag.
- l is the Low flag. The Low flag signals the result of an unsigned comparison between two integers. The 1 flag is set to 1 if the second integer is less than the first; 1 flag is set to 0 if the second integer is greater than, or equal to, the first.
- f is the General Condition flag. If set to 1, this flag indicates an overflow in arithmetic operations, a set bit in a bit instruction, an until/while condition in a string instruction, or an out-of-bounds subscript in a check instruction. If set to 0, this flag indicates no overflow in arithmetic operations, a clear bit in a bit instruction, no until/while condition in a string instruction, and no out-of-bounds subscript in a check

instruction.

- z is the Zero flag. The Zero flag indicates the result of the comparison between two integers. The z flag is set to 1 if the integers are equal and is set to 0 if not equal.
- n is the Negative flag. The Negative flag indicates the result of a signed comparison between two integers. The n flag is set to 1 if the second integer is less than the first and is set to 0 if the second integer is greater than, or equal to, the first.

Supervisor Flags (available to supervisor programs only)

- u is the User Mode flag. The User Mode flag sets the current mode of system operation. If u is 1, the system is in the user mode and no privileged instructions may be executed. If ua is 0, the system is in the supervisor mode and all instructions may be executed.
- s is the Stack flag. The Stack flag selects the current stack pointer. If s is 1, the User Stack Pointer (sp1) is active. If s is 0, the Interrupt Stack Pointer (sp0) is active. On an interrupt or a trap, the s bit is automatically cleared.
- p is the Trace Pending flag. The Trace Pending flag, in conjunction with the t flag, enables/disables the trace trap. At the start of an instruction, the t flag contents are copied to the p flag. At the end of the instruction, if p is 1, a trace trap is taken. If p is 0, no trace trap is taken.
- i is the Interrupt flag. The Interrupt flag enables/disables the vectored and nonvectored interrupts. If i is 1, the interrupts are enabled. If i is 0, then all interrupts except the Non-Maskable Interrupt (NMI) are disabled.

1.3.3 Floating-Point Registers

The floating-point registers for the NS32081, NS32181, NS32381, and NS32580 are described in this Section. The Floating-Point Status Register (fsr) contains the floating-point status flags. The Series 32000 Programmer's Reference Manual describes the flags in detail.

The NS32081 Registers

The NS32081 registers (f0, f1, f2, f3, f4, f5, f6 and f7) provide temporary work space for floating-point operations. Each register is 32 bits long and may hold single-precision floating-point numbers.

These registers may be combined to form even/odd register pairs: f0/f1, f2/f3, f4/f5, or f6/f7. A register pair is 64 bits in length and may hold double-precision floating-point numbers. The odd register contains the high-order bytes of the number; the even register contains the low-order bytes. Register pair names are: f0, f2, f4, and f6.

The NS32181,NS32381 and NS32580 Registers

The NS32181, NS32381 and NS32580 registers (f0, f1, f2, f3, f4, f5, f6, and f7) provide temporary work space for floating-point operations. Each register is 32 bits long and may hold single-precision floating-point numbers.

The NS32181, NS32381 and NS32580 registers (l0, l1, l2, l3, l4, l5, l6, and l7) are 64 bits long and may hold double-precision floating-point numbers.

1.3.4 Memory Management Registers

The Memory Management registers support virtual memory and program debugging.

Memory Management registers are described in detail in the Series 32000 Programmer's Reference Manual.

NS32082 MMU Registers

The following is a comprehensive list of the Memory Management registers for the NS32082. All Memory Management registers, except sc0 and sc1, are 32 bits long. Both sc0 and sc1 are 16 bits long and occupy a single 32-bit register. The assembler refers to sc0 and sc1 with the symbol sc. The sc0 register is contained in the lower 16-bit field of sc; sc1 is contained in the upper 16-bit field of sc.

Register	Name	Function					
Page Table Register 0	ptb0	Contains the base address of the level 1 Page Table.					
Page Table Register 1	ptb1	Contains the base address of the user mode level 1 Page Table (when MMU is in dual space operation).					
Error/Invalidate Address	eia	Contains, on an error, the virtual address that caused the error. When written to, causes the removal of invalid Page Table entries from the MMU Translation Buffer.					
Breakpoint Register 0	bpr0	Contains a breakpoint address. The system breaks execution when the address is accessed.					
Breakpoint Register 1	bpr1	Contains a breakpoint address. The system breaks execution when the address is accessed.					

Breakpoint Count	bent	Contains a count of the number of bpr0 breakpoint conditions that have been met. If count is 0, a break is taken. Otherwise, no break is taken.
Program Flow 0	pf0	Contains the address of the last nonsequential instruction.
Register	Name	Function
Program Flow 1	pf1	Contains the address of the next to last non-sequential instruction.
Sequential Count 0	sc0	Contains the number of sequential instructions executed since the last nonsequential instruction.
Sequential Count 1	sc1	Contains the number of sequential instructions executed prior to the last nonsequential instruction.
Memory Status Register	msr	Contains the status and control flags of the MMU.

NS32382 MMU Registers

The following is a comprehensive list of memory management registers for the NS32382. All registers except ivar0 and ivar1 can be read by the smr instruction. Ivar0 and ivar1 are write-only pseudo-registers. The tear, bear, and bdr registers are read-only registers and cannot be loaded by the lmr instruction. Writing to a read-only register has no effect on the MMU; however, avoid reading a write-only register since random data patterns may be returned.

Registers	Name	Description
Breakpoint Address Register	bar	Holds a virtual address for breakpoint address comparison during instruction and operand accesses.
Breakpoint Mask Register	bmr	Indicates which bit positions of the virtual address are to be compared when the Breakpoint Address Compare Function is enabled.

Breakpoint Data Register	bdr	Contains the virtual address of the multiplexed address data bus from the CPU when a breakpoint is detected.				
Registers	Name	Description				
Invalid Virtual Address Register 0	ivar0	Contains 20-bit physical numbers and 20-bit virtual address tag of the 32 most recently used pages. Used to invalidate entries with AS (Address Space)=0.				
Invalid Virtual Address Register 1	ivar1	Contains 20-bit physical numbers and 20-bit virtual address tag of the 32 most recently used pages. Used to invalidate entries with AS=1.				
MMU Control Register	mcr	Contains the different features provided by the MMU.				
MMU Status Register	msr	Contains the status of the MMU when a translation exception or a bus error is reported to the CPU.				
Translation Exception Address Register	tear	Is clocked when a translation exception occurs. The register contains the 32-bit virtual address which caused the translation exception.				
Bus Error Address Register	bear	Is clocked when a CPU or MMU error occurs. This register contains the 32-bit virtual address which triggered the bus error.				
Page Table Base 0	ptb0	Contains the base address used for address translation (when in superuser mode.)				
Page Table Base 1	ptb1	Contains the base address used for address translation (when in user mode.)				

NS32532 MMU Registers

The following is a comprehensive list of memory management registers for the NS32532. All registers except ivar0 and ivar1 can be read by the smr instruction. Ivar0 and ivar1 are write-only pseudo-registers. The tear register is a read-only register and cannot be loaded by the lmr instruction. Writing to a read-only register has no effect on the MMU. However, reading a write-only register should be avoided since random data patterns may be returned.

Registers	Name	Description
Invalid Virtual Address Register 0	ivar0	Contains 20-bit physical numbers and 20-bit virtual address tag of the 32 most recently used pages. Used to invalidate entries with AS=0.
Invalid Virtual Address Register 1	ivar1	Contains 20-bit physical numbers and 20-bit virtual address tag of the 32 most recently used pages. Used to invalidate entries with AS=1.
MMU Control Register	mcr	Contains the different features provided by the MMU.
MMU Status Register	msr	Contains the status of the MMU when a translation exception or a bus error is reported to the CPU.
Translation Exception Address Register	tear	Is clocked when a translation exception occurs. The register contains the 32-bit virtual address which caused the translation exception.
Page Table Base 0	ptb0	Contains the base address used for address translation (when in superuser mode.)
Page Table Base 1	ptb1	Contains the base address used for address translation (when in user mode.)

1.4 DEFINITION OF TERMS

The following terms are used throughout this document:

Software Module	A software module is a portion of a program that may be separately compiled or assembled and linked together with other software modules into an execut- able program image.
Series 32000 Module	A Series 32000 module is a software module that uses the Series 32000 architecture support for linkage. Currently, the GNX linker supports only one Series 32000 module per program.
Relative Value	A relative value is a symbol or expression that specifies an address within one of the Common Object

File Format (COFF) sections or the corresponding assembly program segment. Because such addresses are not bound to actual memory locations until link time, their value is relative to the base or starting address of the segment. Relative values are called relocatable addresses.

Absolute Value

An absolute value is a symbol or expression that specifies a numeric address. An absolute value or absolute address is unaffected by linkage.

1.5 DOCUMENTATION CONVENTIONS

The following documentation conventions are used in text, syntax descriptions, and examples in describing commands and parameters.

1.5.1 General Conventions

Nonprinting characters are indicated by enclosing a name for the character in angle brackets <>. For example, <CR> indicates the RETURN key, <ctrl/B> indicates the character input by simultaneously pressing the control key and the B key.

Constant-width type is used within text for filenames, directories, command names and program listings; it is also used to highlight individual numbers and letters. For example,

the C preprocessor, cpp, resides in the GNXDIR/lib directory.

1.5.2 Conventions in Syntax Descriptions

The following conventions are used in syntax descriptions:

Constant-width boldface type indicates actual user input.

Italics indicate user-supplied items. The italicized word is a generic term for the actual operand that the user enters. For example,

```
\mathtt{cc} [[option]... [filename]...]...
```

Spaces or blanks, when present, are significant; they must be entered as shown. Multiple blanks or horizontal tabs may be used in place of a single blank.

- { } Large braces enclose two or more items of which one, and only one, must be used. The items are separated from each other by a logical OR sign " | ."
- [] Large brackets enclose optional item(s).

- ١ Logical OR sign separates items of which one, and only one, may be used.
- Three consecutive periods indicate optional repetition of the preceding item(s). If a group of items can be repeated, the group is enclosed in large parentheses "()."
- Three consecutive commas indicate optional repetition of the preced-,,, ing item. Items must be separated by commas. If a group of items can be repeated, the group is enclosed in large parentheses "()."
- () Large parentheses enclose items which need to be grouped together for optional repetition. If three consecutive commas or periods follow an item, only that item may be repeated. The parentheses indicate that the group may be repeated.
- Indicates a space. i is only used to indicate a specific number of \Box required spaces.

All other characters or symbols appearing in the syntax must be entered as shown. Brackets, parentheses, or braces which must be entered, are smaller than the symbols used to describe the syntax. (Compare user-entered [], with [] which show optional items.)

1.5.3 Example Conventions

In interactive examples where both user input and system responses are shown, the machine output is in constant-width regular type; user-entered input is in constantwidth boldface type. Output from the machine which varies (e.g., the date) is in italic type. For example,

```
(dbug) < CR>
   Breakpoint 2 reached at filename _main: .3
        printf("hello\r\n");
```

ELEMENTS OF THE GNX ASSEMBLY LANGUAGE

2.1 INTRODUCTION

This chapter describes the elements of the GNX Assembly Language. The following topics are discussed:

- · Character set
- Statements
- Constants
- · Symbols, symbol types, and values
- · Location counter
- Expressions

2.2 CHARACTER SET

The GNX Assembly Language character set consists of the following subset of the standard ASCII character set:

- Upper- and lower-case letters A through Z of the English alphabet.
- Digits 0 through 9.
- Blanks (ASCII 32), Tabs (9), Vertical Tabs (11), and Form Feeds (12).
- The following printable characters:

Character	Name	Character	Name
,	Single Quote/Apostrophe	+	Plus Sign
(Left Parenthesis	/	Slash
)	Right Parenthesis	:	Colon
•	Period	;	Semi-Colon
_	Underscore	@	At Sign
,	Comma	[Left Square Bracket
-	Minus Sign/Hyphen]	Right Square Bracket
*	Asterisk	"	Double-Quote
\	Back Slash	%	Percent
~	Tilde	#	Pound Sign
^	Caret	1	Vertical Bar
&	Ampersand	<	Left Angle Bracket
\$	Dollar Sign	>	Right Angle Bracket
?	Question Mark		_

Carriage Return and Line Feed serve as line terminators; therefore, they cannot be entered directly into source code statements. They can be entered as their ASCII value.

Any other ASCII character may appear only within quoted strings.

The GNX Assembler is case sensitive, *i.e.*, the assembler distinguishes between upperand lower-case letters. Reserved symbols must be typed in lower-case. User symbols are interpreted exactly as they are typed.

2.3 GNX ASSEMBLER STATEMENTS

The GNX Assembly Language consists of lines of text that contain one or more statements separated by semicolons and an optional comment. A statement is an optional label followed, optionally, by a mnemonic plus its operands. Statements are composed of user-defined symbols (names and labels representing variable quantities or memory locations), reserved symbols, constant values, and delimiters.

GNX Assembly Language statements are of two kinds: GNX assembly language instructions and GNX assembler directives. The GNX assembly language instructions are translated directly into machine instructions so that their meanings are carried out at execution time. The GNX Assembler directives, on the other hand, are commands to the assembler itself to carry out some action during program translation, e.g., allocating a block of memory.

Lines of GNX Assembly Language code have the following form:

([label: [:]] [mnemonic [operands]][;]),,, [# comment] Syntax:

where: label is an optional label. The label must be a valid symbol name and must be followed by one or two colons. See the syntax descriptions of GNX assembly language directives in Chapter 6 for those directives that do not

allow labels.

mnemonic is an optional instruction mnemonic or assembler

directive. It must end with a space, tab, end-of-line, or

semicolon.

operandsare the operands of the instruction or of the assembler

> directive. The number of operands depends on the instruction or directive type. Each operand must be separated from the next operand by a comma. Spaces between operands are ignored. If the statement contains no instruction or directive, the operands must

also be omitted.

comment is the optional comment. A comment must be preceded

> by a pound sign (#). If the -c flag (or /CPP in VMS) is given, the comments should not begin in column 1.

Description: A line of GNX Assembly Language code must conform to the following rules:

> 1. Multiple statements (i.e., label, mnemonic, and operands) must be separated by a semicolon (;).

- 2. The code line may begin in any column.
- 3. A line of code may be up to 64K characters (including the end-ofline (EOL) character) in length. However, in the listing, lines longer than 132 characters (including the new-line (NL) character) will be truncated.
- 4. A code line may consist of zero or more statements, i.e., label, mnemonic, and operands, separated by semicolons, and optionally followed by a comment.

```
Example:

1 ret 0 # a return instruction
2 jump START # a jump instruction and its one operand
3 movw r2, r3 # a move word instruction and two operands
4 END: # a label only
5 START: movb r0, r1 # a label, instruction, and operands
6 # a comment only
```

2.4 STRING AND NUMBER SYNTAX

There are four basic types of constants in GNX Assembly Language statements: integer values, floating-point values, character constants, and strings. The syntax for each type of constant is defined in Sections 2.4.1 through 2.4.4.

2.4.1 Integer Syntax

Integer syntax has the following form:

[sign][base]digits Syntax: where: specifies the sign. By default, the sign is positive. A sign negative sign may be specified with the minus sign (-). base specifies the base. It may be one of the following: Binary — B' or b' Octal — O', o', Q', q' or 0 (leading digit zero) Decimal — D' or d' Hexadecimal — H', h', X', x', 0x (digit zero), or 0X (digit zero) Default is decimal. digits specifies the integer. Digits must be compatible with the specified base. Binary — 0 to 1 Octal — 0 to 7 Decimal - 0 to 9 Hexadecimal — 0 to 9 and A to F or a to f

Description: Integer constants may have the following range of values, depending on the context in which the constant is specified: -128 to 255 for byte constants, -32768 to 65535 for word constants, and -2147483648 to 2147483647 (-231 to 231-1) for double-word constants.

Decimal constants are sign-extended to double-words. Hexadecimal, octal and binary constants are zero-extended to double-words.

If the first operand of the addpi or subpi instruction is a constant, the processor expects BCD encoding. The assembler generates only two's complement encoding. However, a valid BCD number preceded by H' or 0x will be correctly encoded, because both hexadecimal and BCD use the same encodings within the BCD range.

For example, the instruction

addpd \$0x123, bcd_int

adds the immediate decimal value 123 to the contents of the location bcd int.

Examples:	Binary	Octal	Decimal	Hexadecimal
	B'11110001	0′077	D'1492	H'12ff
	- B′11	- Q′5077	-999	-X'302F
	b′11	0123	1457	0xAB03

2.4.2 Floating-Point Number Syntax

Floating-point values may be specified in one of two forms: as a decimal number in scientific notation, or as a hexadecimal value. The GNX Assembler expects floatingpoint numbers specified as hexadecimal values to be correctly encoded in the Series 32000 internal floating-point format. Therefore, hexadecimal notation is most useful to the writers of compilers or optimizers.

Decimal Floating-Point Syntax

Decimal floating-point syntax has the following form:

Syntax: [decimal prefix]decimal value

where: decimal prefix specifies whether the constant is short or long floating-point format. It may be one of the following:

> {0f | 0F} — short format floating-point value (float).

 $\{0l \mid 0L\}$ — long format floating-point value (long).

decimal value specifies a floating-point value in scientific notation.

Description: A decimal floating-point constant has two parts, an optional prefix that specifies short format (32 bits) or long format (64 bits) and a decimal

value expressed in scientific notation.

The decimal value format is:

where:

Syntax:	[sign]	digits	digits.	۱۲.	{E	e}	[sign]	digits	l

Mantissa	Exponent
sign	specifies the sign. A negative sign may be specified (-); by default, the sign is positive.
digits	specify the value. Only decimal digits are permitted (0 to 9). At least one digit must precede the decimal point.

 $E \mid e$ is the exponent flag. It is required when specifying an exponent.

Description: The decimal value must be in the appropriate range for the prefix size specified or in the format that is required by the instruction. See note below.

is the decimal point.

Examples:	Valid	Invalid	Comments
	3.14152	.0125	# digit before decimal point required
	971.	-0.00FF	# decimal digits only
	0f0 1F-14	0 125E999	# evnoment evceeds limit

NOTE: The GNX Assembler recognizes two types of floating-point constants: single-precision (float) and double-precision (long). Singleprecision numbers occupy four bytes. The most positive singleprecision value is 3.40282346 x 1038; the least positive value is 1.17549436 x 10⁻³⁸. The most negative value is the negative of the most positive value. Double-precision numbers occupy eight bytes. The most positive double-precision number is 1.7976931348623157 x 10^{308} ; the least positive value is 2.2250738585072014 x 10^{-308} . The negative range is the negative of the positive value.

Hexadecimal Floating-Point Syntax

Hexadecimal floating-point syntax is of the following form:

Syntax: hexadecimal prefix hexadecimal digits

where: hexadecimal prefix

is one of the following:

$$\begin{cases} f' \mid F' \mid 0y \mid 0Y \} & -\text{short format.} \\ \{l' \mid L' \mid 0z \mid 0Z \} & -\text{long format.} \end{cases}$$

f' | F' | 0y | 0Y

specifies an encoded short (32-bit) floating-point value. Must be followed by eight hexadecimal digits, if not, the assembler might generate unpredictable results.

1' | L' | 0z | 0Z

specifies an encoded long (64-bit) floating-point value. Must be followed by sixteen hexadecimal digits, if not, the assembler might generate unpredictable results.

hex digits

specify the value. Only hexadecimal digits are permitted (0 to F or f). The encoded value is an exact bit representation of the resultant 32- or 64-bit value.

Examples: Valid Invalid Comments f'E01267AC -F'A7261CD5 #no sign permitted L'12A945BD4266ECF0 L'E596C.4BF5DB46A26 #no decimal point permitted

NOTE: The memory formats for both float and long constants are described in Chapter 3 of the Series 32000 Programmer's Reference Manual. The GNX Assembler stores both as long type.

2.4.3 Character Constant Syntax

Character constants have the following form:

Syntax: '{ASCII char | escape sequence}'

where: ASCII char is any single ASCII encoded character.

escape sequence

is one of the special escape sequences, described in this

section.

Description:

A character constant is a single ASCII character enclosed by single quotes, as in 'A'. If the desired character is a special character, for example, the single quote itself, or if the character is not a printable character, then an escape sequence may be used to represent the character. The following rules apply to escape sequences:

- Except as noted in Table 2-1, any character preceded by the escape character backslash (\) represents that character.
- A backslash followed by one to three octal digits represents the character whose ASCII encoding is the octal value.
- Certain special characters are represented by the escape sequences specified in the escape sequence table below.

If the character constant is itself a single quote, the quote must be escaped, that is, preceded by the escape character backslash (\). Thus, the character constant single quote is $(\ \ \)$. Similarly, if the character constant is a backslash it must be escaped. The character constant backslash is (\\).

Other non-printable or special characters may be generated by the escape sequences in Table 2-1.

Character constants may be used in expressions. The value of the constant is its ASCII encoding. If the character constant is used as an immediate operand or in an expression, it is zero-extended to the appropriate number of bytes.

Table 2-1. Escape Sequences

ESCAPE	VALUE
\n \t \b \r \f \\ \' \0	newline horizontal tab backspace carriage return form feed backslash single quote ASCII character 0, or null, the C string terminator an arbitrary byte-sized bit pattern, where ddd is one to three octal digits, i.e., the character constant "" represents the character with value zero.

2.4.4 String Syntax

String syntax has the following form:

Syntax: "({ASCII char | escape sequence})..."

where: ASCII char is an ASCII encoded character.

escape sequence

is a character sequence used to represent special or non-printable ASCII encoded characters. Refer to Table 2-1.

Description: A string is a sequence of ASCII encoded characters enclosed by double-quotes. The same rules and escape sequence definitions specified in the description of character constants may be used in string constants. Special consideration must be given if a double-quote mark is part of the string. Strings enclosed in double-quote marks which also contain double-quotes are allowed. However, each quote which is a part of the string must be escaped, that is, it must be preceded by the escape character backslash (\). It is not necessary to escape the single-quote character

acter in a string constant.

Examples:	Strings Coded In Source Statements	Generated String	
	"This is a string" "Five O'Clock" "\"A\" for Ampere"	This is a string Five O'Clock "A" for Ampere	

2.5 SYMBOLS

A symbol is a name that refers to a memory location. Each symbol has a type and a value. The type of a symbol is either the segment in which the symbol is defined, external if the symbol is not defined in the assembly file, or absolute if the symbol is a numeric address. The value of a symbol is the address of the memory location. A symbol may have the attribute global. A symbol with the global attribute may be referenced from any software module in the program. By default, all symbols referenced but not defined are considered global.

Some symbol names are reserved, *i.e.*, the instruction mnemonics, directive mnemonics, names for the registers, address mode indicators, flags, scaled index qualifiers, the delimiters, and operators. The user may not redefine the reserved symbols. Appendix B contains a list of the reserved symbols in the GNX Assembly Language. The rest of this section and all of Section 2.6 deal with user-defined symbols.

2.5.1 Symbol Names

The name of a user-defined symbol is composed of one or more letters, digits and the characters underscore (_) and period (.). Except for temporary labels, the first character of the name may not be a digit. Symbol names with the initial character period (.) are assumed to be internal names generated by the GNX language tools; for example, compiler labels, Common Object File Format (COFF) section names, and reserved names should not be used. The name's length is limited to 64 characters.

The assembler is case sensitive, that is, it differentiates between upper- and lower-case letters in a user-defined symbol name. Thus, for example, the names ALPHA and Alpha are not identical and can be defined as separate symbols.

Examples:	Valid	Invalid	Comment	
	SYMBOL	\$YMBOL	# ''\$'' dollar-sign character illeg	jal
	_ALPHA	2ALPHA	# first character cannot be number	
	REG2	r1	# r1 is reserved symbol	

2.5.2 Symbol Types

The type of a symbol specifies the segment of the object file in which it occurs. All labels defined within a segment have the type of that segment. For example, all symbols defined in the .text segment (*i.e.*, following the .text directive) are of type text. The address of symbols associated with object file segments must be updated at link time, when the linker associates the object file segment with memory locations.

Undefined symbols are of type external. The value of an undefined symbol is resolved by the linker. Numeric addresses are of type absolute. The value of absolute symbols is unaffected by linkage.

A symbol's type determines the default addressing mode the assembler uses when the symbol is referenced. The following table lists symbol types, the associated object file segment and the default addressing mode for references to the symbol.

Type	Segment	Default Addressing Mode
\mathbf{Text}	Text or code segment	PC Relative
Data	Initialized data segment	Absolute
Bss	Uninitialized data segment	Absolute
Static	Static base segment	SB Relative
Link	Link table segment	Absolute
External	-	Absolute
Absolute	-	Absolute
<user-defined></user-defined>	<defined attributes="" by=""></defined>	${\bf Absolute}$

The type of a symbol delimits the places where the symbol may be used as an operand and the way its value may be manipulated in expressions. Expressions also have one of the above types. The type of an expression is determined by the types of the symbols it contains.

Following are descriptions of each of the symbol types:

1. Symbols of type text.

All symbols defined in the .text segment, i.e., labels following a .text directive, are of type text. All symbols or expressions of type text represent addresses within the text segment of the program's object code. The text segment contains program code and read-only data. The GNX Assembler uses the Program Counter (PC) Relative addressing mode for symbols and expressions of type text.

2. Symbols of type data.

All symbols defined in the .data segment, i.e., labels following a .data directive, are of type data. All symbols or expressions of type data represent addresses within the initialized data segment of the program's object code. The GNX Assembler uses the Absolute addressing mode for symbols and expressions of type data.

3. Symbols of type bss.

All symbols defined in the uninitialized data (.bss) segment are of type bss. Symbols defined by the .bss directive are of type bss, as are labels defined after a .udata directive. All symbols or expressions of type bss represent addresses within the uninitialized data segment of the program's object code. The GNX Assembler uses the Absolute addressing mode for symbols and expressions of type bss.

4. Symbols of type static.

All symbols defined in the .static segment, *i.e.*, labels following a .static directive, are of type static. All symbols or expressions of type static represent addresses within the .static segment of the program's object code. The .static segment is used to store static base relative data. The GNX Assembler uses the Static Base Register (SB) Relative addressing mode for symbols and expressions of type static.

5. Symbols of type link.

All symbols defined in the .link segment, *i.e.*, labels following a .link directive are of type link. All symbols or expressions of type link represent addresses within the .link segment of the program's object code. The .link segment is used to store the link table for a *Series 32000* module. The GNX Assembler uses the Absolute addressing mode for symbols and expressions of type link.

6. Symbols of type external.

All undefined symbols are of type external. Symbols defined using the .comm directive are also of type external. The GNX Assembler uses the Absolute addressing mode for symbols and expressions of type external.

7. Symbols of type absolute.

All symbols assigned numeric values are of type absolute. Absolute symbols specify an absolute numeric address. They are not relative to any segment of the object file. Symbols of type absolute may only be defined using the .set directive. The GNX Assembler uses the Absolute addressing mode for symbols and expressions of type absolute.

8. Symbols of user-defined type.

All symbols defined in a section, following the .section definition, are the type of the section. All symbols are allowed via absolute addressing mode.

2.5.3 Global Symbols

Global symbols are used by multiple software modules. The symbol must be defined exactly once. The defining module exports the symbol, that is, makes the symbol available for import by one or more additional software modules. Global symbols must be declared for export by the defining module with the .glob1 directive. Undefined symbols intended to be imported from other software modules should also be declared with the .glob1 directive, although this is not required.

Except for temporary labels, every user-defined symbol must be defined exactly once. A symbol definition assigns a value and type to a symbol name. There are several formats for defining symbols. The formats form four groups:

- · Labels.
- Symbols defined by the .set directive.
- Uninitialized symbols defined by the .bss directive.
- Common symbols defined by the .comm directive.

External, or undefined, user symbols may be declared for import with the .globl directive. Such a declaration does not define the symbol. Any symbol that is referenced in an assembler statement but not defined within the assembly is assigned type external.

Labels

The formats permitted for label definitions are:

```
Syntax:
             symbol name:
              or
             symbol name ::
              or
              symbol name: assembly statement
              or
              symbol name :: assembly statement
```

where:

assembly statement

may be any assembly statement except those directives that do not accept labels. See Chapter 6 for detailed descriptions of the syntax of all the GNX assembly language directives.

Description:

In each case, the current value and the type of the location counter is assigned to the symbol, see Section 2.7. The second construction (using "::") also sets the global attribute on the symbol, see Section 6.6.

Temporary Labels

Syntax:

temporary label:

where:

temporary label

consists of a digit from 1 to 9.

Description:

A temporary label consists of a digit from 1 to 9, followed by a colon. Reference to the label is via the symbols nf and nb, where n specifies temporary label n, where f means forward, and b means backwards. All referenced temporary labels must be defined somewhere within the program. Temporary labels may not be exported. There is no limit on the number of times that a temporary label may be redefined. The following symbols are reserved:

1f 2f 3f 4f 5f 6f 7f 8f 9f 1b 2b 3b 4b 5b 6b 7b 8b 9b

Temporary labels are most useful in conjunction with macros.

Example:

```
1
                         9:
2
  T00000000
              a2a2a2a2
                             .space 10
              a2a2a2a2
              a2a2
  T0000000a
                                        # branch to line 6
3
              ea06
                             br 7f
  T0000000c
              ea74
                             br 9b
                                        # branch to line 1
5
  T0000000e ea02
                             br 9f
                                        # branch to line 7
6
                         7:
7
                         9:
8
                         7:
  T0000010
              ea00
                             br 7b
                                        # branch to line 8
```

In this program, the branch on line 3 refers to label 7 on line 6, the branch on line 4 refers to label 9 on line 1, the branch on line 5 refers to label 9 on line 7, and the branch on line 9 refers to label 7 on line 8.

Defining Symbols with the .set Directive

The format for symbol definition using the .set directive is:

Syntax: .set symbol name, expression

Description: The statement assigns the value and type of expression to the symbol.

The expression may not be of type external (undefined), nor a forward

reference.

Defining Uninitialized Symbols with the .bss Directive

The format for the definition of uninitialized symbols using the .bss directive is:

Syntax: .bss symbol name, expression1, expression2

Description: This form is used only for uninitialized data (bss) symbols. The symbol

is assigned type bss and the value of the current bss location counter after it is aligned to a multiple of expression2. For a complete descrip-

tion of the .bss directive see Section 6.7.4.

Defining Common Symbols

The format for the definition of uninitialized, common symbols using the .comm directive is:

Syntax: .comm symbol name, expression

Description: The type of common symbols is external. If no software module defines

a global symbol by this name, then the linker will allocate an uninitialized storage area whose size is the largest *expression* specified by any .comm directive for this *symbol*. See Section 6.6.2 for a description of

the .comm directive.

2.6 LOCATION COUNTER

The GNX Assembler manages a location counter that keeps track of the current relocatable memory address. The current location counter is set to the type of the segment that is being assembled and the value of the next available address within the segment. The current location counter is initialized to the TEXT segment, address 0 at the start of assembly.

The assembler re-initializes the current location counter to a new value (i.e., a new type and offset) each time a segment control directive is encountered. The segment

control directives determine the segment into which the following code should be assembled. On encountering a segment control directive, the assembler saves the next available address in the previous segment before entering the new segment, so that it is able to restore the previous address if the previous segment is re-opened. The assembler maintains a saved location counter for each object file segment (text, data, bss, static, user-defined sections, dsects and link) as well as each user-defined segment.

When a statement is processed, the assembler increments or decrements the location counter by the number of bytes of object code generated or by the amount of data storage allocated.

The location counter symbol, (.) period, is a special token which may be used in expressions or instruction operands to specify the location counter's current value. The symbol may appear alone or as a term in an arithmetic expression (addition or subtraction only).

Examples:

- 1. .set A, . 2. bne .-8
- In example 1, (.) specifies the current address. The symbol A is assigned the current location counter address.

In example 2, the expression .-8 specifies the current address minus 8.

2.7 EXPRESSIONS

An expression is a combination of terms and operators which evaluate to a single value and type. Valid expressions include addresses and integer expressions. Floating-point expressions are not valid.

Terms in expressions may be constants or symbols, including the location counter symbol (.), see Sections 2.4, 2.5, and 2.6. The type of the term determines the way in which the term may be combined with other terms and operators. Section 2.7.2 defines the effect the type of a term has on the result of an expression.

Operators in expressions are the special symbols which define arithmetic and logical operations. An operator has the following characteristics:

- An operator has a level of precedence which affects the order in which the GNX Assembler evaluates an expression containing the operator.
- An operator defines the type of the term(s) that may be used with the operator and the location of the term(s) relative to the operator.

Table 2-2 lists all GNX Assembly Language operators in order of precedence.

Table 2-3 defines the type and order of the terms that may be used with the operators.

Table 2-2. Operator Precedence

PRECEDENCE	OPERATOR	NAME	OPERATION
Unary Operator			
1 1	- ~	Unary minus Unary complement	Two's complement. One's complement.
Binary Operator			
2 2 2 2	* / % <<	Multiply Divide Modulus Shift left Shift right	Multiply 1st term by 2nd. Divide 1st term by 2nd.* Remainder from 1st term divided by 2nd.** Shift 1st term by 2nd; emptied bits are zero-filled. Shift 1st term by 2nd; emptied bits
2	~	Logical OR / complement	are zero-filled. Bit-wise OR of 1st term and one's complement of 2nd term.
3 3 3	& 	Logical AND Logical OR Logical XOR	Bit-wise AND of 1st and 2nd terms. Bit-wise OR of 1st and 2nd terms. Bit-wise XOR of 1st and 2nd terms.
4	+	Add Subtract	Add 1st and 2nd terms. Subtract 2nd term from 1st term.

^{*} Rounds toward 0, e.g., -7/3 = -2 and 7/3 = 2 ** e.g., -7%3 = -1 and 7%3 = 1.

Table 2-3. Types and Operators

Operator - ~		Term1	Operation
		abs abs	Type abs. Type abs.
BINARY	OPERATORS		
Term1 Type	Operator	Term2 Type	Result Type
abs	*	abs	Type abs.
abs	/	abs	Type abs.
abs	%	abs	Type abs.
abs	<<	abs	Type abs.
abs	>>	abs	Type abs.
abs	~	abs	Type abs.
abs	&	abs	Type abs.
abs	I	abs	Type abs.
abs	^	abs	Type abs.
abs	+	abs	Type abs.
abs	-	abs	Type abs.
rel	+	abs	Type rel.*
rel	-	abs	Type rel.*
rel	-	rel	Type abs.**
ext	+	abs	Type ext.
ext	-	abs	Type ext.

NOTE:

- abs Any term of type absolute.
- rel Any term of relative type, i.e., text, data, etc.
- ext Any term of type external, undefined.
- * The type of the result matches the type of the relative term in the expression.
- ** Term1 and Term2 must be the same type, the result is type absolute.

2.7.1 Rules for Expressions

The rules for forming and evaluating expressions are as follows:

- 1. All unary operators must precede a single term and cannot be used to separate two terms.
- 2. All binary operators must separate two terms. For example, the expression 8*4 is legal, but 8**4 is not.
- 3. Compound expressions are valid. An expression may be constructed from other expressions using unary and binary operators. For example, the two individual expressions A+1 and B+2 may be combined with a multiply operator and parentheses to form the single expression (A+1)*(B+2). Note that the parentheses override the default precedence rules.
- 4. Evaluation of an expression is governed by three factors:
 - Parentheses expressions enclosed in parentheses are always evaluated first. For example, the expression 8/4/2 evaluates to 1, but the expression 8/(4/2) evaluates to 4.
 - Precedence Groups an operation of a higher precedence group is evaluated before an operation of a lower precedence whenever parentheses do not otherwise determine the evaluation order. For example, the expression 8+4/2 is evaluated as 10, but the expression 8/4+2 is evaluated as 4.
 - Left to Right Evaluation expressions are evaluated from left to right whenever parentheses and precedence groups do not determine evaluation order. For example, the expression 8*4/2 is evaluated as 16, but the expression 8/4*2 is evaluated as 4.

2.7.2 Types in Expressions

The type of the result of an expression depends on the type of the terms and the operations performed. The rules for types in expressions are as follows:

1. Expressions with terms having absolute type.

Terms with absolute type may be added, subtracted, multiplied, etc. All operators are allowed. The result is always an absolute type.

```
Examples:
            1. 21 * 5
                        # result is 105
            2. 21 / 5
                      # result is 4
            3, 21 % 5
                        # result is 1
            4. 21 & 5
                        # result is 5
            5. 21 << 5 # result is 672
            6. 21 >> 5 # result is 0
            7.21 + 5
                        # result is 26
            8.21 - 5
                        # result is 16
            9. 21 | 5
                        # result is 21
           10. 21 ^ 5
                        # result is 16
```

2. Expressions combining terms having relative and absolute types.

The only valid operations between terms with relative types and terms with absolute type are addition and subtraction. The operations take place between the values of the first and the second terms and the result is assigned the type of the relative term.

Addition is commutative. An absolute term may be added to a relative term or a relative term may be added to an absolute term, the result is the same in either case.

Subtraction is not commutative. An absolute term may be subtracted from a relative term. A relative term may not be subtracted from an absolute term.

```
Example:
              1
                         .set
                                ZERO, 0
              2
                         .set
                                TEN, 10
              3
                                COUNT, 30
                         .set
              4
              5
                         .udata
              6
                Size:
                        .blkd
                 Start: .space (COUNT * 4)
              8
                 End:
                        .blkd
              9
             10
                         .text
             11
                         movb
                                 $ZERO, Start + ZERO
                                 $TEN, TEN + Start
             12
                         movb
             13
                         movd
                                 (End - TEN), r0
```

In the preceding example several symbols and expressions are used. The symbols ZERO, TEN, and COUNT are of type absolute. The symbols Size, Start, and End are of type bss, refer to Section 2.5.2.

The expression "(COUNT * 4)" in line 7 combines two absolute terms, the result is absolute.

The expression "Start + ZERO" in line 11 adds a relative type to an absolute type. The result is type bss.

The expression "TEN + Start" in line 12 adds an absolute type to a relative type. The result is type bss.

The expression "End - TEN" in line 13 subtracts an absolute type from a relative type. The result is type bss.

3. Expressions combining terms having relative types.

Terms with relative or absolute type may be subtracted from terms with the same type. No other operator is allowed. The result is always an absolute type.

```
Example:
            1
                       .set
                              COUNT, 30
            2
            3
                       .udata
            4 Size:
                       .blkd
            5 Start: .space (COUNT * 4)
              End:
                       .blkd
            7
            8
                       .text
             9
                       movd
                              $(End - Start)/4, Size
```

The expression "End - Start" in line 9 subtracts a relative term from another relative term. Since both symbols are of the same type (bss), this is a legal expression. The result is of type absolute, *i.e.*, the absolute number of bytes between the two labels. The result of the subtraction is then divided by 4, both terms are type absolute and the result is type absolute.

Note that "(End - Start)/4" is not a legal expression without parentheses. Division is of higher precedence than subtraction, but a relative term may not be divided.

4. Expressions with terms having external and absolute type.

Terms with absolute type may be added to or subtracted from terms with external type. No other operations are allowed. The result always has external type. A term of type absolute may be subtracted from a term of type external, but a term of type external may not be subtracted from a term of type absolute. The first term of the subtraction must be the term of type external.

```
Example:
             1
                   .set
                         ZERO, 0
             2
                   .set TEN, 10
             3
                   .set COUNT, 30
             4
             5
                   .globl Start
             6
                   .globl End
             7
             8
                   .text
             9
                   movb
                          $ZERO, Start + ZERO
            10
                   movb
                          $TEN, TEN + Start
            11
                   movd (End - TEN), r0
```

The expression "Start + ZERO" in line 9 adds an absolute type to an external (undefined) type. The result is type external.

The expression "TEN + Start" in line 10 adds an external type to an absolute type. The result is type external.

The expression "End - TEN" in line 11 subtracts an absolute type from an external type. The result is type external.

5. Expressions with character constants.

Character constants may appear as terms in expressions. When a character constant is used this way, it is converted to an integer constant. Integer constants are stored in four bytes; the assembler fills the higher order bytes with zero.

```
Examples: 1. .set UPCASE, 'A' - 'a # result is -32
2. .set LOWCASE, 'a' - 'A # result is 32
```

2.7.3 Size of Expressions

Expressions are stored in 4 bytes, with the higher order bytes filled with zero by the assembler.

GNX ASSEMBLER PROGRAMS

3.1 INTRODUCTION

This chapter describes the structure of GNX Assembly Language programs and how the GNX Assembler assigns memory addresses to symbols, instructions, and data. In particular, it describes:

- Program Structure
- Program Segments
- Series 32000 Module Segments
- User-Defined Dummy and Comment Segments
- Linkage and Relocation Modes

3.2 GNX ASSEMBLER PROGRAM STRUCTURE

The structure of a GNX Assembly Language program reflects the structure of the object file and the layout of the program image in memory. The structure allows instructions and data to be grouped into logical segments that occupy contiguous memory. Each segment is an atomic unit, that is, segments may be combined together into larger units but not broken into smaller units.

Every object file contains at least three program segments: text, data and bss. These segments correspond to the .text, .data, and .bss sections of a Common Object File Format (COFF). The text segment contains program instructions and constant data, the data segment contains writable, initialized data, and the bss segment contains uninitialized data. No object file space is allocated for the bss segment.

In addition to the default program segments, there are several special segments that support Series 32000 modules. The module table segment contains the module table entries and corresponds to the .mod section of the COFF file. The link segment contains the module's Link Table and corresponds to the .link section of the COFF file. The static segment contains Static Base Relative data and corresponds to the .static section of the COFF file.

The programmer is also allowed to create user-defined segments through the assembler directives .dsect and .section or comment segment through the assembler directive .ident. The GNX Assembler maintains a location counter for each object file segment.

3.3 PROGRAM SEGMENTS

Every assembly program consists of one or more program segments. A program segment is a block of sequential statements which are placed in contiguous memory and treated as a unit with common properties, for example, access protection. Every program contains the following types of segments:

- Text or Program Code Segment
- · Initialized Data Segment
- Uninitialized Data Segment (bss)

A segment begins and ends with one of the segment control directives (Section 6.7) and contains any number of statements. The following illustrates the form of a program segment:

```
.text  # specifies the start of a program code segment
statement-1  # assembler statements

statement-2

.
statement-n
.data  # specifies start of a data segment
  # a segment terminates with another segment
  # control directive or EOF
```

3.3.1 Text Segment

The text segment contains *Series 32000* instructions and constant data. After every statement, the text segment location counter is incremented by the number of bytes generated for that statement. The location counter of the text segment may not be decremented.

The text segment is written to the .text section of the object file. Each text address maps to a location in the .text section of the object file. When the text segment is loaded into memory, it is protected for read-only access.

NOTE: This statement is only true for GNX native environments and if the MMU is on a development board. It may not be true in other applications.

All symbols defined in the text segment are of type text. References to locations in the text segment are addressed with the Program Counter Relative addressing mode.

Related directive: .text (Section 6.7.2).

3.3.2 Initialized Data Segment

The initialized data segment contains writable, initialized data. After every statement, the data segment location counter is incremented by the number of bytes generated for that statement. The location counter of the data segment may not be decremented.

The data segment is written to the .data section of the object file. Each data address maps to a location in the .data section of the object file. When the data segment is loaded into memory, it is protected for read-write access.

All symbols defined in the data section are of type data. References to locations in the data segment are addressed with the Absolute addressing mode.

Related directive: .data (Section 6.7.3).

3.3.3 Uninitialized Data (bss) Segment

The uninitialized data or bss segment consists of storage allocated for uninitialized data. After every statement following the .udata section control directive, the bss segment location counter is incremented by the number of bytes allocated by that statement. The bss location counter is also updated by the .bss directive. No code or data may be generated in the bss segment. The location counter of the bss segment may not be decremented.

Each bss address maps to a location in the .bss section of the object file, although the .bss section of the COFF file contains no actual data. Storage space is allocated and zeroed at load time. When the bss section is loaded into memory, it is protected for read-write access

All symbols defined in the .bss section are of type bss. References to locations in the bss segment are addressed with the Absolute addressing mode.

Related directives: .udata (Section 6.7.5), .bss (Section 6.7.4).

3.4 SERIES 32000 MODULE SEGMENTS

The GNX Assembler supports three additional segments for building Series 32000 modules. A Series 32000 module uses the Series 32000 hardware support for linkage.

The following segment types support Series 32000 modules:

- Module Table Segment
- Link Table Segment
- Static Base Relative Segment

The Series 32000 hardware support for linkage requires a Module Table for the program and a Link Table for each Series 32000 module.

The Module Table records the Program Base, the Static Data Base, and the Link Table Base for each module. The Program Base is the base address for the text (or program code) segment of the module. The Static Data Base is the base address for the static data segment of the module. The Static Data Base may be defined once for each module with the .module or .modentry directive. If the Static Data Base address is not explicitly defined, it defaults to zero. The Link Table Base is the base address for the link segment. The Link Table Base may be defined once for each module with the .module or .modentry directive. If the Link Table Base address is not explicitly defined, it defaults to zero. The Module Table is built by the linker.

The Link Table contains an address for each external data reference and an external procedure descriptor for each external function entry point. It must be built by the programmer in the link segment using the .xdd directive to define each external data address and the .xpd directive to define an external procedure descriptor for each function entry point that uses the cxp/rxp calling discipline. The addresses in the Link Table are generated at link time.

3.4.1 Module Table Segment

The module table segment is one of three special segments whose function is to support *Series 32000* modules. The module table segment, if one is present, contains the module table for the program. Each module table entry consists of four 32-bit entries corresponding to each component of a module:

- The Static Base (sb) entry contains the base address for the module's static local data.
- The Link Base (lb) entry contains the base address for the module's link table.
- The Program Base (pb) entry contains the base address for the module's program code.
- A fourth entry is currently unused but reserved.

Each base address is a standard Series 32000 address.

Module table entries may be generated with the .module and the .modentry directives.

The module segment location counter is incremented by the number of bytes generated for the directive. The location counter of the module segment may not be decremented. The module segment is written to the .mod section of the object file.

Related directives: .module (Section 6.8.1) and .modentry (Section 6.8.2).

3.4.2 Link Table Segment

The link table segment is one of three special segments whose function is to support Series 32000 modules. The link table segment, if one is present, contains the link table for the Series 32000 module. The link table consists of one 4-byte entry for each variable or function that is accessed with the External addressing mode, see Section 4.2.13. If the link table entry is for a data item, the entry contains the absolute memory address of the variable. If the link table entry is for the entry point of a function, the link table entry contains an external procedure descriptor. Each link table entry is filled with the appropriate address or procedure descriptor by the linker at link time.

An external procedure descriptor must be generated for any function called with the cxp or cxpd instruction. An external procedure descriptor consists of a 16-bit module table offset and a 16-bit program code offset. The module table offset is the distance in bytes from the base of the program's module table to the module table entry for this module. The program code offset is the distance from the program code base of the module to the entry point of the function. External procedure descriptors may be generated with the .xpd directive.

Link table entries for data items may be generated with the .xdd directive.

After every statement, the link segment location counter is incremented by the number of bytes generated for that statement. The location counter of the link segment may not be decremented. The link segment is written to the .link section of the object file. Each link address maps to a location in the link section of the object file. When the link segment is loaded into memory, it is protected for read-only access.

All symbols defined in the link segment are of type link. References to locations in the link segment are addressed with the Absolute addressing mode.

.xpd (Section 6.3.8), .xdd (Section 6.3.9), .link (Section 6.7.7), Related directives: .module (Section 6.8.1), and .modentry (Section 6.8.2).

3.4.3 Static Base Relative Segment

The static segment should be used instead of the data segment when building a program of Series 32000 modules. The static segment contains Static Base Relative data. If the static segment is present, the linker assigns the Static Base Register the value of the base address of the static segment. After every statement, the static segment location counter is incremented by the number of bytes generated for that statement. The location counter of the static segment may not be decremented. The static segment is written to the .static section of the object file. Each static address maps to a location in the .static section of the object file. When the static segment is loaded into memory, it is protected for read-write access.

All symbols defined in the static segment are of type static. References to locations in the static segment are addressed with the Static Base Relative addressing mode.

Related directives: .static (Section 6.7.6), .module (Section 6.8.1) and .modentry (Section 6.8.2).

3.5 USER-DEFINED, DUMMY AND COMMENT SEGMENTS

This section describes user-defined, dummy and comment segments.

3.5.1 User-Defined Segments

User-defined segments are generated with the .section directive. These segments occupy real space in the object file and, depending on the attributes selected, may appear in the linked file. Symbols declared in these segments are addressed via the absolute addressing mode.

Related directive: .section (Section 6.7.8).

3.5.2 Dummy Segments

The "dummy" segments are generated with the .dsect directive. These segments do not allocate storage, nor do they contain generated code or data. If the dummy segment is of a relative type, it will overlay some portion of that type of segment. For example, a user-defined dummy segment might be used to overlay one or more structured data types on a pool of storage. Dummy segments of type absolute may be used to generate symbolic positive or negative offsets from the frame pointer register for function arguments or local variables.

Every statement following a .dsect directive increments or decrements the location counter for the dummy segment by the number of bytes specified by that statement.

Related directive: .dsect (Section 6.7.1).

3.5.3 Comment Segments

Comment segments are generated with the .ident directive and corresponds to the .comment section of the COFF file.

3.6 LINKAGE

Linkage is the combination of the output of several assemblies or compilations into a single program. A linker must also resolve all external references and all references to relocatable addresses within each program segment.

The GNX Linker combines all input segments of the same type into a single output segment and assigns the resultant output segments to specific memory addresses. The linker also updates all references to addresses within the segment if the base address of the segment has changed.

3.6.1 Relocatable Addresses

The GNX Assembler assigns a relocatable memory address to each instruction and each byte of data storage defined in an assembly language program. A relocatable memory address is one which is relative to the start of the segment. If the linker moves the base address of the segment, the linker must update every address within the segment by the same amount. At link time each relocatable address is resolved to an absolute address, i.e., to the actual address in system memory where the instruction or data is stored.

A relocatable memory address consists of a type that specifies the segment in which the symbol is defined and an address that specifies the location of the instruction or data in memory, relative to the beginning of its segment. If the base address of the segment is changed at link time, all relocatable addresses within the segment must be modified accordingly.

3.6.2 Linking Program Segments

An assembly language program segment is the smallest unit the GNX Linker manipulates. Within a segment all code or data remains contiguous throughout the linkage process. By default, the linker combines all input segments of the same type and module according to the linker's combining rule, for example, all text segments, into a single output segment of the same type. The linker binds the output segment to a section of memory within the program's address space. The linker may function differently depending upon the programmer's instructions.

Each program segment the assembler outputs has associated relocation entries for every undefined symbol or relocatable address referenced within the segment. The linker uses these entries to generate absolute memory addresses for the references.

A program segment is relocatable if the segment may be combined with other segments of the same type and if there are relocation entries for all undefined or relocatable addresses the segment references.

3.6.3 Linking Series 32000 Modules

Series 32000 modules use special hardware support provided by the Series 32000 chip family to resolve external references. A Series 32000 module has three components, a program base relative code segment, a static base relative data segment, and a link table. The program base relative portion of the module corresponds to the text segment of the assembly program. The static base relative component is the static segment. All data references should use the Static Base Register Relative addressing mode. See Section 9.3 and Table 9-2 for the command line option that defaults data segment addresses to the Static Base Register Relative addressing mode. The link table corresponds to the link segment of the assembly program.

A Series 32000 module built with all code in the text segment, all data in the static base relative segment, and all external references resolved through the link table is position independent. All memory references in the module are relative to base addresses stored in its Module Table entry. Only the module table and possibly the link table require updating if the module is moved to a different memory location.

To link Series 32000 modules, a module table entry must be built for each module. The link table of each module must be filled with the address of each external data variable and an external procedure descriptor for each external procedure.

INSTRUCTION OPERANDS

4.1 INTRODUCTION

This chapter defines the syntax of instruction operands. Instruction operands identify the participants in the operation specified by an opcode or a directive.

Instruction operands may be constants, memory addresses, symbols, and/or expressions. The type of operand required in an instruction is determined by the instruction itself. These are the following operand types:

Operand Type	Section
General Operands	Section 4.2
Expression Operands	Section 4.2.1
Register Operands	Section 4.2.2
Register Relative Operands	Section 4.2.3
Frame Memory Operands	Section 4.2.4
Frame Memory Relative Operands	Section 4.2.5
Stack Memory Operands	Section 4.2.6
Stack Memory Relative Operands	Section 4.2.7
Static Memory Operands	Section 4.2.8
Static Memory Relative Operands	Section 4.2.9
Program Memory Operands	Section 4.2.10
Immediate Operands	Section 4.2.11
Absolute Operands	Section 4.2.12
External Operands	Section 4.2.13
Top-of-Stack Operands	Section 4.2.14
Scaled-Index Byte Operands	Section 4.2.15
Scaled-Index Word Operands	Section 4.2.16
Scaled-Index Double-Word Operands	Section 4.2.17
Scaled-Index Quad-Word Operands	Section 4.2.18
Displacement Operands	Section 4.2.19
Immediate Subrange Operands	Section 4.3
Quick Operands	Section 4.3.1
Block Length Operands	Section 4.3.2
Bit-Field Length Operands	Section 4.3.3
Bit-Field Offset Operands	Section 4.3.4
Displacement Operands	Section 4.3.5

Operand Type	Section	
Program Memory Operands	Section 4.4	
General Register Operands	Section 4.5	
Register List Operands	Section 4.6	
Configuration List Operands	Section 4.7	
Processor Register Operands	Section 4.8	
Memory Management Register Operands	Sections 4.9 – 4.11	
External Register Operands	Section 4.12	

About 90 percent of the instructions use one or more general operands.

The following sections define the syntax of the instruction operands.

4.2 GENERAL OPERANDS

Syntax:

gen

where:

gen

is one of the following general operand types:

Expression Register

Register Relative Frame Memory

Frame Memory Relative

Stack Memory

Stack Memory Relative

Static Memory

Static Memory Relative

Program Memory

Immediate Absolute External Top-of-stack Scaled-index Byte

Scaled-index Word

Scaled-index Double-word Scaled-index Quad-word Displacement (:b, :w, :d)

Description:

Each of the general operand types corresponds to a GNX Assembler general addressing mode.

Many general operands use displacements (disp) to specify the offset from a base address to a particular memory location. General operand displacements must be within the range -224+1 to 224-1 (-16777215 to 16777215) if the CPU is a 24-pin address CPU. Although the 32-pin address processors have a full 32-bit address space, displacements are limited to the range-(2²⁹-2²⁴) to 2²⁹-1 (-536870912 to 536870911) because of the four byte displacement format (see the Series 32000 Programmer's Reference Manuals for more details). Displacements that are expressions must be enclosed in parentheses.

NOTE: The GNX Assembler uses the range -2^{29} to $2^{29}-1$. It is up to the user to limit this range if a 24-pin address processor is used.

24-pin address CPUs include the NS320xx and the NS32CG16.

32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

Sections 4.2.1 through 4.2.19 define the syntax and function of each of the general operand types.

4.2.1 Expression Operands

Syntax:

expression

Description:

When an expression is used as an operand for a general class instruction, the addressing mode, or operand type, of the operand depends on the type of the expression. Expressions of type text generate the Program Counter Relative addressing mode. Expressions of type static generate the Static Base Relative addressing mode. All other expression types generate the Absolute addressing mode.

4.2.2 Register Operands

Syntax:

register

where:

register

is one of the General-purpose or Floating-point registers. (See Sections 1.3.1 and 1.3.3.) The specified

register contains the operand.

Description:

A register operand specifies a General-purpose or Floating-point register. In some instructions, the specified General-purpose register points to the location of the operand, i.e., the register contents are the address of the operand. In such cases, the contents of the register are not affected by the instruction operation.

Floating-point registers may be specified only in floating-point instructions.

Example:

```
T00000000
           be4500
                    movf
                           f1, f2
T0000003
           c101
                    addw
                           r0, r7
```

The movf instruction copies a single-precision floating-point number from Floating-point register f1 to Floating-point register f2. The addw instruction adds the low-order word of r0 to the low-order word of r7.

4.2.3 Register Relative Operands

expression(register) Syntax:

where: expression is a displacement or expression which evaluates to an

absolute value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU; or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU; or to a relative value of type text, data,

bss, static, or link.

(register) is one of the general registers, r0 to r7 (see Section

1.3.1). Parentheses are required.

The GNX Assembler uses the range NOTE:

> -536870912 to 536870911 for displacement. It is up to the user to limit this range if a 24-pin address

CPU is used.

Description: A Register Relative operand specifies an operand at a memory address.

The address is the sum of the displacement expression and the contents

of the General-purpose register rn.

Example: 1 TEN, 10 .set

> 2 3 T00000000 81aac000 addw INTEG, 0(r2)

000000

T00000007 435514c0 addd (TEN*2)(r2), INTEG

000000

In line 3, 0(r2) is a Register Relative operand. The instruction adds the word at the address specified by the symbol INTEG to the word at the memory address specified by 0(r2). The result is stored at 0(r2).

In line 4, (TEN*2)(r2) is a Register Relative operand. The expression "TEN * 2" evaluates to the absolute value 20. This value is added to the contents of register r2 to yield the operand's address. The instruction adds the double-word at this address to the double-word at the address specified by the symbol INTEG. The result is stored at INTEG.

NOTE: 24-pin address CPUs include the NS320xx and the NS32CG16.

 $32\mbox{-pin}$ address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.4 Frame Memory Operands

Syntax:

disp(fp)

where:

disp

is a displacement or expression which evaluates to an absolute base value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU 32-pin address CPU.

(fp)

specifies the Frame-pointer register. Parentheses are required.

NOTE:

The GNX Assembler uses the range -536870912 to 536870911 for displacement. It is up to the user to limit this range if a 24-pin address CPU is used.

Description:

A Frame Memory operand specifies an operand at a memory address. The address is the sum of the displacement disp and the contents of the Frame-pointer register.

Example:

```
1
                         .set
                                TEN, 10
2
3
  T00000000
              01aec000
                         addw
                                INTEG, 31(fp)
               00001f
  T00000007
              43c514c0
                         addd
                                 (TEN*2)(fp), INTEG
               000000
```

In line 3, 31(fp) is a Frame Memory operand. The instruction adds the word at the address specified by the symbol INTEG to the word at the memory address specified by 31(fp). The result is stored at 31(fp).

In line 4, (TEN*2)(fp) is a Frame Memory operand. The expression "(TEN*2)" evaluates to the absolute value 20. This value is added to the contents of the Frame-pointer register (fp) to yield the operand's address. The instruction adds the double-word at this address to the double-word at the address specified by the symbol INTEG. The result is stored at INTEG.

24-pin address CPUs include the NS320xx and the NS32CG16. NOTE:

> 32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.5 Frame Memory Relative Operands

Syntax: disp2(disp1(fp))

where: disp1

is an expression with absolute type with a value in the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

disp2

is an expression with absolute type with a value absolute value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

(fp)

specifies the Frame-pointer register. Parentheses are required.

Parentheses are required around disp1 (fp).

NOTE:

The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a 24-pin address CPU is used.

Description:

A Frame Memory Relative operand specifies an operand at a memory address which is relative to the contents of a double-word in memory. The address is the sum of disp2 and the double-word at the address specified by the Frame-pointer relative value disp1 (fp).

```
Example:
```

```
1
                         .set
                                TEN, 10
2
                                FIFTY, 50
                         .set
3
                                r0, 15(FIFTY+1(fp))
  T00000000
              1404330f
                         movb
5
  T00000004
              d7801400
                         movd
                                0((TEN*2)(fp)), r3
```

In the example, 15(FIFTY+1(fp)) is a Frame Memory Relative operand. The instruction copies the low-order byte of register r0 to the specified

address. The address is the sum of 15 and the double-word at the address (FIFTY+1(fp)). The address (FIFTY+1(fp)) is the sum of the symbol FIFTY and one, which evaluates to the absolute value 51, and the current contents of the fp register.

Line 4 moves the double-word pointed to by 20(fp) to r3.

NOTE: 24-pin address CPUs include the NS320xx and the NS32CG16.

32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.6 Stack Memory Operands

Syntax:

disp(sp)

where:

disp

is a displacement or expression which evaluates to an absolute base value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

(sp)

specifies the current stack pointer. The current stack pointer may be the User Stack Pointer (sp1) or the Interrupt Stack Pointer (sp0). The s bit in the psr specifies which pointer is currently active. Parentheses are required.

NOTE: The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a 24-pin address CPU is used.

Description:

A Stack Memory operand specifies an operand at a memory address. The address is computed as the sum of the displacement disp and the contents of the current stack pointer register.

Example:

```
1
                         .set
                                TEN, 10
3
  T00000000
              41aec000
                         addw
                                INTEG, 31(sp)
               00001f
  T00000007
               43cd14c0 addd
                                (TEN*2)(sp), INTEG
               000000
```

In line 3, 31(sp) is a Stack Memory operand. The instruction adds the word at the address specified by the symbol INTEG to the word at the memory address specified by 31(sp). The result is stored at 31(sp).

In line 4, (TEN*2)(sp) is a Stack Memory operand. The expression "(TEN*2)" evaluates to the absolute value 20. This value is added to the contents of the Stack-pointer register to yield the operand's address. The instruction adds the double-word at this address to the double-word at the address specified by the symbol INTEG. The result is stored at INTEG.

24-pin address CPUs include the NS320xx and the NS32CG16. NOTE:

> 32-pin address CPUs include the NS32332, NS325X16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.7 Stack Memory Relative Operands

Syntax: disp2(disp1(sp))

where: disp2 is an expression with absolute type with a value in the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

disp1

is a displacement or expression which evaluates to an absolute base value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

(gg)

specifies the current stack pointer. The current stack pointer may be the User Stack Pointer (sp1) or the Interrupt Stack Pointer (sp0). The s bit in the psr specifies which pointer is currently active. Parentheses are required.

Parentheses are required around the stack memory value disp1 (sp).

NOTE:

The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a 24-pin address CPU is used.

Description:

A Stack Memory Relative operand specifies an operand at a memory address which is relative to the contents of a double-word in memory. The address is the sum of disp2 and the double-word at the address specified by the Stack-pointer relative value, disp1(sp).

```
Example:
```

```
1
                                TEN, 10
                          .set
2
                          .set
                                FIFTY, 50
3
4
  T00000000
              5404350f
                                r0, 15(FIFTY+3(sp))
                         movb
5
  T00000004
              17881400
                                 0((TEN*2)(sp)), r0
                         movd
```

In the above example, 15(FIFTY+3(sp)) is a Stack Memory Relative operand. The instruction copies the low-order byte of register r0 to the specified address. The address is the sum of 15 and the double-word at address FIFTY+3(sp). The address FIFTY+3(sp) is the sum of the symbol FIFTY, which evaluates to the absolute value 50, 3, and the contents of the current stack pointer.

In line 5, O((TEN*2)(sp)) is a Stack Memory Relative operand. The instruction copies the double-word at the address O((TEN*2)(sp)) into register r0. The address O((TEN*2)(sp)) is the sum of 0 and (TEN*2)(sp). (TEN*2)(sp) is the sum of 20 and the current contents of the Stack-pointer register.

NOTE: 24-pin address CPUs include the NS320xx and the NS32CG16.

32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.8 Static Memory Operands

Syntax:

disp(sb)

or

disp

^expression

where:

is a displacement or expression which evaluates to an

absolute value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin

address CPU.

(sb) specifies the Static Base register. Parentheses are

required.

expression

is a legal expression of any type.

NOTE: The GNX Assembler uses the range

-536870912 to 536870911. It is up to the user to limit this range if a

24-pin address CPU is used.

Description:

A Static Memory operand specifies an operand at a memory address. The address is the sum of the displacement disp and the contents of the Static Base register.

If the Static Memory operand is of the form ^expression, the address specified by expression is converted to an offset from the Series 32000 module's Static Base.

```
Example:
```

```
1
                              ..eet TEN, 10
2
3
  T00000000 81aec000
                                    INTEG, 31(sb)
                              addw
             00001f
  T00000007 43d514c0
                                    (TEN*2)(sb), INTEG
                              addd
             000000
  T0000000e 97aec000
                              movd INTEG, ^s_val
             0000c000
             018
6
                              .data
  D00000000 000000000 s_val:.double 0
```

In line 3 of the example, 31(sb) is a Static Memory operand. The instruction adds the word at the address specified by the symbol INTEG to the word at the memory address specified by 31(sb). The result is stored at 31(sb).

In line 4 of the example, (TEN*2)(sb) is a Static Memory operand. The expression "(TEN*2)" evaluates to the absolute value 20. This value is added to the contents of register sb to yield the operand's address. The instruction adds the double-word at this address to the double-word at the address specified by the symbol INTEG. The result is stored at INTEG.

In line 5 of the example, "^s_val" is a Static Memory operand. The displacement value is the distance from the Static Base to the address specified by the "s_val" label. Section 3.4 explains how the Static Base is determined. The instruction moves the value stored at the location INTEG to the s_val location.

NOTE: 24-pin address CPUs include the NS320xx and the NS32CG16.

32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.9 Static Memory Relative Operands

Syntax: disp2(disp1(sb))

where: disp2 is an expression of absolute type with a value in the

range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911

if the CPU is a 32-pin address CPU.

where: disp1 is a displacement or expression which evaluates to an

absolute base value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin

address CPU.

(sb) specifies the Static Base register. Parentheses are

required.

Parentheses are required around the static memory

value, disp1 (sb).

The GNX Assembler uses the range

-536870912 to 536870911. It is up to the user to limit this range if a

24-pin address CPU is used.

A Static Memory Relative operand specifies an operand at a memory Description:

address which is relative to the contents of a double-word in memory. The address is the sum of disp and the double-word at the address

specified by the sb relative value, disp1(sb).

Example: 1 TEN, 10 .set

> 2 .set FIFTY, 50

3

4 T00000000 9404320f movb r0, 15(FIFTY(sb))

T00000004 17901400 movd 0((TEN*2)(sb)), r0 In the above example, 15(FIFTY(sb)) is a Static Memory Relative operand. The instruction copies the low-order byte of register r0 to the specified address. The address is the sum of 15 and the double-word contents of the address FIFTY(sb). The address FIFTY(sb) is the sum of the symbol FIFTY, which evaluates to the absolute value 50, and the current contents of the sb register. In line 5 of the example, O((TEN*2)(sb)) is a Static Memory Relative operand. The statement moves the double-word pointed to by (TEN*2)(sb) to r0. (TEN*2)(sb) is the sum of 20 and the current contents of the Static Base register.

24-pin address CPUs include the NS320xx and the NOTE: NS32CG16.

> 32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.10 Program Memory Operands

Syntax:

* $\{ + | - \} disp$

or

%expression

where:

is the current contents of the Program Counter regis-

ter.

disp

is a displacement or expression which evaluates to an absolute value within the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin

address CPU.

expression

is a legal expression of any type.

NOTE:

The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a

24-pin address CPU is used.

Description:

A Program Memory operand specifies an operand at a memory address. The address is the sum of the displacement disp and the current contents of the Program Counter register.

If the Program Memory operand is of the form *%expression*, the address specified by expression is converted to an offset from the current location, *i.e.*, the contents of the Program Counter register.

Example:

1			.set	TEN, 10)
2					
3	T00000000	c1aec000	addw	INTEG,	*+31
		0000c000			
		001f			
4	T0000000a	43ddffff	addd	* - (TEN	2), INTEG
		ffecc000		,	
		0000			
5	T00000014	d7aec000	movd	INTEG,	%data
	10000014	00000000	mova	INTEG,	odaca
		000c			
6			.data		
7	D00000000	00000000	data: .double	0	

In line 3 of the example, "*+31" is a Program Memory operand. The instruction copies the word at the address specified by the symbol INTEG to the word at the memory address specified by the contents of the Program Counter register plus 31. The result is stored at the "*+31" address.

In line 4 of the example, "*-(TEN*2)" is a Program Memory operand. The expression "(TEN*2)" evaluates to the absolute value 20. This value is subtracted from the contents of the Program Counter register. The instruction adds the double-word at this address to the double-word at the address specified by the symbol INTEG. The result is stored at INTEG.

In line 5 of the example "%data" is a Program Memory operand. It is interpreted as the distance from the current location, i.e., the contents of the Program Counter register and the address specified by the "data" label. The instruction moves the value stored at the location INTEG to the location data.

24-pin address CPUs include the NS320xx and the NOTE: NS32CG16.

> 32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.11 Immediate Operands

Syntax:

\$expression

where:

expression

is one of the following:

- A short or long format floating-point value (refer to Section 2.4.2).
- A character constant (refer to Section 2.4.3).
- A legal expression of any type (refer to Section 2.7).

Description:

Immediate operands are encoded into the Immediate addressing mode: thus, the operand's value is stored in the instruction stream. If the expression is a relative type or an external, undefined type, the assembler generates a relocation entry for the operand. The linker uses the relocation entry to update the operand address at link time.

The range of immediate operands is limited by the length specifier of the instruction as follows:

• For expressions of type absolute, the ranges are:

-128..255

for byte instructions.

-32768..65535

for word instructions.

-2147483648..2147483647

for double-word instructions.

• For floating-point expressions, the positive ranges are:

 $1.18x10^{-38}..3.40x10^{38}$

for single-precision instruc-

tions.

2.23x10-308..1.80x10308

for double-precision instruc-

tions.

If a character constant is shorter than the length required by the instruction, the high-order bytes are zero-filled. If the relocated address of a relative type is too large for the instruction, an error occurs at link time.

Example:

```
NUMB, 5
 1
                           .set
 2
   T00000000
               55a50005
                          movw
                                  $NUMB, TEMP
               c0000000
 3
                                  $0f3.14152e26, f0
 4
   T00000008
               be01a06b
                          addf
               81ee23
 5
 6
   T0000000f
               57a50000
                                  $'?', LAST
                          movd
               003fc000
               0000
 7
 8
                           .set
                                  ONE, 1
 9
                           .set
                                  THREE, ONE+2
10
   T00000019
               04a003
                          cmpb
                                  $THREE, r0
```

Example line 2 copies the constant 5 to the memory address specified by TEMP.

Example line 4 adds the floating-point number 3.14152e26 to the contents of register f0.

Example line 6 copies the character constant '?' to the double-word at the address specified by LAST.

Example line 10 compares the value of the expression "ONE+2" with the low-order byte of register r0. The expression must evaluate to an absolute value in the range -128 to 255, in this case the value is 3.

4.2.12 Absolute Operands

Syntax: @expression

expression is a legal expression of any type. where:

Description: An Absolute operand specifies the absolute memory address of an

operand. Regardless of the type of the expression that specifies the address, or the default addressing mode that the assembler would otherwise use, an Absolute operand always implies the Absolute addressing

mode.

Examples: 1. addw \$H'1234, @9

> 2. addw @TWELVE, r0

3. .set BASE, 100 addw @BASE, r0

In example 1, @9 is an Absolute operand. The instruction adds the immediate operand H'1234 to the word starting at absolute address 9. The result is stored at the absolute address.

In example 2, @TWELVE is an Absolute operand. The symbol TWELVE may be of any type. The instruction adds the word at the absolute address specified by TWELVE to the low-order word of register r0. If TWELVE is a segment relative symbol (e.g., text, data, etc.) the assembler generates a relocation entry so that the correct address can be inserted at link time. The result is stored in r0.

In example 3, BASE is location 100, type absolute. The addw instruction adds the word at the absolute address specified by BASE to the low-order word of register r0. The result is stored in the low-order word of r0. The upper word of r0 is undisturbed.

4.2.13 External Operands

Syntax: disp(link offset(ext))

where: disp

is an expression with absolute type with a value in the range -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range -536870912 to 536870911 if the CPU is a 32-pin address CPU.

link offset

specifies the byte offset from the base of the Link Table. The link offset must be an expression of type link or type absolute, and a multiple of four bytes.

(ext)

is a literal that represents the base address of the Link Table. The Series 32000 processor gets this address from the Module Table entry for the current module. Parentheses are required.

Parentheses are required around the Link Table entry value, link offset (ext).

NOTE:

The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a 24-pin address CPU is used.

Description:

An External operand specifies a Link Table entry and, possibly, an offset. During execution the contents of the Link Table entry and the offset are added together to produce an address. External operands should be used only in Series 32000 modules.

Examples:

- 1. movb r0, 12(ext)
- 2. movb LAST, THREE (TWELVE (ext))

In example one, 12(ext) is an External operand. The instruction copies the low-order byte of register r0 to the byte specified by 12(ext). The external address is the sum of the double-word contents of the third Link Table entry and 0 (the default offset).

In example two, THREE(TWELVE(ext)) is an External operand. The instruction copies the byte at the address specified by LAST to the byte specified by THREE(TWELVE(ext)). The symbol THREE must evaluate to an absolute value. The symbol TWELVE must evaluate to an absolute value, or a value of type link, that is a multiple of four.

24-pin address CPUs include the NS320xx and the NOTE: NS32CG16.

> 32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.2.14 Top-of-Stack Operands

Syntax: tos

where: tos is the required keyword.

Description: A Top-of-Stack operand (tos) specifies an operand at the top of the stack.

The top of the stack is the address specified by the stack pointer. The stack pointer will be either the User Stack Pointer (sp1), or the Interrupt Stack Pointer (sp0) depending on the value of the s bit in the psr.

(Refer to Section 1.3.2.)

Top-of-Stack operands are encoded as tos addressing mode. (See the Series 32000 Programmer's Reference Manual.)

If a Top-of-Stack operand is read, the stack pointer is incremented by the length (in bytes) of the operand after the read is performed. If the operand is to be written, the operation decrements the stack pointer by the length (in bytes) of the operand before the write is performed. When an operand is both read and written, the stack pointer is not modified.

Examples: 1. movb r0, tos

2. addb tos, tos

Example 1 decrements the stack pointer by 1 and then copies the low-order byte of register r0 to the top of the stack.

Example 2 reads the byte at the top of the current stack, increments the stack pointer by 1, and adds this byte to the byte at the new top of stack.

4.2.15 Scaled-Index Byte Operands

Syntax:

gen [register:b]

where:

gen

specifies a general operand. It must not be an immedi-

ate operand or another Scaled-Index operand.

register

specifies a General-purpose register rn where n must

be a decimal digit in the range of 0 to 7.

:b

is the byte-scaling flag; it specifies a multiplier of 1.

The colon (:) is required.

[]

are the required brackets.

Description:

A Scaled-Index Byte operand specifies an operand at a memory address which is relative to the address specified by a general operand. The address is the sum of the contents of the General-purpose register rn multiplied by 1 and the address given by the general operand gen.

Example:

movb r0, 5(sp)[r1:b]

In this example, 5(sp)[r1:b] is a Scaled-Index Byte operand. The instruction copies the low-order byte of register r0 to the specified address. The address is the sum of the contents of the register r1 multiplied by 1 and the address specified by 5(sp).

4.2.16 Scaled-Index Word Operands

Syntax:

gen [register:w]

where:

gen

operand or another Scaled-Index operand.

register

specifies a General-purpose register rn where n must

be a decimal digit in the range of 0 to 7.

:w

is the word-scaling flag; it specifies a multiplier of 2.

The colon (:) is required.

[]

are the required brackets.

Description:

A Scaled-Index Word operand specifies an operand at a memory address which is relative to the address specified by a general operand. The address is the sum of the contents of the General-purpose register rn multiplied by 2 and the address of the general operand gen.

Example:

movb r2, 10(sb)[r6:w]

In this example, 10(sb)[r6:w] is a Scaled-Index Word operand. The instruction copies the low-order byte of register r2 to the specified address. The address is the sum of the contents of the register r6 multiplied by 2 and the address specified by 10(sb).

4.2.17 Scaled-Index Double-Word Operands

Syntax: gen [register:d]

where: specifies a general operand. It must not be an absolute gen

operand or another Scaled-Index operand.

register specifies a General-purpose register rn where n must

be a decimal digit in the range of 0 to 7.

is the double-word scaling flag; it specifies a multi-:d

plier of 4. The colon (:) is required.

are the required brackets. []

Description: A Scaled-Index Double-Word operand specifies an operand at a memory

address which is relative to the address specified by a general operand. The address is the sum of gen and the contents of the General-purpose register rn multiplied by 4 and the address of the general operand gen.

Example: r5, 10(r6)[r7:d] movb

> In this example, 10(r6)[r7:d] is a Scaled-Index Double-Word operand. The instruction copies the low-order byte of register r5 to the specified address. The address is the sum of the contents of register r7 multiplied

by 4 and the address specified by 10(r6).

4.2.18 Scaled-Index Quad-Word Operands

Syntax:

gen [register:q]

where:

gen

specifies a general operand. It must not be an Abso-

lute operand or another Scaled-Index operand.

register

specifies a General-purpose register n where n must

be a decimal digit in the range of 0 to 7.

: a

is the quad-word scaling flag; it specifies a multiplier

of 8. The colon (:) is required.

[]

are the required brackets.

Description:

A Scaled-Index Quad-Word operand specifies an operand at a memory address which is relative to the address specified by a general operand. The address is the sum of the contents of the General-purpose register rn multiplied by 8 and the address of the general operand gen.

Example:

movb r0, 8(fp)[r1:q]

In this example, 8(fp)[r1:q] is a Scaled-Index Quad-Word operand. The instruction copies the low-order byte of register r0 to the specified address. The address is the sum of the contents of register r1 multiplied by 8 and the address specified by 8(fp).

4.2.19 Displacement Operands

Syntax: addressing_mode

where: addressing_mode

is not Register, Top-of-Stack, External, Immediate, or

Scaled Indexed.

displacement_size

is an optional field. It can be one of the following:

specifies 1 byte displacement. :b

specifies 2 byte displacement. :w

:d specifies 4 byte displacement.

Description:

The displacement_size option allows the programmer to specify the size of the displacement field. If the desired displacement is too small, the assembler will issue an error. This feature is allowed only in an operand position and only if the operand involves a displacement.

D 1	
Examo	0
DAGILLO	LC.

1	T00000000	ea34		br L1:b
2	T00000002	a2a2a2a2		.space 10
		a2a2a2a2		
		a2a2		
3	T0000000c	ea8028		br L1:w
4	T0000000f	a2a2a2a2		.space 10
		a2a2a2a2		
		a2a2		
5	T00000019	eac00000		br L1:d
		1b		
6	T0000001e	a2a2a2a2		.space 10
		a2a2a2a2		
		a2a2		
7	T00000028	ea0c		br L1
8	T0000002a	a2a2a2a2		.space 10
		a2a2a2a2		
		a2a2		
9			L1:	

In this program, the branch on line 1 is requested to be placed in a byte-displacement field, the branch on line 3 is placed in a word-displacement field, the branch on line 5 is placed in a double-word-displacement field, and the branch on line 7 is placed in the smallest single displacement field in which it will fit.

4.3 IMMEDIATE SUBRANGE OPERANDS

All Immediate Subrange operands are expressions of absolute type with values within subranges of the full double-word range.

4.3.1 Quick Operands

Syntax:

[\$]quick

Description:

A signed constant or expression which evaluates to a constant immediate value within the range of -8 to 7 inclusive.

A Quick operand is encoded as a 4-bit signed integer in a field of the instruction. Quick operands are used in the quick-integer instructions. (See Section 5.3.) A Quick operand is the first operand in the following instructions:

Move Quick Integer	movqi
Compare Quick Integer	${ m cmpq}i$
Add Quick Integer	$\operatorname{addq} i$
Add, Compare, and Branch	acbi

Examples:

-2, FIRST(r1) 1. movqd 2. 5, TEMP cmpqw 3. addqb -1, r1 4. LOOP: muld r2, r1 -1, r0, LOOP acbb

Example 1 copies the Quick operand -2 to the Double-word operand at the address specified by FIRST(r1).

Example 2 compares the Quick operand 5 with the Word operand specified by TEMP.

Example 3 adds the Quick operand -1 to the low-order byte of register

In Example 4, the acbb instruction adds -1 to the low-order byte of register r0 and passes execution to the muld statement labelled LOOP as long as the result is not zero.

4.3.2 Block Length Operands

Syntax:

[\$]integer_cons

Description:

An unsigned constant or expression which evaluates to an absolute value within the range of 1 to 16 (see below).

A Block Length operand is an unsigned constant which specifies the length of a block of integers. The block may be no more than 16 bytes in length. Therefore, the range of values the constant may have depends on the instruction's length specifier (b, w, or d) as shown by the following:

Length Specifier	Integer Size (Bytes)	Range
b	1	1 to 16
w	2	1 to 8
d	4	1 to 4

At assembly-time, the operand is multiplied by the corresponding integer size and then decremented by one, before being encoded in the instruction.

A Block Length operand is the last operand in the following instructions:

Move Multiple movmi Compare Multiple cmpmi

Examples:

- 1. movmd GEN1, GEN2, 3
- 2. cmpmw GEN1, GEN2, NELEMENTS

In example 1, the block length 3 specifies the number of double-words to move from the address specified by GEN1 to the address specified by GEN2.

In example 2, the block length is the expression "NELEMENTS." It specifies the number of elements to be compared. NELEMENTS must evaluate to a number in the range of 1 to 8.

4.3.3 Bit-Field Length Operands

Syntax: [\$]integer_cons

Description: An unsigned constant or an expression which evaluates to an absolute value within the range of 1 to 32. At assembly-time, the number is

decremented by 1 before being encoded into the instruction.

A Bit-Field Length operand is an unsigned number. It specifies the length of a bit field in a bit-field instruction (Section 5.7). The length operands of the short bit-field instructions are encoded into a 5-bit field and into a byte in the other bit-field instructions. A Bit-Field Length operand is the last operand in the following instructions:

Extract Field exti**Insert Field** insi Extract Field Short extsiInsert Field Short inssi

Examples:

```
1. extsw
          BASE, DEST, 3, 14
2. inssb
          SRC, BASE, 7, 10
```

In example one, 14 is the bit-field length constant. The instruction computes the location of a bit field that is 14 bits in length at 3 bits offset from the address specified by BASE and then copies the field to the address specified by the symbol DEST.

In example two, 10 is the bit-field length constant. The instruction computes the destination of a bit field that is 10 bits in length by adding a bit offset 7 to the address referenced by BASE. It then moves the field from the address specified by SRC to the destination.

4.3.4 Bit-Field Offset Operands

Syntax: [\$]integer cons

Description: An unsigned constant or expression which evaluates to an absolute value within the range of 0 to 7.

> A Bit-Field Offset operand is an unsigned number. It specifies an offset which is used to compute the location of the first bit in a bit field. A Bit-Field Offset operand is the third operand in the following instructions:

Extract Field Short extsi Insert Field Short inssi.

Examples:

- 1. extsw BASE, DEST, 3, 14
- 2. inssb SRC, BASE, 7, 10

In example one, 3 is a Bit-Field Offset constant. The instruction copies a field, 14 bits in length, to the address specified by the symbol DEST and zero-fills the high-order two bits. The field's location is specified by adding a bit offset of 3 to the address BASE.

In example two, 7 is a Bit-Field Offset constant. The instruction copies SRC into the bit field addressed by adding a bit offset 7 to the address referenced by BASE. The length of the field to be written to is 10 bits.

4.3.5 Displacement Operands

Syntax:

[\$]disp

Description:

A constant or expression which evaluates to an absolute base value within the range of -16777215 to 16777215 if the CPU is a 24-pin address CPU, or the range of -536870912 to 536870911 if the CPU is a 32-pin address CPU.

NOTE:

The GNX Assembler uses the range -536870912 to 536870911. It is up to the user to limit this range if a 24-bit CPU is used.

A Displacement operand specifies a signed integer. A Displacement operand is the last (or only) operand in the following instructions:

Extract Field	${f ext}i$
Insert Field	${ m ins} i$
Return From External Procedure	rxp
Return from Trap	rett
Enter New Context	enter
Return from Subroutine	\mathbf{ret}

Examples:

```
1. extw r2, BASE, DEST, 4
2. insb r0, r2, 0(r1), 7
3. rxp 5
4. rett 1
5. enter [r0], 2
6. ret 0
```

In example 1, the displacement is 4. It specifies the length of a field.

In example 2, the displacement is 7. It specifies the number of bits in the field to be written to.

In example 3, the displacement is 5. It specifies the number of bytes to be removed from the stack on the return from an external procedure.

In example 4, the displacement is 1. It specifies the number of bytes to be removed from the stack on the return from a trap.

In example 5, the displacement is 2. It specifies the number of bytes to allocate on the stack on entry to a procedure.

In example 6, the displacement is 0. It specifies the number of bytes to remove from the stack on the return from a local procedure.

Displacement operands are encoded the same way as memory displacements are. This format is described in the Series 32000 Programmer's Reference Manual.

NOTE: 24-pin address CPUs include the NS320xx and the NS32CG16.

> 32-pin address CPUs include the NS32332, NS32532, NS32FX16, NS32CG160, NS32GX32, and the NS32GX320.

4.4 PROGRAM MEMORY OPERANDS

Syntax:

label

where:

label

is a legal expression of any type.

Description:

A Program Memory operand specifies the destination of a branch instruction. The operand is interpreted as the address of the destination of the branch. The assembler converts this address to an offset from the current location counter. The Label operand must specify the address of the first byte of an instruction.

The Program Memory operand *label* may also use the syntax of the general Program Memory class operands, refer to Section 4.2.10.

A Label operand is the last (or only) operand in the following instructions:

Branch on Condition	bcond
Unconditional Branch	br
Add, Compare, and Branch	acbi
Branch to Subroutine	bsr

Examples:

- 1. beq EQUAL
- 2. br * + 8
- 3. acbb -1, r0, * 12
- 4. bsr SUBROUTINE

In example 1, the Label operand is the label EQUAL. If the z flag in the psr is set, the instruction passes control to the location EQUAL.

In example 2, the Label operand is the "*+8" expression. The "*" symbol specifies the current location counter as a pc-relative address. The expression evaluates to a pc-relative address which is 8 bytes from the current location.

In example 3, the Label operand is "* - 12" which evaluates to a PCrelative value. As long as the contents of register r0 remains non-zero, the program continues its execution at a point which is 12 bytes lower than the current program code address.

In example 4, the Label operand is the label SUBROUTINE. When executed, the instruction transfers program control to the subroutine referenced by the label SUBROUTINE.

4.5 GENERAL REGISTER OPERANDS

Syntax:

register

Description:

A General-purpose register specified by rn, where n must be a decimal digit in the range of 0 to 7.

A General Register operand specifies one of the General-purpose registers. The value of the operand is the value contained in the register. A General Register operand is the first operand in the following instructions:

Extract Field exti
Insert Field insi
Convert to Bit Pointer cvtp
Check Array Index checki
Calculate Array Index indexi

General Register operands differ from Register operands (Section 4.2.2) only in that Register operands can be used with floating-point instructions to specify floating-point registers.

Examples:

```
1. extw r2, BASE.A, DEST.A, 5
2. insb r0, r2, 0(r1), 7
3. cvtp r1, BASE.B, DEST.B
4. checkw r3, BOUND1, K
5. indexd r5, 3, J
```

In example 1, the General Register operand is r2. The contents of register r2 (together with the values of BASE.A and the displacement 5) is used as an offset to compute the location of a bit field which is five bits long. The field is copied to the address specified by DEST.A.

In example 2, the General Register operand is r0. The contents of register r0 is used as an offset from the base 0(r1) to specify the starting bit of the desired bit field.

In example 3, the General Register operand is r1. The contents of register r1 (together with the value of BASE.B) is used to compute the bitaddress of a bit of memory. The bit-address is copied to DEST.B.

In example 4, the General Register operand is r3. The contents of register r3 reflects the difference between an array's lower bound, addressed by BOUND1, and an index K into the array.

In example 5, the General Register operand is r5. The register contains the accumulated index into an array. This index is generated by adding 1 to 3, multiplying this result by the previous contents of register index, and then adding the value referenced by J to this product.

4.6 REGISTER LIST (reglist) OPERAND

Syntax: [[register,,,]]

where:

[] are the required brackets. The brackets are required

even if no registers are specified.

register

specifies a symbol with register type.

Description:

A Register List operand specifies one or more General-purpose registers.

A Register List operand may be used in the following instructions:

Save Registers save Restore Registers restore Enter New Context enter Exit Context exit

Examples:

```
1. save
           [r1]
2. restore [r0, r1]
           [r0, r1, r2, r3, r4, r5, r6, r7], 5
3. enter
4. exit
           [ ]
```

In example 1, the operand specifies a single register r1. The contents of register r1 are saved on stack.

In example 2, the operand specifies two registers: r0 and r1. The instruction pops two consecutive double-words from the stack to the registers.

In example 3, the operand specifies all eight General-purpose registers. The instruction copies the contents of the eight General-purpose registers to consecutive double-words on stack. The Displacement operand 5 is then used to allocate five bytes of the stack for storage.

In example 4, the operand specifies no General-purpose registers and none are popped off the stack when the exit instruction is executed.

4.7 CONFIGURATION LIST (cfglist) OPERAND

Syntax:	[[c][i][de][r	n][f] [ff][fm][fc][p]]
where:	[]	are the required brackets. The brackets are required even if no configuration bit is specified.
	С	specifies the Clock Scaling bit for NS32CG16, NS32FX16, and NS32CG160.
		specifies the Custom Slave bit for the rest of the $Series$ 32000 processors.
	i	specifies the Interrupt Control Unit bit.
	de	specifies the direct exception bit in the NS32CG160.
	m	specifies the Clock Scaling Factor bit for the NS32CG16, NS32FX16, and NS32CG160.
		illegal for the NS32008, NS32GX32, and NS32GX320.
		specifies the Memory Management Unit bit for the NS32016, NS32032, NS32332, and NS32532.
	f	specifies the Floating-Point Unit bit.
	ff	specifies the Fast FPU Protocol bit, NS32332 and NS32532 only.
	fm	specifies the Fast MMU Protocol bit, NS32332 and NS32532 only.
	fc	specifies the Fast Custom Slave Protocol bit, NS32332 and NS32532 only.
	р	specifies the 4096 bytes page size bit, NS32332 and NS32532 only.

If a configuration option is specified, the corresponding bit in the $Series\ 32000$ Configuration register is set (see the data sheet for the

appropriate Series 32000 processor); otherwise, the bit is cleared. Any combination is allowed; however, if more than one bit is specified, they must be separated by commas.

Description:

A Configuration List operand specifies Configuration register bits. The list may specify any combination of the bits, depending on which devices are present in the system.

A Configuration List operand may be used in the setcfg instruction.

Examples:

1. setcfg [] 2. setcfg [f] 3. setcfg [de]

In example 1, the operand specifies no register bits. The instruction clears all bits in the Configuration register.

In example 2, the operand specifies the f bit. The instruction sets the f bit and clears the i, m, and c bits.

In example 3, the operand specifies the de bit of the NS32CG160.

4.8 PROCESSOR REGISTER OPERANDS

Syntax: procreg

Specifies a Dedicated register. It must be one of the following register Description:

names:

upsr User Processor Status Register Frame Pointer fp Stack Pointer spsbStatic Base

Processor Status Register psr

intbase **Interrupt Base**

Module mod

The function of the Dedicated registers is described in Section 1.3.2.

A Processor Register operand specifies a Dedicated register. A Processor Register operand is the first operand in the following instructions:

Load Processor Register lpri Store Processor Register spri

Examples:

1. lprw mod, r1 2. sprb upsr, TEMP

In example 1, mod is the Processor Register operand. The instruction copies the low-order word in register r1 to the Module register.

In example 2, upsr is the Processor Register operand. The instruction copies the low-order byte of the Processor Status register (i.e., the user's part of the psr) to the address specified by the symbol TEMP.

4.9 NS32082 MEMORY MANAGEMENT REGISTER OPERAND

Syntax:

mmureg

Description:

Specifies a NS32082 Memory Management register. It must be one of the following register names:

bpr0	Breakpoint Register 0
bpr1	Breakpoint Register 1
pf0	Program Flow 0
pf1	Program Flow 1
bent	Breakpoint Count
ptb0	Page Table Base 0
ptb1	Page Table Base 1
sc	Sequential Count 0 and Sequential Count 1
msr	Memory Management Status Register
eia	Error/Invalidate Address

Memory Management registers are described in Section 1.3.4 and in the NS32082 Data Sheet.

A Memory Management Register operand specifies a Memory Management register. A Memory Management Register operand is the first operand in the following instructions:

Load Memory Management Register lmr Store Memory Management Register smr

Examples:

```
1. lmr
                SETBPR0
         bpr0,
2. smr
         msr,
                SAVEMSR
```

In example 1, bpr0 is the Memory Management Register operand. The instruction loads the double-word at the address specified by SETBPR0 into the Breakpoint Register 0.

In example 2, msr is the Memory Management Register operand. The instruction stores the double-word contents of the msr at the address specified by the symbol SAVEMSR.

4.10 NS32382 MEMORY MANAGEMENT REGISTER OPERAND

Syntax:

mmureg

Description:

Specifies an NS32382 Memory Management register. It must be one of the following register names:

bar Breakpoint Address Register
bmr Breakpoint Mask Register
bdr Breakpoint Data Register
ivar0 Invalid Virtual Address Register 0
ivar1 Invalid Virtual Address Register 1
mcr MMU Control Register
msr MMU Status Register

tear Translation Exception Address Register

bear Bus Error Address Register

ptb0 Page Table Base 0ptb1 Page Table Base 1

Memory Management registers are described in Section 1.3.4 and in the NS32382 Data Sheet.

A Memory Management Register operand specifies a Memory Management register. A Memory Management Register operand is the first operand in the following instructions:

Load Memory Management Register lmr Store Memory Management Register smr

Examples:

1. lmr bpr0, SETBPR0
2. smr msr, SAVEMSR

In example 1, bpr0 is the Memory Management Register operand. The instruction loads the double-word at the address specified by SETBPR0 into the Breakpoint Register 0.

In example 2, msr is the Memory Management Register operand. The instruction stores the double-word contents of the msr at the address specified by the symbol SAVEMSR.

4.11 NS32532 MEMORY MANAGEMENT REGISTER OPERAND

Syntax: mmureg

Specifies an NS32532 Memory Management register. It must be one of Description: the following register names:

> ivar0 Invalid Virtual Address Register 0 ivar1 Invalid Virtual Address Register 1

MMU Control Register mcr MMU Status Register msr

Translation Exception Address Register tear

Page Table Base 0 ptb0 ptb1 Page Table Base 1

Memory Management registers are described in Section 1.3.4 and in the NS32532 Data Sheet.

A Memory Management Register operand specifies a Memory Management register. A Memory Management Register operand is the first operand in the following instructions:

Load Memory Management Register lmr Store Memory Management Register smr

Examples:

1. lmr bpr0, SETBPR0 2. smr msr, SAVEMSR

In example 1, bpr0 is the Memory Management Register operand. The instruction loads the double-word at the address specified by SETBPRO into the Breakpoint Register 0.

In example 2, msr is the Memory Management Register operand. The instruction stores the double-word contents of the msr at the address specified by the symbol SAVEMSR.

4.12 EXTERNAL PROCEDURE OPERANDS

Syntax:

external

Description:

An operand of the general operand type External with no offset, or a procedure label for which a Link Table entry has been defined.

An External Procedure operand specifies an entry in the Link Table for an external procedure descriptor. Link Table entries for external procedures, called external procedure descriptors, consist of the 16-bit address of an entry in the Module Table and a 16-bit offset. During execution, the address of the external procedure is calculated by adding the offset to the address in the Module Table entry. (See the section on software modules in the Series 32000 Programmer's Reference Manual.)

An External operand is the first operand in the following instructions:

Call External Procedure cxp

Example:

.globl OUT

.link

.xpd OUT

.text

cxp OUT

In this example, OUT is an External operand. OUT references a Link Table entry address. The Link Table entry offset of OUT is divided by four to obtain the Link Table entry number. The double-word at this Link Table entry number specifies a Module Table entry and an offset from the address contained in the Module Table entry. The address plus offset is the start address of a procedure.

4.13 LENGTH OF DISPLACEMENTS

The GNX Assembler attempts to determine the optimal number of bytes to allocate for each displacement it assembles, *i.e.*, the smallest number of bytes into which the displacement value will fit. If an expression involves a forward reference, the displacement size cannot be determined until the reference is defined. If an expression is composed of one undefined symbol plus or minus a constant, the Assembler allocates one byte and makes an entry in the span-dependent instruction link list. The actual size required to hold the displacement is determined at the completion of the first pass. If the size of the displacement cannot be determined at assembly time, the GNX Assembler uses the largest displacement size available by default.

The Assembler determines displacement length by the following rules:

- 1. If the expression evaluates to a defined absolute value, the Assembler uses the smallest displacement that will fit.
- 2. If the expression can be evaluated and the type is relocatable, that is, relative to the memory location into which an object file segment will be loaded, then the Assembler allocates the maximum number of bytes and generates a relocation entry. The relocation entry will be used to determine the actual address at link time.
- If the expression contains an external, undefined term, the maximum displacement is generated.
- 4. Optimizing of displacement may be overridden by using the displacement operands, refer to Section 4.2.19, or the -n flag (or /nosdi flag for VMS).

A programmer may set the maximum length displacement using a command line argument. If the maximum size chosen is too small, an error will result at link time. See Chapter 9.

NOTE: Displacements which span an .align directive use the maximum length displacement.

For example:

uses 4 bytes or a user-specified disp for displacement.

SERIES 32000 INSTRUCTION SET

5.1 INTRODUCTION

This chapter presents the syntax of the Series 32000 assembly language instruction set. The syntax describes the following:

- Opcode Mnemonic
- Operands

The opcode mnemonic specifies the operation to be performed by the instruction. In most cases, the opcode mnemonic consists of three or more letters and one of the following:

```
i — length of integer operands — must be b (byte), w (word), or d (double-word)
f — length of floating-point operands — must be f (float) or 1 (long)
```

When encoding an instruction, the i and f must be replaced by the appropriate operand length specifier.

The operand syntax specifies the number, type, and access class of the operands. The first line of the operand description indicates the use for the operand, e.g., the first operand of movi is marked src; therefore, that operand is the source for the move. The second line, when present, indicates the access class for the operand. For a complete discussion of the access classes, see the Series 32000 Programmer's Reference Manual. The operand type is indicated by a combination of the access class and, when present, a third line. Most of the operands can use any of the general operand types. The general operands use a particular set of access classes, so the access class alone is used to identify a general operand. For nongeneral operands the access class is not sufficient; the third line of the operand description states the specific type of operand for nongeneral operands.

The general operand access classes are:

read	— the operand is read.
write	— the operand is written.
rmw	— the operand is read, modified, and written.
addr	- the address of the memory location designated by the
	operand is calculated. Whether or not the address is
	accessed depends upon the instruction.

regaddr — the operand designates either a memory location or a general register which is in turn used as a base for a bit address calculation.

The other access classes used are:

quick — 4-bit constant is read
reg — double-word from register is read
short — 4-bit condition code is read
imm — a) 8-bit register mask is read
b) concatenated 5-bit and 3-bit constants are read
disp — 1-, 2-, or 4-byte displacement is read

NOTE: The GNX Assembler groups quick, *imm* type b and disp operands together as immediate subrange operands (Section 4.3), the 5-bit field of imm type b. The GNX Assembler uses bit-field offset operands to store the 3-bit field of imm type b. The GNX Assembler uses block-length operands to store the 4-bit constant of the movmi and cmpmi instructions. (The constant is encoded in a disp operand.)

Instead of being a member of one of the access classes an operand may be:

```
cond
                          - equal: z=1
               = eq
                          — not equal: z=0
                  ne
                          - carry set: c=1
                  CS
                          -- carry clear: c=0
                  cc
                          — lower: z=0 and l=0
                  lo
                  hs
                          — higher or the same: z=1 or l=1
                  lt
                          - less than: z=0 and n=0
                          — greater than or equal: z=1 or n=1
                  ge
                          - flag set: f=1
                  fs
                          - flag clear: f=0
                  fc
                          — higher: l=0 and z=0
                  hi
                  ls
                          - lower or the same: l=1
                          — greater than: n=1
                  gt
                  le
                          — less than or equal: n=0
cfglist
                = [[i][f][de][m][c][ff][fm][fc][p]]
                  []
                          - no slaves
                  i
                          — ICU (Interrupt Control Unit)
                  de

    Direct exception

                  f
                          - FPU (Floating-Point Unit)
                          - MMU (Memory Management Unit)
                  m
                             or Clock scaling factor
                          — Custom slave clocking scale or clock scaling list
                  c
                  ff
                          - Fast FPU
```

```
fm

    Fast MMU (32332 and 32532 only)

                 fc

    Fast Custom (32332 and 32532 only)

                         — 4 Kbytes (4096 byte) page (32332 and 32532 only)
                 р
procreg
               = upsr
                         — User psr (low byte in psr)
                 fp

    Frame Pointer

                 sp

    Stack Pointer

                 sb
                         - Static Base
                         - Processor Status Register
                 intbase — Interrupt Base
                 mod
                         — Module
               = bpr0
                         - Breakpoint Register 0
mmureg
(NS32082)
                         - Breakpoint Register 1
                 bpr1
                         - Program Flow 0
                 of0
                 pf1
                         - Program Flow 1
                         - Sequential Count Registers sc0 and sc1
                 SC
                         - Memory Status Register
                 msr
                         - Breakpoint Count
                 bcnt
                         - Page Table Base 0
                 ptb0
                 ptb1
                         — Page Table Base 1
                 eia

    Error/Invalidate Address

mmureg
               = bar

    Breakpoint Address Register

(NS32382)
                 bmr
                         - Breakpoint Mask Register
                 bdr

    Breakpoint Data Register

                         - Invalid Virtual Address Register 0
                 ivar()
                         - Invalid Virtual Address Register 1
                 ivar1
                         - MMU Control Register
                 mcr
                 msr
                         - MMU Status Register
                         — Translation Exception Address Register
                 tear
                 bear
                         - Bus Error Address Register
                 ptb0
                         — Page Table Base 0
                 ptb1
                         - Page Table Base 1
mmureg
               = ivar0

    Invalid Virtual Address Register 0

(NS32532)

    Invalid Virtual Address Register 1

                 ivar1
                         - MMU Control Register
                 mcr
                 msr
                         - MMU Status Register

    Translation Exception Address Register

                 tear
                 ptb0
                         - Page Table Base 0
                         — Page Table Base 1
                 ptb1
[b[,]][u \mid w] = b
                         - backwards
                         - while
```

b, w - backwards and while

u — until

b, u — backwards and until

When encoding an instruction, the above operand names must be replaced with appropriate operands. Operand types and syntax are described in detail in Chapter 4. Commas, if shown, are required.

Some instructions are privileged and may be executed only when the system is in the supervisor-mode (*i.e.*, the u bit in the *psr* is clear). In the following sections, the symbol "§" specifies a privileged instruction.

Instruction operations are defined in the Series 32000 and Series 32000/EP Programmer's Reference Manuals.

NOTE: The MMU can generate an ABT trap for any instruction; this occurs when the instruction or operand is stored in, or tries to write to, an address not currently in memory or in a protected memory location. Some instructions may cause an ABT without themselves causing a page fault. Only this latter group of instructions are marked as capable of taking an ABT trap.

The following notations are used in the description of the action of the instructions:

OPERATIONS

Operators	Definition
t=	replace value on left with value on right.
+, -, * div / mod **	addition, subtraction, multiplication. division with truncation. division with rounding toward negative infinity. modulus (or remainder after "div"). exponential operator.
AND NOT(name) OR XOR	bit-wise logical AND. bit-wise complement of name. bit-wise logical OR. bit-wise logical exclusive OR.
SIGN(name) BIT(base, offset) FIELD(base, offset, length)	evaluates to sign bit of name. evaluates to bit at bit address 8*base+offset. evaluates to field at bit address 8*base+offset; length is field length in bits.
$egin{array}{l} WORD(address) \ DOUBLEWORD(address) \ ADDR(name) \end{array}$	word operand from address. double-word operand from address. evaluates to address of name.
return address	address of next sequential instruction after a Branch, Jump, Call instruction.
PUSHi(name) POPi(name)	push argument name, of length i , onto the stack. pop item, of length i , from the stack into name.

TRAPS

Trap N	ame	Taken on
DVZ	=Divide by Zero Trap	a zero divisor in a Divide, Modulus, Quotient, Remainder, or Divide Extended Integer instruction.
ILL	=Illegal Instruction Trap	a Privileged instruction when u=1
UND	=Undefined Instruction Trap	a Memory Management instruction when cfg m=0, or a Floating-point instruction when cfg f=0, or any undefined operation codes.
FPU	=Floating-Point Error Trap	a Floating-point instruction on: Underflow Overflow Invalid Division Illegal Instruction Reserved Operand Inexact Result
SVC	=Supervisor Trap	a Supervisor Call instruction.
FLG	=Flag Trap	a Flag instruction when f=1.
BPT	=Breakpoint Trap	a Breakpoint instruction.
ABT	=Instruction Abort Trap	a Page fault.
TRC	=Trace Trap	instruction completion while in trace mode (Series 32000 family only)
SLAVE	E =Slave Trap	exceptional condition detected during slave instruction execution.
OVF	=Integer Overflow Trap	detected overflow during integer instruction execution (NS32532, NS32GX32, and NS32GX320 only).
DBG	=Debug Trap	a condition selected by a DSR bit is detected (NS32532, NS32GX32, and NS32GX320 only).

5.2 INTEGER INSTRUCTIONS

SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
A	rithmetic Ins	structions			
add <i>i</i>	<i>src</i> , read. <i>i</i>	dest rmw.i	Add	c f	_
			<pre>dest := dest + src c := 1 on carry; c := 0 on no carry f := 1 on overflow; f := 0 on no overflow</pre>		
addci	src, read.i	dest rmw.i	Add with Carry	c f	_
			dest := dest + src + c c := 1 on carry; $c := 0$ on no carry f := 1 on overflow; $f := 0$ on no overflow		
cmp <i>i</i>	src1,	src2	Compare	z	
	read.i	read.i	<pre>z := 1 if src1=src2; z := 0 otherwise n := 1 if src1>src2; n := 0 otherwise (signed operands) l := 1 if src1>src2; l := 0 otherwise (unsigned operands)</pre>	n l	
sub <i>i</i>	src, read.i	dest rmw.i	Subtract dest := dest - src c := 1 on borrow; c := 0 on no borrow f := 1 on overflow; f := 0 on no overflow	c f	_
subc <i>i</i>	src, read.i	dest rmw.i	Subtract with Borrow dest := dest - (src + c) c := 1 on borrow; c := 0 on no borrow c := 1 on overflow; f := 0 on no overflow	c f	_
negi	<i>sr</i> c, read. <i>i</i>	<i>dest</i> write. <i>i</i>	Negate dest := 0 - src c := 1 on carry; c := 0 on on carry f := 1 on overflow; f := 0 on no overflow	c f	_
absi	src, read.i	<i>dest</i> write. <i>i</i>	Absolute Value if $src < 0$, then $dest := 0 - src$; $f := 1$ on overflow $f := 0$ on no overflow else $dest := src$; $f := 0$	f	_

INTEGER INSTRUCTIONS (Cont)

SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
Arith	metic Instr	uctions			
mul <i>i</i>	src, read.i	dest rmw.i	Multiply	_	_
			dest := src * dest		
div <i>i</i>	src, read.i	dest rmw.i	Divide	_	DVZ
	70441		if src=0, then TRAP(DVZ) else dest := dest DIV src		
			(signed division; dest DIV src rounded toward negative infinity)		
$oxdot{mod}i$	src, read.i	dest rmw.i	Modulus	_	DVZ
			if src=0, then TRAP(DVZ) else		
			<pre>dest := dest - src*(dest DIV src) (signed division; dest DIV src rounded toward negative infinity)</pre>		
quo <i>i</i>	src, read.i	dest rmw.i	Quotient	_	DVZ
	10441	····	if src=0, then TRAP(DVZ) else dest := dest/src		
			(signed division; dest/src round toward zero)		
rem <i>i</i>	src, read.i	dest rmw.i	Remainder		DVZ
			if src=0, then TRAP(DVZ) else dest := dest - src*(dest/src)		
			(signed division; dest/src rounded toward zero)		
Move Ins	tructions				
movi	src, read.i	dest write.i	Move	_	_
	•		dest := src		
movxbw	<i>src</i> , read.b	dest write.w	Move Sign-Extending Byte to Word	_	_
			dest (low-order byte) := src dest (high-order bits) := SIGN(src)		
movxbd	src, read.b	<i>dest</i> write.d	Move Sign-Extending Byte to Double-Word	_	_
			dest (low-order byte) := src dest (high-order bits) := SIGN(src)		

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
Mo	ve Instruct	ions			
movxwd	src, read.w	<i>dest</i> write.d	Move Sign-Extending Word to Double-Word	_	_
	roudin	W112014	<pre>dest (low-order byte) := src dest (high-order bits) := SIGN(src)</pre>		
movzbw	<i>src</i> , read.b	<i>dest</i> write.w	Move Zero-Extending Byte to Word	_	_
			<pre>dest (low-order byte) := src dest (high-order bits) := 0</pre>		
movzbd	src, read.b	<i>dest</i> write.d	Move Zero-Extending Byte to Double-Word		_
			dest (low-order byte) := src		
			dest (high-order bits) := 0		
movzwd	<i>src</i> , read.w	<i>dest</i> write.d	Move Zero-Extending Word to Double-Word	_	_
			dest (low-order word) := src		
			dest (high-order bits) := 0		
addr	<i>sr</i> c, addr	<i>dest</i> write.d	Compute Effective Address		_
	uuu		dest := ADDR(src)		
Shift Inst	ructions				
ash <i>i</i>	count, read.B	dest rmw.i	Arithmetic Shift (Left or Right)	_	_
	read.D	Imw.	<pre>if count< 0, then dest := dest shifted right by count bits, emptied bit positions filled from original sign bit.</pre>		
			else dest := dest shifted left by I count I bits, emptied bit positions filled with zero.		
lsh <i>i</i>	count, read.Bi	dest rmw.i	Logical Shift (Left or Right)	_	_
	read.Di	1111W.2	<pre>if count < 0, then dest := dest shifted right by count bits, emptied bit positions filled with zeroes.</pre>		
			else dest := dest shifted left by count bits, emptied bit positions filled with zeroes.		
roti	count, read.Bi	dest rmw.i	Rotate (Left or Right)	_	_
	- 344127		<pre>if count< 0, then dest := dest shifted right by count bits, end-around.</pre>		
			else dest := dest shifted left by count bits, end-around.		

INTEGER INSTRUCTIONS (Cont)

SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
	Logical Instruc	tions			
and <i>i</i>	src,	dest	Logical AND		_
	read.i	rmw.i	dest := dest AND src		
ori	,	dest	Logical OR		_
	read.i	rmw.i	$dest := dest \ OR \ src$		
bici	src,	dest	Bit Clear		_
	read. i	rmw. <i>i</i>	dest := dest AND NOT(src)		
xori	src,	dest	Exclusive OR		_
	${\sf read}.i$	rmw.i	dest := dest XOR src		
com <i>i</i>	src,	dest	Complement	_	
	read.i	write.i	dest := NOT(src)		

5.3 QUICK INTEGER INSTRUCTIONS

SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN	
movq <i>i</i>	<i>src</i> , quick quick	dest write.i dest := src	Move Quick Integer	_	_
			(src sign-extended to dest length)		
${ m cmpq}i$	src1, quick	src2 read.i	Compare Quick Integer	z	_
	quick		<pre>z := 1 if src2=src1; z := 0 otherwise n := 1 if src2<src1; (signed="" (unsigned="" :="0" if="" l="" n="" operands)="" operands)<="" otherwise="" pre="" src2<src1;=""></src1;></pre>	1	
			(src1 sign-extended to src2 length)		
addqi	<i>src</i> , quick	dest rmw.i	Add Quick Integer	c f	_
	quick		<pre>dest := dest + src c := 1 on carry; c := 0 on no carry f := 1 on overflow; f := 0 on no overflow (src sign-extended to dest length)</pre>		

EXTENDED INTEGER INSTRUCTIONS

5.4 EXTENDED INTEGER INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
mei <i>i</i>	src, read.i	dest rmw.2i	Multiply Extended Integer		-
			$dest := src * (dest \mod 2^{**i})$ (unsigned operands) (low-order half of $dest$)		
đei <i>i</i>	src, read.i	dest rmw.2i	Divide Extended Integer	-	DVZ
			dest := (dest div src) * 2**i + dest mod src (unsigned operands)		

5.5 BOOLEAN INSTRUCTIONS

SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
noti	src,	dest	NOT	<u></u>	
	${ m read.} i$	write.i	dest := src XOR 1		
s $\{cond\}i$		<i>dest</i> write.i	Save Condition Code as a Boolean	_	_
			if cond, then		
			dest := 1 else,		
			dest := 0		

5.6 BIT INSTRUCTIONS

SYNTAX				OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
tbit <i>i</i>	offset,	base		Test Bit	f	_
	read.i	regaddı	•	f := BIT(base, offset)		
$\mathrm{sbit}\big[\mathrm{i}\big]i$	offset, read.i	<i>base</i> regaddi	-	Set Bit	f	_
	1eau.	regaddi		f := BIT(base, offset) BIT(base, offset) := 1		
$\mathrm{cbit} \big[\mathrm{i} \big] i$	offset,	<i>base</i> regaddi	_	Clear Bit	f	
	${\tt read}.i$		•	f := BIT(base, offset) BIT(base, offset) := 0		
ibit <i>i</i>	offset,	<i>base</i> regaddr	_	Invert Bit	f	_
	read. <i>i</i>		•	f := BIT(base, offset) BIT(base, offset) := NOT[BIT(base, offset)]		
cvtp	offset,	<i>base</i> , addr	dest write.d	Convert to Bit Pointer	_	_
	reg reg		witte.u	$dest := (8*ADDR(base) + offset) \bmod 2**32$		
ffsi	<i>base</i> , read.i	offset rmw.B		Find First Set Bit	f	_
	reau.	imw.b		if (offset<0 or offset≥length in bits of base), then operation is undefined else j:= offset while (j < length of base and BIT (base,j) = 0) do j:= j+1 if j = length of base then f:= 1; offset := 0 else f:= 0; offset := j		

5.7 BIT FIELD INSTRUCTIONS

		SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
ext <i>i</i>	offset,	<i>base</i> , regaddr	dest, write.i	<i>length</i> disp	Extract Field	_	
	reg reg	regaddi	wine.i	rish	dest := FIELD(base, offset, length)		
extsii	base,	dest,	offset,l	_	Extract Field Short	_	
	regaddr	write.i	imm cons3,cons5		dest := FIELD(base, offset, length)		
ins <i>i</i>	offset,	src,	base,	length	Insert Field		_
	reg reg	read. <i>i</i>	regaddr	disp disp	FIELD(base, offset, length) := src		
inss <i>i</i>	src,	base,	offset,length imm cons3,con5		Insert Field Short	_	_
	read.i	i regaddr			FIELD(base, offset, length) := src		

5.8 STRING INSTRUCTIONS

	SYNTAX	OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
movsi	[b[,]][u w]	Move String	f	_
		<pre>string2 := string1 f:=1 if until/while condition is met; f:=0 otherwise</pre>		
movst	[b[,]][u w]	Move String with Translation	f	
		<pre>string2 := translate-string f:=1 if until/while condition is met; f:=0 otherwise</pre>		
cmpsi	[b[,]][u w]	Compare String	z	
_		f:=1 if until/while condition is met; f:=0 otherwise	n	
		z:=1 if string1=string2 and f=0; else z:=0 n:=1 if string2 <string1 and="" else="" f="0;" n:="0<br">l:=1 if string2<string1 and="" else="" f="0;" l:="0</td"><td>l f</td><td></td></string1></string1>	l f	
cmpst	[b[,]][u w]	Compare String with Translation	z	_
		f:=1 if until/while condition is met; f:=0 otherwise	n	
		z:=0 if translate-string*string2 and f=0; z:=0 otherwise n:=1 if translate-string>string2 and f=0; n:=0 otherwise l:=1 if translate-string>string2 and f=0; l:=0 otherwise	l f	
s k ps <i>i</i>	[b[,]][u w]	Skip String	f	_
		f:=1 if until/while condition is met; f:=0 otherwise		
skpst	[b[,]][u w]	Skip String with Translation	f	_
		f:=1 if until/while condition is met; f:=0 otherwise		

The flags $\,b,\,$ w, and $\,u$ are optional. The $\,u$ and $\,w$ flags are mutually exclusive. The comma is required whenever both $\,b$ and either $\,u$ or $\,w$ are specified.

5.9 BLOCK INSTRUCTIONS

SYNTAX				OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
movm <i>i</i>	block1, addr	block2, addr	<i>length</i> disp	Move Multiple	_	_
			cons4	block2 := block1		
cmpm <i>i</i>	block1,	block2,	length	Compare Multiple	z	
	addr	addr	disp		n	
			cons4	z:=1 if $block1=block2$; else $z:=0$	1	
				n:=1 if block1>block2; else n:=0		
				(signed integers)		
				l:=1 if block1>block2; else l:=0		
				(unsigned integers)		
				(

5.10 PACKED DECIMAL INSTRUCTIONS

SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
addp <i>i</i>	<i>src</i> , read. <i>i</i>	dest rmw.i	Add Packed Decimal dest := dest + src + c c := 1 on carry; c := 0 on no carry f := 0	c f	_
subp <i>i</i>	src, read.i	dest rmw.i	Subtract Packed Decimal dest := dest - src - c c := 1 on borrow; c := 0 on no borrow f := 0	c f	_

5.11 ARRAYINSTRUCTIONS

SYNTAX				OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
index <i>i</i>	accum, reg reg	length, read.i	index read.i	Calculate Array Index accum := (length + 1)*accum + index	_	_
check <i>i</i>	dest, reg reg	bounds, addr	src read.i	Check Array Index if bounds(upper) >= src >= bounds(lower) then, dest := src - bounds(lower) f := 0 else; dest := undefined f := 1	f	_

5.12 PROCESSOR CONTROL INSTRUCTIONS

	SYNTAX			OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN				
Direct and Conditional Jumping										
jump	dest			Jump		_				
	addr			$\mathtt{pc} \coloneqq \mathtt{ADDR}(dest)$						
b $\{cond\}$	disp	dest		Conditional Branch	_					
	short	disp label		if cond, then pc := pc + disp						
br	dest			Unconditional Branch	_	_				
	disp label			pc := pc + disp						
casei	index			Case Branch	_	_				
	read. i			pc := pc + index (signed index)						
acb <i>i</i>	inc,	index,	dest	Add, Compare, and Branch	_	_				
	quick quick	rmw. i	disp label	<pre>index := index + inc if index <> 0, then pc := pc + disp</pre>						
Subroutin	ne and Proce	edures								
jsr	<i>dest</i> addr			Jump to Subroutine		_				
	addr			PUSHD(return address) pc := ADDR(dest)						
bsr	dest			Branch to Subroutine	_					
	disp label			PUSHD(return address) pc := pc + disp						
ret	constant			Return from Subroutine	_	_				
	disp			POPD(pc)						
				sp := sp + constant						
cxp	<i>constant</i> disp			Call External Procedure	_	_				
	external			sp:= sp - 2 PUSHW(mod) PUSHD(return address) temp:= DOUBLEWORD (DOUBLEWORD(mod+4) +constant) mod := WORD(temp) sb := DOUBLEWORD(mod+0) pc := DOUBLEWORD(mod+8) + WORD(temp+2)						

PROCESSOR CONTROL INSTRUCTIONS (Cont)

	SYNTAX	OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
Subrou	tine and Procedures			
cxpd	<i>desc</i> addr	Call External Procedure with Descriptor sp := sp - 2 PUSHW(mod) PUSHD(return address) mod := WORD(descriptor) sb := DOUBLEWORD(mod+0) pc := DOUBLEWORD(mod+8) + WORD(descriptor+2)	_	
rxp	constant disp	Return from External Procedure POPD(pc) POPW(mod) sb := DOUBLEWORD(mod+0) sp := sp + constant + 2	_	_
Service	Return			
rett	constant disp	Return from Trap § if u=1, then TRAP(ILL) else POPD(pc) POPW(mod) POPW(psr) sb := DOUBLEWORD(mod) sp := sp + constant	all	ILL
reti		Return from Interrupt § if u=1, then TRAP(ILL) else, POPD(pc) POPW(mod) POPW(psr) sb := DOUBLEWORD(mod)	all	ILL

5.13 PROCESSOR SERVICE INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
Register/Stac	k Manipulation				
adjspi	src read.i		Adjust Stack Pointer	_	_
			sp := sp - src (src is signed) S bit specifies current sp		
$bicpsr\left\{b \ \ w\right\}$	src read. {b w}		Bit Clear in psr § if w length	all	ILL
	read. (b) w)		if bicpsrw and u=1, then TRAP(ILL) else, psr := psr AND NOT(src)		
$bispsr\left\{b \ \big \ w\right\}$	src read. {b w}		Bit Set in psr § if w length	all	ILL
			if bispsrw and u=1, then TRAP(ILL) else, psr := psr OR src		
save	reglist imm		Save General Purpose Registers		
	reglist		for each register rn in reglist, PUSHD(rn) in numerical order.		
restore	reglist imm		Restore General Purpose Registers		_
	reglist		for each register rn in reglist, POPD(rn) in reverse numerical order.		
enter	reglist, imm	constant disp	Enter New Context	_	_
	reglist,	disp	PUSHD(fp)		
			fp := sp		
			sp := sp - constant for each register rn in reglist,		
			PUSHD(rn) in numerical order.		
exit	<i>reglist</i> imm		Exit Context		
	reglist		for each register rn in reglist, POPD(rn) in reverse numerical order. sp := fp		
			POPD(fp)		
lpri	procreg, short	src read.i	Load Processor Register § if psr or intbase	all	ILL
	procreg		if u=1 and ((procreg=psr) or		
			(procreg=intbase)) then TRAP(ILL)		
			else procreg := src (S bit specifies current sp)		
			(all flags affected if <i>procreg</i> = psr or upsr)		

PROCESSOR SERVICE INSTRUCTIONS (Cont)

SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
Register/Stack Man	nipulation dest	Store Processor Register § if psr or intbase	_	ILL
short procreg	write.i	if u=1 and ((procreg=psr) or (procreg=intbase)) then TRAP(ILL) else dest := procreg (s bit specifies current sp)		222
setcfg <i>cfglist</i> short cfglist		Set Configuration Register § if u=1, then TRAP(ILL) else cfg := short	_	_
Exceptions				
bpt		Breakpoint Trap	_	BPT
		TRAP(BPT)		
svc		Supervisor Call Trap	_	SVC
		TRAP(SVC)		
flag		Flag Trap	_	FLG
		if f=1, then TRAP(FLG)		
Miscellaneous				
nop		No Operation	_	_
		pc := pc + 1		
wait		Wait for Interrupt	_	•
		pc := pc + 1 Wait until next interrupt		
dia		pc := pc cycle infinite loop until an interrupt occurs	_	_

MEMORY MANAGEMENT INSTRUCTIONS

5.14 MEMORY MANAGEMENT INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
lmr	mmureg, short	<i>src</i> read.d	Load MMU Register		UND* ILL**
	mmureg		mmureg := src		
smr	mmureg, short	<i>dest</i> write.d	Store MMU Register	_	UND* ILL**
	mmureg		dest := mmureg		
rdval	<i>src</i> addr		Validate Address for Reading §	f	UND* ILL**
	auu		if ADDRESS(src) in User mode may be read, f := 0 else f := 1		ABT***
wrval	dest addr		Validate Address for Writing §	f	UND* ILL**
			<pre>if ADDRESS(dest) in User mode may be written to, then f := 0 else f := 1</pre>		ABT***
movsu <i>i</i>	<i>src</i> , addr	<i>dest</i> addr	Move Value from Supervisor to User Space §		UND* ILL**
			<pre>dest := src (src is in supervisor space; dest in user space)</pre>		
movusi	<i>src</i> , addr	<i>dest</i> addr	Move Value from User to Supervisor Space §	_	UND* ILL**
			<pre>dest := src (src is in user space; dest in supervisor space)</pre>		

^{*} TRAP(UND) if m bit in cfg is 0.

^{**} TRAP(ILL) if u flag in psr is 1.

*** TRAP(ABT) if level 1 page table address invalid.

5.15 NS32081FLOATING-POINT INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
movf	src, read.f	dest write.f	Move Floating-Point		UND*
	,	•	dest := src		
movlf	src, read.l	dest write.f	Move Long Floating to Floating	_	UND* FPU
	,		dest.f := src.l	fsr:tt uf if	
movfl	src, read.f	dest write.l	Move Floating to Long Floating	_	UND* FPU
	• • • • • • • • • • • • • • • • • • • •		dest.l := src.f	fsr:tt	110
movif	$src, \\ read.i$	dest write.f	Move Integer to Floating-Point	 fsr:tt	UND* FPU
			dest.f := src.i	if	
roundfi	src, read.f	<i>dest</i> write. <i>i</i>	Round Floating-Point to Integer (round to even)	fsr:tt if	UND* FPU
			dest.i := src.f If overflow, then TRAP(FPU) (src.f rounded to nearest integer, or to nearest even integer if a tie)		
trunc <i>fi</i>	src, read.f	<i>dest</i> write. <i>i</i>	Truncate Floating-Point to Integer dest.i := src.f if overflow, then TRAP(FPU) (src.f rounded toward zero)	fer:tt if	UND* FPU
floorfi	src, read.f	dest write.i	Floor Floating-Point to Integer dest.i := src.f if overflow, then TRAP(FPU) (round src.f toward negative infinity)	fsr:tt if	UND* FPU
addf	src, read.f	dest rmw.f	Add Floating-Point dest := dest + src	fsr:tt uf if	UND* FPU
subf	src, read.f	dest rmw.f	Subtract Floating-Point dest := dest - src	fsr:tt uf if	UND* FPU

NS32081 FLOATING-POINT INSTRUCTIONS (Cont)

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
$\mathrm{mul} f$	src, read.f	dest rmw.f	Multiply Floating-Point	— fsr:tt	UND* FPU
	,	,	dest := dest * src	uf if	
divf	src, read.f	dest rmw.f	Divide Floating-Point	— fsr:tt	UND* FPU
	read.,	1111 w. j	if $src=0$, then TRAP(FPU) else $dest := dest / src$	uf if	110
cmpf	src1, read.f	src2 read.f	Compare Floating-Point	z n	UND* FPU
	reau.,	reau.j	z := 1 if src2=src1; else z := 0 n := 1 if src2< src1; else n := 0 l := 0 (always)	l fsr:tt	FIG
neg <i>f</i>	src, read.f	dest write.f	Negate Floating-Point	fsr:tt	UND* FPU
			<pre>dest := 0 - src (src sign bit complemented)</pre>		
absf	src, read.f	dest write.f	Absolute Value of Floating-Point	— fsr:tt	UND* FPU
		,	if src< 0, dest := 0 - src if src>=0,		
			dest := src		
lfsr	<i>src</i> read.d		Load fsr $sr := src$	fsr:all	UND*
sfsr	<i>dest</i> write.d		Store fsr	_	UND*
	write.a		dest := fsr		

^{*} TRAP(UND) if f bit in cfg is 0.

NS32181 and NS32381 FLOATING-POINT INSTRUCTIONS

5.16 NS32181and NS32381 FLOATING-POINT INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
movf	$src, \\ { m read}.f$	dest write.f	Move Floating-Point	_	UND*
	reau.	write.j	dest := src		
movlf	src, read.l	dest write.f	Move Long Floating to Floating	_	UND* FPU
	read.i	WIIVE	dest.f := src.l	fsr:tt uf if	PTO
movfl	src, read.f	<i>dest</i> write.l	Move Floating to Long Floating	_	UND* FPU
	1044.1	**1100.1	dest.l := $src.$ f	fsr:tt	110
movif	<i>src</i> , read <i>.i</i>	<i>dest</i> write. <i>f</i>	Move Integer to Floating-Point	 fsr:tt	UND* FPU
			dest.f := src.i	if	
round <i>fi</i>	src, read.f	dest write.i	Round Floating-Point to Integer (round to even)	fsr:tt if	UND* FPU
			<pre>dest.i := src.f If overflow, then TRAP(FPU) (src.f rounded to nearest integer, or to nearest even integer if a tie)</pre>		
truncfi	src, read.f	dest write.i	Truncate Floating-Point to Integer	— fsr:tt	UND* FPU
	roudy	***************************************	<pre>dest.i := src.f if overflow, then TRAP(FPU) (src.f rounded toward zero)</pre>	if	770
floorfi	$src, \\ ext{read}.f$	dest write.i	Floor Floating-Point to Integer	— fsr:tt	UND* FPU
	- ouuy		<pre>dest.i := src.f if overflow, then TRAP(FPU) (round src.f toward negative infinity)</pre>	if	710

NS32181 and NS32381 FLOATING-POINT INSTRUCTIONS(Cont)

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
$\operatorname{add} f$	src, read.f	dest rmw.f	Add Floating-Point	— fsr:tt	UND* FPU
	,	y	dest := dest + src	uf if	
subf	src, read.f	dest rmw.f	Subtract Floating-Point	— far:tt	UND* FPU
	. Suay	· ···· · · · · · · · · · · · · · · · ·	dest := dest - src	uf if	
mulf	$src, \\ {\sf read}.f$	dest rmw.f	Multiply Floating-Point	 fsr:tt	UND* FPU
			dest := dest * src	uf if	
$\mathrm{div} f$	$src, \\ read. f$	dest rmw.f	Divide Floating-Point	 fsr:tt	UND* FPU
	,	,	if $src=0$, then TRAP(FPU) else $dest := dest / src$	uf if	
cmpf	src1, read.f	src2 read.f	Compare Floating-Point	z n	UND* FPU
	,	,	z := 1 if src2=src1; else z := 0 n := 1 if src2 <src1; :="0<br" else="" n="">l := 0 (always)</src1;>	l fer:tt	
neg <i>f</i>	src, read.f	<i>dest</i> write. <i>f</i>	Negate Floating-Point	 fsr:tt	UND* FPU
	reau.,	wille.	<pre>dest := 0 - src (src sign bit complemented)</pre>	151,00	110
absf	src, read.f	<i>dest</i> write. <i>f</i>	Absolute Value of Floating-Point	— fsr:tt	UND* FPU
	,	ŕ	if $src<0$, dest := 0 - src		
			if $src>=0$, dest:=src		
lfsr	src read.d		Load fsr	— fsr:all	UND*
			fsr := src		
sfsr	<i>dest</i> write.d		Store far	_	UND*
			dest := fsr		

NS32181 and NS32381 FLOATING-POINT INSTRUCTIONS(Cont)

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
scalb <i>f</i>	src, read.f	dest rmw.f	dest := dest * 2src src = integer	— fsr:all	UND FPU
logbf	<i>scr</i> , read. <i>f</i>	dest write.f	$dest := ext{unbiased exponent of } src$	— fsr:all	UND FPU
$\mathrm{dot} f$	src, read.f	dest read.f	Scalar Product $f0 := (src * dest) + f0$	fsr:all	UND FPU
polyf	src, read.f	dest read. <i>f</i>	Polynomial Step $f0 := (f0 * src) + dest$	— fsr:all	UND FPU

^{*} TRAP(UND) if f bit in cfg is 0.

5.17 NS32580 FLOATING-POINT INSTRUCTIONS

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
movf	src,	dest	Move Floating-Point	_	UND*
	read.f	write.f	dest := src		
movlf	src, read.l	dest write.f	Move Long Floating to Floating	_	UND* FPU
	rouun	W.1100.1	dest.f := src.l	fsr:tt uf if	110
movfl	src, read.f	dest write.l	Move Floating to Long Floating	_	UND* FPU
	reau.i	write.i	dest.l := $src.$ f	fsr:tt	
movif	src, read.i	<i>dest</i> write. <i>f</i>	Move Integer to Floating-Point	 fsr:tt	UND* FPU
			dest.f := src.i	if	
round <i>fi</i>	<i>src</i> , read <i>.f</i>	<i>dest</i> write. <i>i</i>	Round Floating-Point to Integer (round to even)	fsr:tt if	UND* FPU
			<pre>dest.i := src.f If overflow, then TRAP(FPU) (src.f rounded to nearest integer, or to nearest even integer if a tie)</pre>		
trunc <i>fi</i>	<i>src</i> , read. <i>f</i>	dest write.i	Truncate Floating-Point to Integer	fsr:tt	UND* FPU
	reau.,		<pre>dest.i := src.f if overflow, then TRAP(FPU) (src.f rounded toward zero)</pre>		FIG
floorfi	src,	<i>dest</i> write. <i>i</i>	Floor Floating-Point to Integer		UND* FPU
	read.f	write.i	<pre>dest.i := src.f if overflow, then TRAP(FPU) (round src.f toward negative infinity)</pre>	fsr:tt if	FFU

NS32580 FLOATING-POINT INSTRUCTIONS (Cont)

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
$\operatorname{add}\!f$	src, read.f	dest rmw.f	Add Floating-Point	 fsr:tt	UND* FPU
	roudy	·,	dest := dest + src	uf if	
subf	<i>src</i> , read <i>.f</i>	dest rmw.f	Subtract Floating-Point	— fsr:tt	UND* FPU
			dest := dest - src	uf if	
mulf	src, read.f	dest rmw.f	Multiply Floating-Point	 fsr:tt	UND* FPU
			dest := dest * src	uf if	
divf	src, read. f	dest rmw.f	Divide Floating-Point	— fsr:tt	UND* FPU
			if src=0, then TRAP(FPU) else dest := dest / src	uf if	
cmpf	src1, read.f	src2 read. f	Compare Floating-Point	z n	UND* FPU
			z := 1 if src2=src1; else z := 0 n := 1 if src2 <src1; :="0<br" else="" n="">l := 0 (always)</src1;>	l fsr:tt	
neg <i>f</i>	src, read.f	dest write.f	Negate Floating-Point	— fsr:tt	UND* FPU
	·	·	<pre>dest := 0 - src (src sign bit complemented)</pre>		
absf	src, read.f	dest write.f	Absolute Value of Floating-Point	— fsr:tt	UND* FPU
			if src<0, dest := 0 - src if src>=0,		
			dest := src		
lfsr	<i>src</i> read.d		Load fsr	fsr:all	UND*
sfsr	dest		fsr := <i>src</i> Store fsr		UND*
	write.d		dest := fsr		
mac <i>f</i>	src, read.f	dest read.f	move(gen1*gen2)+l1/f1 to l1/f1 with two rounding errors		UND FPU
sqr t f	scr, read.f	<i>dest</i> write. <i>f</i>	move the square root if float to long Float		UND FPU
* 1712 \(\D \rangle \)	IIND) if f bit in	ofa is 0			

^{*} TRAP(UND) if f bit in cfg is 0.

5.18 NS32532 INSTRUCTIONS

The NS32532 supports the full Series 32000 instruction set, as described in Sections 5.2 through 5.13.

The NS32532 also contains four registers dedicated for debugging functions:

Debug Condition Register (dcr) Debug Status Register (dsr) Compare Address Register (car) Breakpoint Program Counter (bpc)

These registers are accessed using privileged forms of the lpr and spr instructions.

The NS32532 supports a privileged Cache Invalidation (cinv instruction and privileged access to the following dedicated registers using the lpr and spr instructions: cfg, usp(sp1), dcr, dsr, car, and bpc.

	SYNTAX		OPERATION	FLAGS AFFECTED	TRAPS TAKEN
cinv	[options],*	src gen read.d	Cache Invalidated	_	ILL
lpr <i>i</i>	procreg,** short	src gen read.i	Load Processor Register	_	ILL
spri	procreg,** short	dest gen write.i	Store Processor Register	_	ILL

options are specified by listing the letters a, i or d separated by comma(s) within brackets.

^{**} procreg can be the user stack pointer (usp or sp1), configuration register (cfg), and the debug registers in addition to the processor registers supported by the NS320xx and NS32332.

5.19 NS32CG16 and NS32CG160 INSTRUCTIONS

In addition to supporting the full Series 32000 instruction set (as described in Sections 5.2 through 5.13), the NS32CG16 and NS32CG160 support the following instructions:

SYNTAX	OPERATIONS	FLAGS AFFECTED	TRAPS
bb{ and or xor stod} [da ia [,]] [s -s]	Bit-aligned block transfer	_	
bbfor	Bit-aligned block transfer		_
bitwit	Bit-aligned word transfer	_	_
extblt	External bit-aligned block transfer	_	_
movmpi	Move multiple pattern	_	_
tbits { 0 1 }	Test bit string	f,l,n,z	_
sbits	Set bit string	f	_
sbitps	Set bit string perpendicular	_	_

Note that the following instructions are not available in the NS32CG16 and NS32CG160:

Instruction

	•
lmr	Load MMU register
smr	Store MMU register
rdval	Validate address for reading
wrval	Validate address for writing
movsu <i>i</i>	Move value from supervisor to user space
$\mathrm{movus}i$	Move value from user to supervisor space

Purpose

For the NS32CG160, the setcfg instruction accepts the de (direct exception) configuration operand.

5.20 NS32GX32 and NS32GX320 INSTRUCTIONS

The NS32GX32 and the NS32GX320 support the same instruction set as the NS32532 (Section 5.18), except for the following instructions which are not supported:

Instruction	Purpose
lmr	Load MMU register
smr	Store MMU register
rdval	Validate address for reading
wrval	Validate address for writing
movsui	Move value from supervisor to user space
${f movus}i$	Move value from user to supervisor space

In addition, the m configuration option of the setcfg instruction is not supported.

For the NS32GX320, four new DSP instructions are supported:

	SYNTAX		OPERATIONS	FLAGS AFFECTED	TRAPS TAKEN
MULWD	src, read.w	$dest \ { m rmw} D$	Multiply word to double	_	_
MACTD	$src1, \\ read. D$	src2 read.D	Multiply and accumulate twice double if $src1 = (A2,A1)$, $src2 = (B2,B1)$ then $R0 := R0 + A1*B1 + A2*B2$	_	OVF
CMACD	$src1, \\ read.D$	src2 read.D	Complex multiply double and accumulate twice if $src1 = (A2,A1)$, $src2 = (B2,B1)$ then $R0 := R0 + A1*B1 - A2*B2$ and $R1 := R1 + A1*B2 + A2*B1$	_	OVF
CMULD	src1, read.D	src2 read.D	Complex multiply double if $src1 = (A2,A1)$, $src2 = (B2,B1)$ then $R0 := A1*B1 - A2*B2$ and $R1 := A1*B2 + A2*B1$	_	OVF

5.21 NS32FX16 INSTRUCTIONS

In addition to supporting the full Series 32000 instruction set (as described in Sections 5.2 through 5.14), the NS32FX16 supports the following instructions:

SYNTAX	OPERATIONS	FLAGS AFFECTED	TRAPS
bb{ and or xor stod} [da ia [,]] [s -s]	Bit-aligned block transfer	_	_
bbfor	Bit-aligned block transfer	_	_
bitwit	Bit-aligned word transfer		
extblt	External bit-aligned block transfer	_	_
movmpi	Move multiple pattern	_	_
tbits { 0 1 }	Test bit string	f,l,n,z	_
sbits	Set bit string	f	_
sbitps	Set bit string perpendicular	_	_

Note that the following instructions are not available in the NS32FX16:

Instruction	Purpose		
lmr	Load MMU register		
smr	Store MMU register		
rdval	Validate address for reading		
wrval	Validate address for writing		
movsu <i>i</i>	Move value from supervisor to user space		
${f movus} i$	Move value from user to supervisor space		

GNX ASSEMBLER DIRECTIVES

6.1 INTRODUCTION

Directives are commands to the assembler which allow the programmer to control the assembler in its generation of object code and production of listings.

The GNX Assembler directives are divided into functional groups as follows:

Directive	Function	Section
Symbol Creation	Assigns a name, type, and value to a symbol.	Section 6.2
Data Generation	Initializes a block of memory with constant values.	Section 6.3
Storage Allocation	Reserves a block of memory for data storage.	Section 6.4
Listing Control	Controls format of program listings.	Section 6.5
Linkage Control	Exports and imports data and procedures.	Section 6.6
Segment Control	Defines physical or logical image segments.	Section 6.7
Module Table	Manages the task of building a module table.	Section 6.8
Filename	Names the source file.	Section 6.9
Symbol Table	Specifies symbol table entry data.	Section 6.10
Line Number Table	Specifies a line number table entry.	Section 6.11
Macro Support	Provides macro and conditional assembly support.	Section 6.12
Procedure Support	Provides an easy method of writing assembly procedures.	Section 6.13

The remainder of this chapter will discuss these directives in detail.

6.2 SYMBOL CREATION DIRECTIVE

The symbol creation directive causes the assembler to compute the value of an expression and assign that value to a symbol name.

> **Directive Function**

> > creates a symbol name .set

6.2.1 .set

Syntax:

.set symbol, expression

where:

.set

is the directive name.

symbol

is a symbol name. It consists of a series of characters. The characters may be letters, numbers, period (.), or underscore (). The first character must not be a

number.

expression

is a constant or an expression. It may evaluate to any

type.

Description:

The .set directive causes the GNX Assembler to compute the value of the expression and assign this value to the symbol name. The expression may evaluate to any type except undefined, refer to Section 2.7. The expression may not be of type external (undefined), not forward reference.

For each symbol defined with the .set directive, the GNX Assembler enters the symbol name and value in its internal symbol table. The symbol may then be used in expressions in subsequent portions of the assembly.

Example:

.set SYMBA,

.set SYMBB. LABELA + SYMBA

.set SYMBC,

Line 1 defines the symbol SYMBA and assigns it the value 5.

Line 2 defines the symbol SYMBB and assigns it the value of LABELA+SYMBA. If SYMBA has the value 5, then SYMBB is assigned the value of LABELA+5 and the type of LABELA.

Line 3 defines the symbol SYMBC and assigns it the value of the 'A' expression. Note that only single character constants may be used in expressions (refer to Section 2.7.2).

6.3 DATA GENERATION DIRECTIVES

The data generation directives place constant data in the instruction stream during assembly-time. These are the following data generation directives:

Directive	Function
.ascii	assigns ASCII encoded textual data
.byte	assigns byte-long data
.word	assigns word-long data
.double	assigns double word-long data
.float	assigns single-precision floating-point number
.long	assigns double-precision floating-point number
.field	assigns bit field
.xpd	assigns external procedure descriptor
.xdd	assigns external data descriptor

Each of the above directives places one or more bytes of data in the object code of the program currently assembling. Data generation directives may be specified only in Program Code segments where data is written to the object file (*i.e.*, when the location counter is in the text segment, the data segment, the static segment, or the link segment).

All the numeric data generation directives, *i.e.*, all directives listed except .field, .ascii, .xpd, and .xdd, have the following form:

```
[label]directive({[[repetition-factor]]expression | string}),,,
```

The *directive* stores the *expression* value in the instruction stream. If a *repetition-factor* is specified, the *directive* stores the *expression* value in consecutive locations as specified by the *repetition-factor*. A *label* is optional.

The .byte, .word, .double, .float, and .long directives may specify one or more expressions. Multiple expressions must be separated by commas. Each expression is evaluated and stored in the number of bytes specified by the directive. An expression must evaluate to an absolute value within the range specified by the directive, but expressions for the .long and .float directives should evaluate to a long value. (The assembler evaluates all floating-point expressions as long floating-point numbers. If necessary, the result is then converted to a single-precision floating-point value.) If no expression is specified, the GNX Assembler issues an error message and terminates code generation.

A *repetition-factor* may be any expression which evaluates to a positive absolute value. The *repetition-factor* expression may use symbolic values, but no forward symbol references are allowed.

Packed Decimal numbers may be generated using the .byte, .word, and .double directives. A Packed Decimal is created by specifying it as a hexadecimal constant. For example, .word H'1289 creates the Packed Decimal number 1289.

The .byte, .word, and .double directives may be used for both signed and unsigned numbers.

6.3.1 .ascii

Syntax:

[label] .ascii "string"

where:

label

is an optional label.

.ascii

is the directive name.

"string"

specifies a string constant. The string must not contain an embedded new-line. The user may use the escape sequence "\n" to enter a new-line into a string

constant.

Description:

The .ascii directive generates textual data. The GNX Assembler places the text in the instruction stream at the current address specified by the location counter. The assembler stores the ASCII value of each character in the string in one byte, placing the first character of the string at the lowest byte address and the last character of the string at the highest byte address. Unprintable ASCII characters may be included via the escapes defined in Section 2.4.3. No special string terminator is implied or inserted by the assembler.

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T			.aata		
2	D00000000	4572726f	.ascii	"Error:	unknown command.\n"
		723a2075			
		6e6b6e6f			
		776e2063			
		6 f 6d6d61			
		6e642e0a			
3	D00000018	55736167	.ascii	"Usage:	list [-tdrx]"
		653a206c			
		69737420			
		5b2d7464			
		72785d20			

Line 2 places the ASCII character string "Error: unknown command." followed by a new-line character (\n) in consecutive bytes beginning at address 0 of the data segment.

Line 3 places the character string "Usage: list [-tdrx]" in consecutive bytes starting at address 00000018 in the data segment.

6.3.2 .byte

Syntax: [label].byte({[[repetition-factor]]expression | string}),,,

where: lahel is an optional label.

> is the directive name. .byte

[repetition-factor]

(optional) specifies the number of occurrences of the specified data byte. It must be an expression which evaluates to a positive absolute value. If the repetition-factor is specified, it must be enclosed in "[]" brackets.

expression specifies the data byte value. This value must be in

the range of -128 to 255.

string specifies a string constant. The assembler issues a

> warning if the string contains an embedded new-line. Therefore, it is preferable to use the "\n" escape

sequence.

Description: The .byte directive generates one or more byte constants. The GNX

Assembler places the constants in the instruction stream at the current address specified by the location counter. If multiple constants are specified (e.g., repetition-factor is greater than one or more than one expression is given), the constants are stored in consecutive bytes begin-

ning at the current address.

If a string is specified, the assembler places the string, starting with the first character in the string, in one or more bytes beginning at the current address. The assembler stores the ASCII value of each character in the string in one byte. Character constants appearing as terms in the expression are converted to integers (see Section 2.7.2, Rule 5).

Example:

```
T00000000
                        .byte 129
1
              81
   T00000001 03030303 .byte [5] 3
              03
   T00000006 414243
                        .byte "ABC"
                        .byte 3, "AB"
   T00000009 034142
                        .byte 'f'/3, 'f'/'3'
5
   T0000000c 2202
   T0000000e 81
                        .byte -127
```

Line 1 places 81 in a byte at address 000000 of the text segment.

Line 2 places 3 (repeated 5 times) in five consecutive bytes starting at address 000001 in the text segment.

Line 3 places the ASCII values of "ABC" in three consecutive bytes starting at address 000006 in the text segment.

Line 4 places 3 in the byte at address 000009 in the text segment followed by the ASCII values of "AB" in two consecutive bytes.

Line 5 places the value of the expressions f/3 and f'/3 in consecutive bytes beginning at address 00000C in the text segment. The value of f'/3 (0x22) is first, followed by the value of f'/3' (0x02).

Line 6 places 81 in a byte at address 00000E in the text segment.

6.3.3 .word

Syntax:

[label] .word ({[[repetition-factor]] expression | string}),,,

where:

label

is an optional label.

.word

is the directive name.

[repetition-factor]

(optional) specifies the number of occurrences of the specified data word. It must be an expression which evaluates to a positive absolute value. If the repetition-factor is specified, it must be enclosed in

"[]" brackets.

expression

specifies the data word value. It must evaluate to an absolute value within the range of -32768 to 65535.

string

specifies a string constant. If the string is not composed of an even multiple of two characters, it is null padded by the appropriate amount.

Description:

The .word directive generates one or more word length constants. The assembler places the constants in the instruction stream at the current address specified by the location counter. The assembler stores the least-significant byte at the lower address and the most-significant byte at the higher address.

If multiple constants are specified (e.g., repetition-factor is greater than one, or more than one expression is given), the constants are stored in consecutive words beginning at the current address.

When a string is specified as an operand of the .word directive, it is output as a byte string beginning at the lowest address and padded at the high address to an even multiple of two bytes if necessary.

Example:

```
1 T0000000 0180 .word 32769
2 T0000002 34123412 .word [2] 0x1234
3 T0000006 41004142 .word 'A', "AB"
4 T000000a 0100
                     .word 0x41424344/0x41424344
5 T000000c 0180
                     .word -32767
```

Line 1 places the constant 32769 in a word at the address 000000 in the text segment.

Line 2 places the constant 0x1234 (repeated twice) in two consecutive words.

Line 3 places the word values of the character constant 'A' and the string "AB" (evaluated as integers) in two consecutive words.

Line 4 places the value of the expression 0x41424344/0x41424344 in a word at the address 00000A in the text segment.

Line 5 places 0x8001 (-32767) in a word at address 00000C in the text segment.

6.3.4 .double

Syntax:

[label] .double ({[[repetition-factor]] expression | string}),,,

where:

label

is an optional label.

.double

is the directive name.

[repetition-factor]

(optional) specifies the number of occurrences of the specified double-word. It must be an expression which evaluates to a positive absolute value. If the repetition-factor is specified, it must be enclosed in "[]"

brackets.

expression

specifies the double-word value. It must evaluate to an absolute value within the range of -2^{31} to $2^{31}-1$.

string

specifies a string constant. If the string is not composed of an even multiple of four characters, it is null padded by the appropriate amount.

Description:

The .double directive generates one or more double-word constants. The assembler places the constants in the instruction stream at the current address specified by the location counter. The assembler places the bytes in ascending order, beginning with the least-significant byte at the lowest address.

If multiple constants are specified (e.g., repetition-factor is greater than one, or more than one expression is given), the constants are stored in consecutive double-words, beginning at the current address. When a string is specified as an operand of the .double directive, it is output as a byte string, beginning at the lowest address and padded at the high address to an even multiple of four bytes if necessary.

Example:	1	T0000000	ffff0000	.double	0x0000FFFF,	0xFFFF0000
			0000ffff			
	2	T0000008	03000000	.double	[2] 3	
			03000000			
	3	T0000010	41424300	.double	''ABC''	
	4	T0000014	01000000	.double	0x41424344/	0×41424344
	5	T0000018	70ffffff	.double	-144, 257	
			01010000			

Line 1 places the constants 0x0000ffff and 0xffff0000 in two consecutive double-words.

Line 2 places the constant 3 (repeated twice) in two consecutive doublewords.

Line 3 places the value of the string "ABC" in a double-word.

Line 4 places the value of the expression 0x41424344/0x41424344 in a double-word at address 00000014 in the text segment.

Line 5 places the value of the signed constants -144 and 257 in consecutive double-words.

6.3.5 .float

Syntax:

[label] .float ([[repetition-factor]] expression),,,

where:

label

is an optional label.

.float

is the directive name.

[repetition-factor]

(optional) specifies the number of occurrences of the specified floating-point number. It must be an expression which evaluates to a positive absolute value. If the repetition-factor is specified, it must be enclosed in

brackets.

expression

specifies a single-precision floating-point constant (refer to Section 2.4.2). Strings are not permitted.

Description:

The .float directive generates one or more single-precision floatingpoint constants. The assembler places the constants in the instruction stream at the current address specified by the location counter. The assembler stores a single-precision floating-point constant in a doubleword (32 bits).

If multiple constants are specified (e.g., repetition-factor is greater than one, or more than one expression is given), the constants are stored in consecutive double-words beginning at the current address.

Example:

```
T0000000
          4cdc3654
                    .float 3.14152E+12
T0000004
          1ff47c3f .float [2]0.9881
          1ff47c3f
```

Line 1 places the floating-point constant 3.14152E+12 in a double-word at the current address.

Line 2 places the floating-point constant 0.9881 (repeated twice) into two consecutive double-words.

6.3.6 .long

Syntax:

[label] .long([[repetition-factor]]expression),,,

where:

label

is an optional label.

.long

is the directive name.

[repetition-factor]

(optional) specifies the number of occurrences of the specified floating-point number. It must be an expression which evaluates to a positive absolute value. If the *repetition-factor* is specified, it must be enclosed in "[]" brackets.

expression

specifies a double-precision floating-point constant (refer to Section 2.4.2). Strings are not permitted.

Description:

The .long directive generates one, or more double-precision floating-point constants. The assembler places the constants in the instruction stream at the current address specified by the location counter. The assembler stores a double-precision floating-point constant in a quadword (64 bits).

If multiple constants are specified (e.g., repetition-factor is greater than one, or more than one expression is given), the constants are stored in consecutive quad-words beginning at the current address.

Example:

```
1 T0000000 00002078 .long 3.14152E+12
89db8642
2 T0000008 3695efe2 .long 6.12E-23, [3] 0.9881
le7f523b
e6ae25e4
839eef3f
e6ae25e4
839eef3f
e6ae25e4
839eef3f
```

Line 1 places the floating-point constant 3.14152E+12 in a quad-word at the current address.

Line 2 places the floating-point constants 6.12E-23 and 0.9881 (repeated three times) in four consecutive quad-words.

6.3.7 .field

Syntax: [label] .field([subfield-size]subfield-value),,,

where: label is an optional label.

.field is the directive name.

[subfield-size] (required) specifies the length in bits of the field being

generated. It may be any expression which evaluates to a positive absolute value. No forward referencing of symbols is permitted. The *subfield-size* must be

enclosed in "[]" brackets.

subfield-value (required) specifies a field value. It may be any

expression which evaluates to a non-negative absolute value. It must be within the range specified by the field size (e.g., 0 to 15 for a 4-bit field, 0 to 31 for a 5-

bit field).

Description:

The .field directive generates one or more bit fields. The assembler places the field(s) in the instruction stream at the current address specified by the location counter. The directive provides no default values; thus, both *subfield-size* and *subfield-value* must be specified.

If the directive specifies more than one *subfield-size/subfield-value* pair, the values are placed in contiguous fields. If a field or a combination of fields do not extend to a byte boundary, the assembler zero-fills the remaining bits.

If multiple constants are specified, the *subfield-size/subfield-value* pairs must be separated by commas. See lines 2 and 3 in the following example.

Example: 1 T0000000 08 .field [4] 8

2 T0000001 3f .field [4] 15, [4] 3

3 T0000002 2143 .field [4] 1, [4] 2, [4] 3, [4] 4

Line 1 places 8 in a 4-bit field at address 0000000 in the text segment and zero-fills the four high-order bits.

Line 2 places 15 and 3 in two consecutive 4-bit fields at address 0000001 in the text segment.

Line 3 places 1, 2, 3, and 4 in four consecutive 4-bit fields. The fields occupy two bytes beginning at address 0000002 in the text segment.

6.3.8 .xpd

Syntax: [label] .xpd expression

where: label is an optional label.

.xpd is the directive name.

expression specifies the entry point of a function using the cxp

rxp calling discipline.

Description:

The .xpd directive generates an external procedure descriptor for the specified entry point. A procedure descriptor is a double-word of data. The low-order two bytes specify the module table entry for the module that contains the function. The high-order two bytes contain the offset of the function entry point from the module's program code base. The module entry and offset values are updated by the linker at link time.

The assembler generates the procedure descriptor at the current location. Normally, the current location will be in the link table (link segment). However, the .xpd directive may also be used to put a procedure descriptor for a function at a known memory location for use with the cxpd instruction.

The definition of an xpd symbol through the .xpd directive should precede any reference to it.

Example:

```
1 .link
2 L0000000 00000000 .xpd _main
3 L0000004 00000000 .xpd _fun1
4 L0000008 00000000 .xpd _fun2
```

Line 2 generates a procedure descriptor link table entry for the function _main at address 00000000 in the link segment.

Line 3 generates a procedure descriptor for the function _fun1 at address 00000004 in the link segment.

Line 4 generates a procedure descriptor for the function _fun2 at address 00000008 in the link segment.

Both sample functions are external to the assembly. The actual module table entry and code offset will be filled in by the linker.

6.3.9 .xdd

Syntax:

.xdd expression

where:

.xdd

is the directive name.

expression

specifies a double-word value.

Description:

The .xdd directive or external data descriptor, defines link table entries for external data variables.

If expression is specified by a single symbol of non-absolute type, references to this symbol can be addressed via the external addressing mode. If the external data variable is defined by:

offset:

bbx.

value

the syntax for addressing the symbol value via the external addressing mode is either by value, which is equivalent to offset (ext), or by disp (value) and value+disp, which is equivalent to disp(offset(ext)), where disp is an expression of absolute type.

If expression is specified by a combination of symbols (e.g., sym+var), or a combination of symbols and constants (e.g., value+10), references to these symbols (i.e., sym, var, value) will be addressed via their appropriate default addressing mode, (i.e., absolute addressing mode if symbol in link segment).

The assembler generates the data descriptor at the current location. Normally, the current location will be in the link table, that is, the link segment. However, the .xdd directive may also be used to put a data descriptor at any other segment.

The definition of an xdd symbol through the .xdd directive should precede any reference to it.

Example: 2 D0000000 00000000 fool:

.blkd 3 4 .link 5 L0000000 00000000 ext_var: .xdd foo1

Line 5 generates an external data variable link table entry for the variable foo at address 00000000 in the link segment.

.data

6.4 STORAGE ALLOCATION DIRECTIVES

There are six storage allocation directives:

Directive	Function		
.blkb	allocates byte storage		
.blkw	allocates word storage		
.blkd	allocates double-word storage		
.blkf	allocates double-word(s) for floating-point storage		
.blkl	allocates quad-word(s)for long floating-point storage		
.space	allocates a block of storage		

All storage allocation directives except . space have the following form:

[label] directive [expression]

The optional expression specifies the number of bytes, words, double-words, or quadwords to be allocated. It must evaluate to a non-negative absolute value. If the expression evaluates to zero, no storage is allocated. If no expression is specified, the default value is one. The expression may use symbolic values, but no forward symbol references are allowed.

When storage allocation directives occur in the text segment, the allocated bytes, words, double-words, or quad-words allocated are initialized to the nop instruction and appear in the program listing as generated code. When storage allocation directives occur in the data, static, or link segments, the allocated bytes, words, double-words, or quad-words are initialized to zero and appear in the program listing as generated code. For all other segment types, the allocated space is uninitialized.

Sections 6.4.1 through 6.4.6 define the syntax of these directives.

6.4.1 .blkb

Syntax: [label].blkb[expression]

where: label is an optional label.

.blkb is the directive name.

expression specifies the number of bytes to be allocated. It must

be an unsigned integer constant or an expression which evaluates to a non-negative absolute value. The

default value is one.

Description: The .blkb directive allocates zero or more consecutive bytes of memory

for data storage. The bytes begin at the current location counter

address.

Example: 1 .static

2 S00000000 00 .blkb 1 3 S00000001 00000000 AA: .blkb 15

00000000

000000

4 S00000010 00000000 .blkb (.-AA)/3

00

5 S00000015 00 .blkb

Line 2 allocates a single byte for data storage. The byte is located at address 00000000 in the static segment.

Line 3 allocates 15 consecutive bytes for data storage, beginning at address 00000001 in the static segment. The label AA is assigned the address of the first byte.

Line 4 allocates the number of bytes specified by the "(.-AA)/3" expression. The expression evaluates to 5, i.e., (16 (static relative) - 1 (static relative) = 15 (absolute), 15/3 = 5. Therefore, 5 bytes are allocated, beginning at address 00000010 static segment relative.

Line 5 allocates a single byte for storage.

6.4.2 .blkw

Syntax: [label].blkw [expression]

where: label is an optional label.

.blkw is the directive name.

expression specifies the number of words to be allocated. It must

be an unsigned integer constant or an expression which evaluates to a non-negative absolute value.

Description: The .blkw directive allocates zero or more consecutive words of memory for data storage. The words begin at the current location

counter address.

Example: 1 .text

2 T00000000 a2a2 .blkw 1

3 T00000002 a2a2a2a2 AA: .blkw 15

a2a2a2a**2**

a2a2a2a2

a2a2a2a2

a2a2a2a2

a2a2a2a2

a2a2a2a2

a2a2

4 T00000020 a2a2a2a2 .blkw (.-AA)/3

a2a2a2a2

a2a2a2a2

a2a2a2a2

a2a2a2a2

T00000034 a2a2 .blkw

Line 2 allocates one word for data storage at address 00000000 in the text segment.

Line 3 allocates 15 consecutive words for data storage, beginning at address 00000002 in the text segment. The label AA is assigned the address of the first word.

Line 4 allocates the number of words specified by the "(.-AA)/3" expression. The expression evaluates to 10, i.e., (32 (text relative) - 2 (text segment relative) = 30 (absolute), 30/3 = 10. Therefore, 10 words are allocated, beginning at address 00000020 in the text segment.

Line 5 allocates one word for storage.

6.4.3 .blkd

Syntax:

[label].blkd[expression]

where:

label

is an optional label.

.blkd

is the directive name.

expression

specifies the number of double-words to be allocated. It must be an unsigned integer constant or an expression which evaluates to a non-negative absolute value.

Description:

The .blkd directive allocates zero or more consecutive double-words of memory for data storage. The double-words begin at the current location counter address.

Example:

```
1
                 .text
2
     text start:
3
                 .dsect lo_text, text_start
4
                  .blkd 1
5
                  .blkd 15
     AA:
6
                  .blkd (.-AA)/3
7
                  .blkd
```

Line 4 allocates one double-word for data storage, overlaid onto address 000000 of the text segment.

Line 5 allocates 15 consecutive double-words for data storage, overlaid onto address 000004 of the text segment. The label AA is assigned the address of the first double-word.

Line 6 allocates the number of double-words specified by the "(.-AA)/3" expression. The expression evaluates to 20, i.e., (64 (text relative) - 4 (text relative)) = 60 (absolute), 60/3 = 20. Therefore, 20 double-words are allocated and overlaid onto address 000040 of the text segment.

Line 7 allocates a single double-word for storage.

6.4.4 .blkf

[label].blkf [expression] Syntax:

where: labelis an optional label.

> .blkf is the directive name.

specifies the number of double-words to be allocated. expression

> It must be an unsigned integer constant or an expression which evaluates to a non-negative absolute value.

The .blkf directive allocates zero or more consecutive double-words of Description:

memory for storage of single-precision floating-point (32-bit) numbers.

The double-words begin at the current location counter address.

Example: 1 .udata

.blkf 1 2 3 .blkf 15 AA: 4 .blkf

Line 2 allocates one double-word for data storage at the address of the bss segment.

Line 3 allocates 15 consecutive double-words for data storage, beginning at the current address of the bss segment. The label AA is assigned the address of the first double-word.

Line 4 allocates one double-word for storage at the address of the bss segment.

6.4.5 .blkl

[label].blk1 [expression] Syntax:

where: labelis an optional label.

> .blkl is the directive name.

specifies the number of quad-words to be allocated. It expression

> must be an unsigned integer constant or an expression which evaluates to a non-negative absolute value.

Description: The .blkl directive allocates zero or more consecutive quad-words of

memory for storage of double-precision floating-point (64-bit) numbers.

The quad-words begin at the current location counter address.

Example: 1 .udata

2 .blkl 1 3 .blkl 15 AA: 4 .blkl

Line 2 allocates one quad-word for data storage at address 00000000 of the bss segment.

Line 3 allocates 15 consecutive quad-words for data storage, beginning at address 00000008 of the bss segment. The label AA is assigned the address of the first quad-word.

Line 4 allocates a single quad-word for storage at 00000128 of the bss segment.

6.4.6 .space

[label] .space expression Syntax:

where: labelis an optional label.

> is the directive name. .space

expression specifies the number of bytes to be allocated. It must

be an unsigned integer constant or an expression

which evaluates to a non-negative absolute value.

Description: The .space directive allocates a consecutive block of memory for data

storage. The block begins at the current location counter address. The

size in bytes of the storage block is specified by *expression*.

Example: 1 .static

> 2 .space 1 S00000000 00 S00000001 00000000 AA: .space 15

> > 00000000 00000000 000000

S0000010 00000000 .space (.-AA)/3

0.0

00 S00000015 .space 1

Line 2 allocates one byte for data storage. The byte is located at address 00000000 in the static segment.

Line 3 allocates 15 consecutive bytes for data storage, beginning at address 00000001 in the static segment. The label AA is assigned the address of the first byte.

Line 4 allocates the number of bytes specified by the "(.-AA)/3" expression. The expression evaluates to 5, *i.e.*, (16 (static relative) - 1 (static relative))relative) = 15 (absolute), 15/3 = 5. Therefore, five bytes are allocated. beginning at address 00000010 static segment relative.

Line 5 allocates a single byte for storage.

6.5 LISTING CONTROL DIRECTIVES

The listing control directives control the format of the GNX Assembler's program listing:

Directive	Function
.title	prints title at top of program listing
.subtitle	prints subtitle at top of program listing
.nolist	suppresses the printing of lines of source program to listing
.list	restores printing of lines of source program to listing
.eject	continues listing at top of next page
.width	sets width of listing page

Sections 6.5.1 through 6.5.6 describe the listing control directives in detail.

6.5.1 .title

Syntax:

[label] .title "string"

where:

label

is an optional label.

.title

is the directive name.

string

specifies the character string to be printed at the top of the listing page. The string (required) may consist of any combination of up to 126 letters, numbers, and text characters and must be enclosed in double-quotes.

Description:

The .title directive causes the assembler to print the specified *string* at the top of each new page of the program listing.

The first .title directive affects the current listing page as well as all previous pages.

If a program contains more than one .title directive, the last .title directive to be specified before the page break affects subsequent pages. If a page other than the first page has no .title directive, it receives the title of the previous page.

If a program contains no .title directive, no title is printed.

No title is printed on the cross-reference page.

Example:

.title "John's Program"

The preceding example causes the string "John's Program" to be printed at the top of the current page of the program listing. If it is the only .title directive in the program, all pages will have the same title.

6.5.2 .subtitle

Syntax: [label] .subtitle "string"

where: labelis an optional label.

> is the directive name. .subtitle

specifies the character string to be printed at the top of string

> listing page. The string (required) may consist of any combination of up to 126 letters, numbers, and text characters and must be enclosed in double-quotes.

Description: The .subtitle directive causes the assembler to print the specified string at the top of each new page of the program listing. If a .title directive is also specified, the subtitle string appears below the title

string.

The first .subtitle directive affects the current listing page as well as all previous pages.

If a program contains more than one .subtitle directive, the last . subtitle directive to be specified before page break affects the subsequent page. If a page has no .subtitle directive, it receives the subtitle of the previous page.

If a program contains no .subtitle directive, no subtitle is printed.

No subtitle is printed on the cross-reference listing page.

Example: .subtitle "Written 7/7/81"

> The preceding example causes the string "Written 7/7/81" to be printed at the top of the current page of the program listing. If it is the only . subtitle directive in the program, all pages will have the same subtitle.

6.5.3 .nolist

[label] .nolist [qualifier_list] Syntax:

labelwhere: is an optional label.

> is the directive name. .nolist

macro listing qualifiers to be set off. Can be any comqualifier_list

> bination of the qualifiers: mac source, mac_expansions and mac_directives,

described in Section 8.14.

Description: The .nolist directive suppresses the printing of source program lines.

All lines following the .nolist directive are assembled but are not

printed to the program listing.

The .nolist directive does not affect the printing of error messages.

The .nolist directive may be disabled by specifying a .list direc-

tive (see Section 6.5.4).

Example: .nolist

> movd r0, r1 addb TEMP, r1 subb r1, r0

.list

In the preceding example, the .nolist directive suppresses printing of the statement containing the .nolist directive and the following three lines of source. Printing is restored by the .list directive. Only the statement containing the .list directive is printed.

6.5.4 .list

Syntax: [label] .list [qualifier_list]

where: label is an optional label.

.list is the directive name.

qualifier_list macro listing qualifiers to be set on. Can be any com-

bination of the qualifiers: mac_source, mac_expansions and mac_directives, as

described in Section 8.14.

 $\label{eq:discrete_prop} \textbf{Description:} \quad \textbf{The .list directive restores the printing of lines of the source program}$

after suppression by a .nolist directive. All lines following the .list directive are printed to the program listing. The statement con-

taining the .list directive is also printed to the program listing.

Example: .nolist

movb r0, r1 addb TEMP, r1 subb r1, r0

.list

NXT: cmpb r1,r0

In this example, the .list directive restores printing after the previous .nolist directive. Only the statement labelled NXT: and the .list statements are printed.

6.5.5 .eject

Syntax:

[label] .eject

where:

label

is an optional label.

.eject

is the directive name.

Description:

The .eject directive causes the program listing to continue at the top of the next page. The statement containing the .eject directive is printed in the program listing.

Example:

.eject

This example causes the program listing to continue at the top of the next page. The statement containing the .eject directive is printed.

6.5.6 .width

Syntax: [label] .width expression

where: labelis an optional label.

> .width is the directive name.

expression specifies page width in characters. It must be an

> unsigned integer constant or expression which evaluates to an absolute value within the range of 80 to 132.

Description: The .width directive sets the width (in characters) of the program list-

ing lines which follow the directive. (The first .width directive effects all preceding pages as well.) More than one .width directive is allowed, with each directive effective until the next or until the end of the file. If there is no .width directive, the width is 132 characters by default. The new-line character is included in the maximum width.

If the expression value is outside the specified range, an error message is

generated.

Example: .width MYPAGEWIDTH - 12

> The preceding example sets the page width to the value of the expression MYPAGEWIDTH-12. The expression must evaluate to a number

within the range 80 to 132.

6.6 LINKAGE CONTROL DIRECTIVES

The linkage control directives provide support for modular programming by allowing symbols and procedures to be exported from, or imported to, separately assembled modules. These directives are:

Directive

Function

.globl	declares external data symbols
.comm	declares external undefined data symbols

The .globl directive declares a symbol external, either for import or export, but does not define the symbol. The .comm directive is similar, except an associated size is specified. At link time, symbols declared with .comm are resolved and allocated in the bss segment.

Sections 6.6.1 through 6.6.2 describe the linkage control directives.

6.6.1 .glob1

Syntax: .glob1 symbol ,,,

where: .globl is the directive name.

symbol is the name of a symbol. If more than one symbol is

specified, the symbols must be separated by commas.

Description:

The .globl directive declares a symbol to be external, that is, a symbol intended to be used by multiple, separately assembled pieces of the same program. The .globl directive guarantees that a symbol table entry will be generated in the object file, marked external. The linker uses these entries to resolve external symbol references at link time. Symbols declared with the .globl directive may or may not be defined within the current assembly. Defined symbols that are not declared to be external are assumed to be local symbols and may not be used to resolve undefined external references at link time. Undefined symbols are assumed to be external, with or without declaration, but it is good practice to declare all external symbols.

An alternate way to declare external symbols is to replace the colon of the label definition with a double colon (::).

Example:

.glob1 FIRST, SECOND

FIRST: SECOND: THIRD::

This example defines and exports three symbols: FIRST, SECOND, THIRD.

NOTE: Because .globl symbols are used by the linker to resolve external symbol references at link time, the user is advised to declare all .globl symbols as either external procedure descriptors (through the .xpd directive) or external data descriptors (through the .xdd directive), when assembling the program module with the modularity flag (-X on UNIX/MS-DOS, or /MODULAR on VMS).

6.6.2 .comm

Syntax: .comm symbol, expression

where: is the directive name. .comm

> is the name of a data symbol referenced, but not symbol

> > defined, in the current module.

expression specifies the number of bytes allocated for the symbol.

It may be any expression which evaluates to a positive

absolute value.

Description: The .comm directive imports the specified symbol and assigns it an

external undefined type. When the module is linked, the symbol will be

placed in the .bss section.

Example: 1 SYM1,16 .comm

2 SYM2,4 .comm 3 T00000000 14a8c000 movb SYM1, r0 0000

T00000006 57a8c000 movd SYM2, r1

0000

NOTE: Because .comm symbols are used by the linker to resolve external symbol references at link time, the user is advised to declare all .comm symbols as either external procedure descriptors (through the .xpd directive) or external data descriptors (through the .xdd directive), when assembling the program module with the modularity flag (-X on UNIX/MS-

DOS, or /MODULAR on VMS).

6.7 SEGMENT CONTROL DIRECTIVES

The segment control directives control the current segment type and the value of the assembler's location counter. These directives are:

Directive	Function
.dsect	sets the location counter to a user-defined segment
.text	sets the location counter to the text segment
.data	sets the location counter to the date segment
.bss	assigns space in the bss segment, updates the location counter
.udata	sets the location counter to the bss segment
.static	sets the location counter to the static segment
.link	sets the location counter to the link segment
.section	defines a section with attributes
.org	sets the location counter to specified value
.align	sets the location counter to specified offset
.ident	places the string argument in the .comment section of the object file

The segment control directives permit definition of program segments. A segment is a group of sequential statements whose addresses are all relative to the same base. Segments permit data or instructions to be processed as a unit and to be stored in a contiguous block within memory at run-time.

Sections 6.7.1 through 6.7.11 describe the syntax and operation of the segment control directives.

6.7.1 .dsect

Syntax:

.dsect symbol expression [, specifier]

where:

.dsect

is the directive name.

symbol

specifies the name of the dummy section.

expression

specifies the value and type of the location counter for the segment. The expression is required the first time a named dsect is invoked. Subsequent .dsect directives using the same name may omit the expression.

specifier

is a plus sign (+) or a minus sign (-). Specifier indicates whether the location counter should be incre-

mented or decremented.

Description:

The .dsect directive defines a named, user-defined (or dummy) segment. A dummy segment is used to define symbols which may be used in expressions or as instruction operands to access data. No code or initialized data may be generated in a dsect.

The assembler assigns a location counter to the segment with the value and type specified by the expression. If the type of the expression is relative, for example text or data, the dummy segment may be thought of as an overlay of an existing memory segment. For example, a dummy segment might be used to define differing logical data structures that occupy the same storage space, as in a C union or a Pascal variant record.

An optional specifier may be used to indicate whether the location counter for the dummy segment will increment or decrement. If the optional specifier is omitted, the value of expression determines whether the location counter increments or decrements. If the value of the expression is negative, the assembler decrements the location counter. If the value of the expression is positive or zero, the assembler increments the location counter. In either case, labels are assigned the lowest byte address of the following statement. That is, the location counter is post-incremented and pre-decremented.

Example:

.dsect DATE_REC, 0

MONTH: .blkb DAY: .blkb YEAR: .blkw

This example defines three absolute symbols in a dummy segment named DATE_REC. The symbols have the absolute values of 0, 1, and 2.

The symbols can be used as offsets into any block of memory. In the example below, r0 contains the address of a block of memory for storing the data. The instructions in the example zero-fill the month, day, and year fields.

.udata DATE: .blkb 4 .text movd DATE, r0 0, MONTH(r0) movab movqb 0, DAY(r0)

movqw

0, YEAR(r0)

6.7.2 .text

Syntax:

.text

where:

.text

is the directive name.

Description:

The .text directive indicates the beginning of a program text segment or code segment. The assembler assigns the current location counter the next available text segment address. Subsequent storage allocation, data generation, or program statements generate code and constant data that will be placed in the .text section of the object file. Storage allocated in the text segment is filled with nop instructions. The location counter is incremented after every assignment, storage allocation, or code generation.

Symbols defined in the text segment are of type text. The assembler uses the Program Counter (PC) Relative addressing mode for all symbols or expressions of type text. When the text segment is loaded into memory, it contains a module's instructions and constant data and is, therefore, protected for read-only access.

Example:

.text

In the preceding example, the location counter is set to text segment type. The offset is set to the next available offset. Instructions and data directives that follow the .text directive generate code in the .text section of the object file.

6.7.3 .data

Syntax:

.data

where:

.data

is the directive name.

Description:

The .data directive indicates the beginning of an initialized data segment. An initialized data segment contains writable data or program code and will be placed in the .data section of the object file. When the data segment is loaded into memory, it is protected for read-write access.

The .data directive sets the location counter to the next available data segment address. The location counter is incremented after every data assignment or code generation. Symbols defined in the data segment are of type data. The assembler uses the Absolute addressing mode for all symbols or expressions of type data.

Example:

.data

In the preceding example, the location counter is set to the data segment. The offset is set to the next available data segment address. Subsequent data directives, or instructions, are output to the .data section of the object file.

6.7.4 .bss

Syntax:

.bss symbol, expression1, expression2

where:

.bss

is the directive name.

symbol

is a symbol name.

expression 1

specifies the symbol size.

expression2

specifies an alignment value for the bss location

counter. The alignment value may not be zero.

Description:

The .bss directive defines a symbol in the bss or the uninitialized data segment. There is no code or data in the object file associated with the bss segment. The .bss directive is a shorthand way to align the location counter associated with the bss segment, define a symbol, and allocate the appropriate number of bytes of storage space. It does not change the current location counter to the bss segment. To change the current location counter, use the .udata directive, see Section 6.7.5.

The .bss directive performs the following actions:

- 1. aligns the bss location counter to a multiple of expression 2. The value of the location counter is incremented if necessary.
- defines the specified symbol. The symbol is assigned the current value of the bss segment location counter and type bss. The assembler uses the Absolute addressing mode to reference symbols or expressions of type bss.
- adds the number of bytes specified by expression1 to the bss location counter.

Example:

.bss name_str, 25, 4

In the preceding example, the bss segment location counter is aligned to the next multiple of four bytes, incrementing if necessary. The symbol name_str is defined and assigned the value of the bss location counter. The bss segment location counter is incremented by 25.

6.7.5 .udata

Syntax:

.udata

where:

.udata

is the directive name.

Description:

The .udata directive indicates the beginning of a bss or uninitialized data segment. It is used to define symbols and allocate storage space. As with dummy sections, no code or data is generated in the object file. However, storage space is accumulated. The total accumulated size of the segment is recorded in the a.out header and the .bss section header of the object file. Memory is allocated for the total size of the bss segment at load time.

The directive sets the location counter to the next available bss segment address. Symbols defined in the bss (udata) segment are of type bss. The assembler uses the Absolute addressing mode for all symbols or expressions of type bss.

Example:

.udata

In the preceding example, the location counter is set to type bss. The offset is set to the next available offset.

6.7.6 .static

Syntax: .static

where: is the directive name. static

Description:

The .static directive defines a static base segment. The assembler assigns the current location counter the next available static segment address. Subsequent storage allocation, data generation, or program statements generate code in the static segment. The location counter is incremented after every assignment or code generation. The data will be placed in the .static section of the object file. Storage allocated in the static segment is zero-filled. All symbols defined in the static segment are of type static. The assembler addresses all symbols or expressions of type static with the SB Relative addressing mode.

The .static directive is useful when building Series 32000 modules. The assembler generates all SB Register Relative and SB Memory Relative addresses as offsets from zero unless a .module directive or a .modentry directive is issued to set the static base address directly.

Example:

1				.statio	2
2	S00000000	00	ALPHA:	.blkb	
3	S00000001	00000000	BETA:	.blkw	2
4	S00000005	00000000	GAMMA:	.blkd	

The preceding example defines three symbols in a static base segment. The .static directive (Line 1) sets the location counter to static segment type and to the next available static segment address. Lines 2, 3, and 4 allocate a total of 9 bytes of storage, zero-filled.

6.7.7 .link

Syntax:

.link

where:

.link

is the directive name.

Description:

The .link directive defines a link table segment. The link segment contains a Series 32000 module's link table. A Series 32000 module requires a link table entry for each variable the module imports from another module and for each procedure the module imports or exports that uses the cxp, rxp calling discipline. The link table offset should be used with the External addressing mode to access all external variables from a Series 32000 module. The .xdd directive should be used to generate link table entries for data variables. The .xpd directive should be used to generate procedure descriptor link table entries for functions. Care should be taken that link table entries remain aligned on 4-byte boundaries if any other directives or instructions are used in the link segment.

The .link directive assigns the current location counter the next available link segment address. The location counter is incremented after every .xdd or .xpd directive. The link table will be placed in the .link section of the object file. Any storage allocated in the link segment is zero-filled. All symbols defined in the link segment are of type link. The assembler addresses all symbols or expressions of type link with the absolute addressing mode.

The definition of a link table entry in the link table segment should precede any reference to it.

```
.link
LINK ENTRY:
               .xpd
                       scan_arg
               .text
               addr
                       LINK_ENTRY, r0
               cxpd
                       r0
```

In this example, the addr instruction uses the absolute addressing mode to access LINK_ENTRY.

1 2 3				_	_main _printf	
4				.link		
5	L00000000	00000000	main:	.xpd	_main	
6	L00000004	00000000	printf:	.xpd	_printf	
7						
8				.text		
9			_main:			
10	T00000000	820000		enter	[],0	
11	T00000003	e7d5c000		addr	${\tt msg,tos}$	
		0020				
12	T00000009	22c00000		cxp	printf	
		07				
13	T0000000e	7ca5fc		adjspb	\$ -4	
14	T00000011	9200		exit	[]	
15	T0000013	3200		rxp	0	
16						
17				.static		
18			msg:			
19	S00000000	48656c6c 6f2c2057 6f726c64 210a00		.ascii	"Hello,	World"

Example:

Lines 1 and 2 declare the variables _main and _printf to be external, *i.e.*, available for export or necessary to import.

Line 4 begins the link table segment. The current location counter is set to link segment type, offset 0.

Line 5 generates a procedure descriptor link table entry for _main, beginning at link table segment address L00000000. Each link table entry is four bytes long. The current location counter is address L00000004 of the link segment at the end of line 5.

Line 6 generates a procedure descriptor link table entry for _printf. The current location counter is link segment address L00000008 at the end of line 6.

Line 8 begins a text segment. The current location counter is set to the next available text segment address, which is T00000000.

Lines 9 to 15 generate program code. At the end of line 15, the current location counter is text segment address T00000015, hexadecimal. This is the next available text address.

Line 17 begins a static segment. The current location counter is set to the next available static segment address, S00000000.

Line 19 generates the ASCII character string "Hello, World!\12\0" in the static segment.

6.7.8 .section

Syntax:

.section section_name, string or

.section section_name

where:

section name

is any legal identifier, only eight significant characters

string

is a quoted string consisting of any combination of the following letters:

b -> STYP_BSS -> STYP_COPY c i -> STYP_INFO -> STYP_DSECT d -> STYP TEXT х -> STYP_NOLOAD n -> STYP OVER 0 1 -> STYP_LIB -> STYP_DATA

Description:

The .section directive allows the assembly programmer to define a section with attributes, refer to the Series 32000 GNX — Version 3 COFF Programmer's Guide for a description of section attributes. Section name is the name of the section, and each character in string represents an attribute. Symbols declared within a section belong to the particular section. A section is active until the next .section, .text, .data, .udata, .link, or .static directive. In the default case, reference to symbols of a user-defined section are referenced via the absolute addressing mode. Only 10 sections are allowed including .text, .data, .bss, .link, .static, .mod, and .comment. The .mod and .comment sections are optional; therefore, there can only be 3, 4 or 5 user-defined sections.

Example:	1 2 3 4 5				.globl .globl .globl	start istart mcount
	6			start:		
	7	T00000000	7ca508		adjspb	\$8
	8	T00000003	57ce0800		movd	8(sp),0(sp)
	9	T00000007	27c80c		addr	12(sp),r0
	10	T0000000a	570604		movd	r0,4(sp)
	11	T0000000d	02c00000 13		bsr	istart
	12	T00000012	02ffffff ee		bsr	_main
	13	T00000017	7ca5f4		adjspb	\$-12
	14			mcount:	J -	
	15	T0000001a	1200		ret	0
	16					
	17				.data	
	18				.align	4
	19			environ:		
	20	D00000000	00000000		.double	0
	21					
	22				.section	n.init,"x"
	23			istart:		
	24	00000000	820700		enter	[r0,r1,r2],0

In this program, line 22 is the declaration of a section called .init, whose section attribute is STYP_TEXT. The label "istart" and the "enter" instruction both belong to the .init section.

6.7.9 .org

Syntax: .org expression

where: is the directive name. .org

> specifies the new value of the location counter. The expression

expression must evaluate to type absolute or the type

of the current location counter.

Description:

The .org directive changes the value of the current location counter within a segment. It sets the location counter to the value specified by expression. The type of the expression must be compatible with that of the current location counter, or it must be an absolute address. If the expression evaluates to an absolute address, the assembler generates a warning message, and sets the location counter to the value specified by expression + the starting location of the current segment.

If the current segment is an object file segment, that is, one of text, data, static, or link, then the value of the expression must be greater than, or equal to, the current location counter (i.e., backstepping is not permitted). Furthermore, for object file segments, the GNX Assembler fills the bytes between the current and the new location with alignment values as filled for the .align directive. The added bytes are included in the program listing.

Example:

```
1
                       .set
                               NUM CHNKS, 10
2
                               CHNK_SIZE, 4096
                       .set
3
4
                       .udata
5
  B00000000
                       .blkd
               c_ptr:
6
  B00000028
               pool:
                       .org
                               pool + (NUM_CHNKS * CHNK_SIZE)
7
  B0000a028
               mark:
                       .blkd
```

This example uses the .org directive to leave a large area of memory available in the bss segment.

6.7.10 .align

Syntax:

.align expression1 [,expression2]

where:

.align

is the directive name.

expression1

specifies the basis of a new location counter value. It must evaluate to a positive absolute value. No forward symbol references are permitted.

expression2

specifies the offset of the new location counter value. It must evaluate to a non-negative absolute value and must be less than the value of *expression1*. Default value is zero. No forward symbol references are permitted.

Description:

The .align directive sets the location counter to a new value without changing the current type. The new value is the sum of a multiple of the basis, *expression1*, and the offset, *expression2*. The new value is always equal to, or greater than, the current location counter and satisfies the following equation:

new value MOD expression1 = expression2

The new value is the multiple of the basis that is greater than, or equal to, the current location counter. For example, if *expression1* is 6 and the current location counter is 20, then the new value is 24 (*i.e.*, 4*6). The default value of *expression2* is zero.

If both expression 1 and expression 2 are specified, the new value is the sum of the multiple of the basis and the offset. For example, if expression 1 is 4, expression 2 is 3, and the current location counter is 22, then the new value is 27 (i.e., 6*4+3).

The assembler will optimize the fill pattern if the current section is .text. The optimized filler can be viewed as a fancy nop. The assembler will use "movb r7,r7" for 2-bytes fillers, "orb \$0,r7" for 3-bytes fillers, "orw \$0,r7" for 4-bytes fillers, "orw \$0,r7" and "nop" for 5-bytes fillers, "ord \$0,r7" for 6-bytes fillers. All other alignments are filled with combinations of the above.

If the .align directive is used in the data, static, or link segment, then the assembler zero-fills all bytes between the current location and the specified address and includes up to 128 bytes of the zero-filled bytes in

the program listing.

Example:

```
1
                                       .static
2
  S00000000
               0.0
                           FIRST:
                                       .blkb
3
  S0000001
               000000
                                       .align 4
4
  S00000004
               00
                                       .blkb
                           SECOND:
5
  S00000005
               00000000
                                       .align 4, 2
               00
  S0000000a
               00
                          THIRD:
                                       .blkb
```

The preceding example contains two .align directives (lines 3 and 5). In line 3, the directive sets the location counter to a multiple of 4. The current location counter is S00000001 (static segment), so the new location counter will be S00000004 (i.e., 1*4). In line 5, the directive sets the location counter to a multiple of 4 plus 2. If the current location counter is 5, then the new location counter is 10 (0xa) (i.e., 2*4 + 2).

Example:

1			_mail:	
2	T00000000	a2		nop
3			LABEL:	
4	T00000001	d439		.align 3
5	T00000003	0a00		.word 10
6	T00000005	d8a100		.align 4
7	T00000008	01		.byte 1
8	T00000009	0a00		.word 10
9	T0000000b	a2		.align 2
10	T0000000c	1200		ret 0

The preceding example contains three .align directives (lines 4, 6, and 9). In line 4, the directive sets the location counter to a multiple of 3. The current location counter is T00000001 (text segment), so the new location counter is T00000003 (i.e., 1*3). The 2-byte filler "movb r7,r7" denoted by the opcode d439 (low bytes first) is used. In line 6, the directive sets the location counter to a multiple of 4. The current location counter is T00000005, so the new location counter will be T00000008 (i.e., 2*4). The 3-byte filler "orb \$0,r7" denoted by the opcode d8a100 is used. In line 9, the directive sets the location counter to a multiple of 2. The current location counter is T0000000b, so the new location counter will be T0000000c (i.e., 6*2). The single byte filler "nop" denoted by the opcode a2 is used in this case.

6.7.11 .ident

Syntax:

.ident string

where:

string

is a quoted string.

Description:

The .ident directive takes its string argument and places it in the .comment section of the object file. This directive may be used more than once. The .comment section is given the section attribute of STYP_INFO. The Linker will combine all .comment sections at link time.

Example:

```
1
                         .text
2
                         .ident "This is .ident"
3
  T00000000 a2a2a2a2
                         .space 10
              a2a2a2a2
              a2a2
                         .ident "Another .ident"
4
```

In this program, the strings "This is .ident" and "Another .ident" are placed in the .comment section of the object file.

6.8 MODULE TABLE DIRECTIVES

Di--- ---

The module table directives manage the task of building the module table. Defined module table entries are placed by the GNX Assembler into the .mod section of the COFF output file. The following are the module table directives discussed in this section:

E-----

Directive	Function
.module	names a module, associates the assembled code and static local data with the module, and defines a module table entry for the module.
Warning	The .text and .static sections of the file where .module is used will
	be treated as modular sections by the GNX linker even when the
	assembler was not invoked with the "-X" ("/MODULAR" on VMS)
	invocation option. In particular, during the link, input section rules of
	the form *(.text) or *(.static), will not apply to such files.
	Please see the GNX Linker Programmer's Reference Manual for further
	information on the linking process.
.modentry	defines a module table entry for a named module.

A module table entry consists of four 32-bit entries corresponding to each component of a module:

- The Static Base (sb) entry contains the base address for the module's static local data.
- The Link Base (lb) entry contains the base address for the module's link table.
- The Program Base (pb) entry contains the base address for the module's program code.
- A fourth entry is currently unused but reserved.

Each base address is a standard Series 32000 address. The relocation information for the sb, lb, and pb entries depends on how these base addresses have been specified. The following discusses the module table entries and their relocation information.

Static Base (sb) Entry

If the sb entry is specified by an expression of:

- 1. absolute type (e.g., sb=200), the module table entry's static base address is the specified absolute value. No relocation information will be generated.
- 2. non-absolute type (e.g., sb=sb_sym+10 where sb_sym is non-absolute), the module table entry's static base address is the value of the expression, and a relocation entry will be generated as follows:

```
R_ADDRTYPE = R_ADDRESS
R_RELTO = R_ABS
R_FORMAT = R_NUMBER
R_SIZESP = R_S_32
```

with symbol table index pointing to the symbol table entry that is being relocated (e.g., sb_sym). Refer to the Series 32000 COFF Programmer's Guide for a definition of these symbols.

If the sb entry is not specified, the assembler will use location zero as the module table entry's static base address. At link time, the linker will set the module's static base to the lowest address of the output section that contains the input static sections for the module.

The relocation entry, generated by the assembler when the sb entry is not specified, is as follows:

```
R_ADDRTYPE = R_STATIC_SEC
R_RELTO = R_ABS
R_FORMAT = R_NUMBER
R_SIZESP = R_S_32
```

with symbol table index pointing to the module name. Refer to the *Series 32000 COFF Programmer's Guide*, for a definition of these symbols.

Link Base (lb) Entry

If the lb entry is specified by an expression of:

- 1. absolute type (e.g., lb=200), the module table entry's link table base address is the specified absolute value. No relocation information will be generated.
- 2. non-absolute type (e.g., lb=lb_sym+10 where lb_sym is non-absolute), the module table entry's link table base address is the value of the expression, and a relocation entry will be generated as follows:

```
R_ADDRTYPE = R_ADDRESS
R_RELTO = R_ABS
R_FORMAT = R_NUMBER
R_SIZESP = R_S_32
```

with symbol table index pointing to the symbol table entry that is being relocated (e.g., lb_sym). Refer to the Series 32000 COFF Programmer's Guide, for a definition of these symbols.

If the lb entry is not specified, the assembler will use location zero as the module table entry's link table base address. At link time, the linker will set the module's link table base to the lowest address of the output section that contains the input link sections for the module.

The relocation entry generated by the assembler when the lb entry is not specified is as follows:

```
= R_LINK_SEC
R_ADDRTYPE
R RELTO
            = R_ABS
R FORMAT
            = R NUMBER
R_SIZESP
            = R_S_32
```

with symbol table index pointing to the module name. Refer to the Series 32000 COFF *Programmer's Guide*, for a definition of these symbols.

Program Base (pb) Entry

If the pb entry is specified by an expression of:

- 1. absolute type (e.g., pb=200), the module table entry's program code base address is the specified absolute value. No relocation information will be generated.
- 2. non-absolute type (e.g., pb=pb_sym+10 where pb_sym is non-absolute), the module table entry's program code base address is the value of the expression, and a relocation entry will be generated as follows:

```
R_ADDRTYPE
            = R_ADDRESS
R_RELTO
            = R_ABS
R_FORMAT
            = R_NUMBER
R_SIZESP
            = R_S_32
```

with symbol table index pointing to the symbol table entry that is being relocated (e.g., pb_sym). Refer to the Series 32000 COFF Programmer's Guide, for a definition of these symbols.

If the pb entry is not specified, the assembler will use location zero as the module table entry's program code base address. At link time, the linker will set the module's program base to the lowest address of the output section that contains the input .text sections for the module.

MODULE TABLE DIRECTIVES (Cont)

The relocation entry generated by the assembler when the pb entry is not specified is as follows:

> R_ADDRTYPE = R_TEXT_SEC $R_RELTO = R_ABS$ $R_FORMAT = R_NUMBER$ $R_SIZESP = R_S_32$

with symbol table index pointing to the module name. Refer to the Series 32000 COFF Programmer's Guide, for a definition of these symbols.

6.8.1 .module

Syntax: .module symbol [, sb=static base] [, lb=link base]

[,pb=program base]

is the directive name. where: .module

> is the name of the module. This symbol will define the symbol

module's module table entry.

sb=static base explicitly sets the static base address for the module.

1b=link base explicitly sets the link table base address for the

module.

pb=program base

explicitly sets the program code base address for the

module.

Description:

The .module directive declares a module name, associates the text, link, and static local data segments generated by this assembly to the module table entry name and optionally defines a module table entry for the module.

If none of the optional arguments are specified, symbol is a global, undefined symbol unless name is previously defined by the .modentry directive. See Section 6.8.2 for the description on the .modentry directive.

If any of the optional arguments are specified, the assembler generates a 16-byte module table entry that contains the module's static base address, link table base address, program code base address, and a reserved double-word set to zero in the .mod section of the output COFF file. The value for the module table entry's static base address, link table base address, and program code base address will be as specified

by the sb, lb, pb contents, or by default, the lowest address of .static, .link, .text section for the named module as output by the linker, if there is one, otherwise zero, and their corresponding relocation entries. Refer to Section 6.8 for the description on module table entries and their relocation information. Symbol, in this case, is global and is defined in the .mod section with the value of the address of the module table entry.

There may be no more than one .module directive per assembly.

Example:

.module hello, sb=.static, 1b=.link

6.8.2 .modentry

Syntax: .modentry symbol [,sb=static base] [,1b=link base]

[,pb=program base]

where: .modentry is the directive name.

> symbolis the module name. This symbol defines the module's

> > module table entry.

sh=static base explicitly sets the static base address for the module. If

> not specified, the assembler will use the default value of zero and at link time, the linker will set it to the

lowest address of the output .static section.

1b=link base explicitly sets the link table base address for the

module. If not specified, the assembler will use the default value of zero and at link time, the linker will set it to the lowest address of the output .link section.

pb=program base

explicitly sets the program code base address for the module. If not specified, the assembler will use the default value of zero and at link time, the linker will set it to the lowest address of the output .text section.

Description:

The .modentry directive defines a module table entry for a named module by generating a 16-byte module table entry that contains the module's static base address, link table base address, program code base address, and a reserved double-word set to zero in the .mod section of the output COFF file. The value for the module table entry's static base address, link table base address, and program code base address will be as specified by the sb, lb, pb contents, or by default, the lowest address of the .static, .link, .text section for the named module as output by the linker, if there is one, otherwise zero, and their corresponding relocation entries. Refer to Section 6.8 for the description on module table entries and their relocation information.

Symbol identifies the module.

```
Example:

devices.s:
    .file "devices.s"
    .modentry devA  # Define mod table entry for device A
    .modentry devB  # Define mod table entry for device B
    .modentry devC  # Define mod table entry for device C

devA.s:
    .file "devA.s"
    .module devA  # Must not use optional args

devB.s:
    .file "devB.s"
    .module devB  # Must not use optional args

devC.s:
    .file "devC.s"
    .module devC  # Must not use optional args
```

6.9 FILENAME DIRECTIVE

The filename symbol directive specifies the name of the source file:

Directive

Function

specifies the source filename .file

6.9.1 .file

Syntax:

.file "symbol"

where:

.file

is the directive name.

"symbol"

specifies source filename for the current assembly.

Must be enclosed in double-quotes.

Description:

The .file directive specifies the name of the source file currently being assembled. The GNX Assembler records the filename in the object file as an auxiliary symbol table entry of the special symbol .file. Only one .file directive per source file is allowed. It may appear anywhere in the file. If no .file directive is specified, the filename is the input source filename.

If more than one .file directive is specified, the first specified filename is taken, and a warning message is issued for the rest of them.

The .file directive is used by compilers to associate the name of a high-level language source file with the object file produced by the GNX Assembler.

Example:

.file "stress.c"

This example defines the symbol stress.c as the name of the source file associated with the current assembly.

NOTE: When using the debugger, the *symbol* must be the same as the filename since the debugger uses this as the name of the source file.

6.10 SYMBOL TABLE ENTRY DEFINITION DIRECTIVES

The symbol table entry definition directives specify symbolic information which the GNX Assembler records in the object file. The directives provide a means to record a variety of information useful to symbolic debuggers. Symbol table entry directives do not affect the execution of an assembly language program.

The basic symbol table entry directives are .def and .endef. They mark the start and the end of a symbol definition. Between these, various directives may be used to assign attributes to the symbol, for example, its size, value, and type or its location in the source file.

Each .def begins to define a new symbol table entry. Therefore, all information to be recorded about a single symbol must be included between the .def directive and the matching .endef directive.

Symbol table entry definitions may not be nested.

The symbol table entry definition directives are as follows:

Directive	rective Function			
.def	begins symbol table entry definition			
.dim	defines the dimensions of an array			
.line	specifies a source line number			
.scl	specifies the symbol's storage classification			
.size	specifies the symbol's storage size			
.tag	specifies the tag name associated with a type			
.type	specifies the symbol's type			
.val	specifies the symbol's value			
.endef	terminates the symbol table entry definition			

Sections 6.10.1 through 6.10.9 describe the symbol table entry directives in detail.

NOTE: It is important to fully understand the Common Object File Format (COFF) symbol table requirements before attempting to use these directives. For complete specification of COFF requirements refer to the Series 32000 GNX — Version 3 COFF Programmer's Guide. For useful constant definitions see the include files:

File	Contents
syms.h	Symbol table entry definition, auxili-
	ary entry definition, type and derived type values
storclass.h	Storage class values

6.10.1 .def

Syntax:

.def symbol

where:

.def

is the directive name.

symbol

is a symbol name. It consists of a series of characters which may be letters, numbers, period (.), or underscore (). The first character must not be a number.

Description:

The .def directive causes the GNX Assembler to begin the definition of a Common Object File Format (COFF) symbol table entry for the specified symbol. The GNX Assembler creates the new symbol table entry and enters the symbol name. The Assembler does not check the COFF validity of the given values for symbol table entries definition.

Example:

```
.def
        _n_ptr
        .val
                  _n_ptr
        .scl
                  2 \mid (1 << 4)
        .type
.endef
.globl
        _n_ptr
.comm
        n ptr,4
```

This example is a symbolic definition associated with the C declaration:

```
char
       *n_ptr;
```

The .def directive starts the definition. The symbol table entry is assigned the value _n_ptr, a storage class of external (C_EXT) represented by the value 2, a base type of character (T_CHAR) represented by the value 2, and a derived type of pointer (DT_PTR) represented by the value 1. The .endef directive ends the definition. For more information about the structure of a COFF symbol table entry, the meaning of various fields, and the values each may contain, refer to the Series 32000 GNX — Version 3 COFF Programmer's Guide.

6.10.2 .dim

Syntax:

.dim expression,,,

where:

.dim

is the directive name.

expression

specifies the size of one dimension of an array.

Description:

The .dim directive defines the dimensions of an array. Each argument expression specifies the number of elements in one array dimension. The symbol table entry format allows the specification of up to four array dimensions.

The GNX Assembler enters the specified expressions into the array dimension field of the auxiliary symbol table entry for the symbol that is being defined. If no auxiliary entry exists, the GNX Assembler creates one.

Example:

.dim 5,10

This example is a portion of the symbolic definition for a twodimensional array. Dimension one is 5, dimension two is 10.

6.10.3 .line

Syntax:

.line expression

where:

line

is the directive name.

expression

is the source file line number of the symbol declara-

tion

Description:

The .line directive specifies the source file line number on which a symbol has been declared. The GNX Assembler enters the specified value, expression, into the line number field of the auxiliary symbol table entry for the symbol that is being defined. The Assembler generates an auxiliary entry if one does not exist.

The .line directive should be used when the symbol being defined is a block symbol. Block symbols include the special symbols .bf and .ef which define the beginning and ending of functions, the special symbols b and eb which define the beginning and ending of blocks, and all symbols defined within a block.

The .line directive should be used only where the NOTE: Common Object File Format symbol table entry specification requires and accepts a line number. For additional information, refer to the Series 32000 GNX — Version 3 COFF Programmer's Guide.

Example:

.line 25

This example is part of the definition of a block symbol declared on source line number 25.

6.10.4 .scl

Syntax:

.scl expression

where:

.scl

is the directive name.

expression

is the value of a storage classification as defined in the Series 32000 GNX — Version 3 COFF Programmer's Guide.

Description:

The .scl directive assigns a storage class value to the symbol definition. The storage class of a symbol affects the interpretation of the "value" field of the entry. Storage classes are as follows:

C_AUTO — automatic variable, whose value is a stack offset.

C_EXT — external symbol, whose value is a relocatable address.

C_STAT — C style static or local variable, whose value is a relocatable address.

C_REG — register variable, whose value is the number of the register. For example, if the register is r0 the register number is 0.

C_LABEL — an assembly language label, whose value is a relocatable address.

C_MOS — member of a structure, whose value is the offset of the field from the start of the structure.

C_ARG — function argument, whose value is a stack offset.

 C_STRTAG — structure tag (name), whose value is 0.

C_MOU — member of a union, whose value is the offset of the field from the start of the union.

C_UNTAG — union tag (name), whose value is 0.

 C_TPDEF — type definition, whose value is 0.

 C_ENTAG — enumeration tag (name), whose value is 0.

C_MOE — member of an enumeration, whose value is the enumeration number.

C_REGPARM — register parameter, whose value is the number of the register.

C_FIELD — bit field, whose value is the bit displacement.

C_BLOCK — beginning or end of block, whose value is a relocatable address.

C_FCN — beginning or end of a function, whose value is a relocatable address.

C_EOS — end of a structure, whose value is the structure size.

C_FILE — filename entry, whose value is the symbol table index of the next .file symbol or the beginning of the global symbols if there are no more .file symbols.

C_ALIAS — duplicate tag, whose value is the symbol table index of the tag definition.

For more complete information about storage classes and their values, refer to the Series 32000 GNX — Version 3 COFF Programmer's Guide.

Example:

.scl 2

This example specifies a storage classification of C_EXT (external), represented by the value 2.

6.10.5 size

Syntax:

.size expression

where:

.size

is the directive name.

expression

specifies the size of a structured variable.

Description:

The .size directive specifies the total size of a structured type, an array, or an enumerated type. The GNX Assembler enters the specified value into the size field of the auxiliary symbol table entry for the symbol that is being defined. If no auxiliary entry exists, the Assembler generates one. For example, the C declaration:

char name list[20] [200];

generates the following symbol specification:

1	.def	_name_list	
2		.val	_name_list
3		.scl	2
4		.type	0362
5		.dim	20,200
6		.size	4000
7	.endef		
8		.globl	_name_list
10		.comm	_name_list,4000

The storage size specified by the .size directive in line 6 is 4000 bytes (20*200*sizeof(char)), where the size of a character is one byte.

Example:

.size 200

This example specifies a symbol's storage size as 200 bytes. The Assembler enters the value 200 into the size field of the auxiliary symbol table entry for the symbol that is being defined.

6.10.6 .tag

Syntax:

.tag symbol

where:

.tag

is the directive name.

symbol

is a symbol. The symbol is the tag name of a data structure definition, for example, a C struct or union.

Description:

The .tag directive associates the tag name of a data structure with a symbol. The GNX Assembler enters the symbol table index of the tag name into the tag index field of the auxiliary entry for the symbol that is being defined. If no auxiliary entry exists, the GNX Assembler generates one.

Example:

```
.def _coord
     .scl 10; .type 010; .size 12; .endef
.def _a
     .val 0; .scl 8; .type 04; .endef
.def _b
     .val 4; .scl 8; .tvpe 04; .endef
.def _c
     .val 8; .scl 8; .type 04; .endef
.def
     .val 12; .scl 102; .tag _coord; .size 12; .endef
.def bar
     .val _bar; .scl 2; .type 010; .tag _coord; .size 12; .endef
     .globl _bar
     .comm _bar,12
```

This example defines the symbols associated with the C declarations:

```
coord {
struct
         int
                   a;
         int
                   b;
         int
                   c:
};
struct
         coord
                   bar;
```

The special symbol .eos (end of structure) uses the .tag directive to point back to the definition of the structure coord.

The bar symbol, which is of type struct coord, also uses the .tag directive to point to the entry for coord.

6.10.7 .type

Syntax: .type expression

where: is the directive name. .type

> specifies the type of a symbol. expression

Description: The .type directive specifies type information associated with the symbol that is being defined. The GNX Assembler enters the expression into the type field of the main symbol table entry for the symbol that is being

defined.

The type field consists of sixteen bits, of which the low-order four contain the base type. The remaining bits contain derived types, each of which is specified in a two-bit field. For definition of types and derived types see the Series 32000 GNX - Version 3 COFF Programmer's Guide.

Examples:

```
1.
      .type
               (2 \mid (2 << 4)) \mid 1 << 6
2.
      .type
               4
```

The first example is a symbolic definition associated with the C declaration:

```
char
          *fn();
```

The base type is T_CHAR (type character) represented by the value 2. The first derived type is DT_FCN (function) represented by the value 2. The second derived type is DT_PTR (pointer) represented by the value 1. The entire type field is interpreted as a pointer to a function that returns a character.

The second example is associated with the C declaration:

```
int
          flag;
```

The .type directive specifies the type T_INT (integer) represented by the value 4.

6.10.8 .val

Syntax:

.val expression

where:

.val

is the directive name.

expression

specifies the value of the symbol.

Description:

The .val directive specifies the value field of the main symbol table

entry for the symbol that is being defined.

Example:

.val _flag

This example sets the value field of the symbol table entry to the

address of the symbol _flag.

6.10.9 .endef

Syntax: .endef

where: is the directive name. .endef

The .endef directive causes the GNX Assembler to end the definition Description:

> of a Common Object File Format (COFF) symbol table entry for the specified symbol. The GNX Assembler adds the new symbol table entry to the symbol table. The GNX Assembler generates an auxiliary entry if the symbol specifications require one and fills in any symbol table index

fields as necessary.

Example: .def _flag

> .val _flag .scl

.type 4

.endef

This example is a symbolic definition associated with the C declaration:

int flag;

The .endef directive ends the definition.

6.11 LINE NUMBER TABLE CONTROL DIRECTIVE

Each section in the object file may have an associated line-number table, for the purpose of source-level debugging support. The line-number table maps source file line numbers to addresses within the section. Each line number table entry is either a function entry or a line number entry. Function entries record the symbol table index for the function. Line number entries record a line number offset from the start of the function and an associated physical address.

Function entries are generated automatically by the assembler when a function is defined, refer to Section 6.10. Line number table entries are created with the .ln directive.

Directive

Function

.1n specifies a line number entry

6.11.1 .ln

Syntax:

.1n expression1 [,expression2]

where:

.ln

is the directive name.

expression 1

specifies the source file line offset from the beginning

of a function.

expression2

specifies an associated memory address. This value

defaults to the current location.

Description:

This directive is used to equate higher level source code line numbers to assembly code, normally generated by compilers. Expression1 must yield a value of absolute type that gives a line number in the source code. Expression2 if present, must have a value of type TEXT, DATA, or BSS that gives the address within the section where the line number occurs. If the second operand is missing, the value of the current location counter will be used as the address of the line number.

Example:

.ln 1

This example defines a line number entry for the first line of a function. The associated memory address is the value of the current location counter.

6.12 MACRO-ASSEMBLER DIRECTIVES

The macro-assembler directives provide the macro and conditional assembly support. They enable the definition and usage of macros, and allow for the inclusion or deletion of optional assembly statements. Other macro-assembler directives help minimize programming errors and speed the development process. For more details see Chapter 8.

The macro-assembler directives are as follows:

Directive	Function
.macro	begins a macro-procedure definition
.endm	ends a macro-procedure definition
.if	begins a conditional macro-assembler statement
.elsif	begins an elsif close for the conditional macro-
	assembler statement
.else	begins an else close for the conditional macro-
	assembler statement
.endif	ends a conditional macro-assembler statement
.repeat/.irp	begins a macro repetitive block
.endr	ends a macro repetitive block
.exit	terminates processing of the current repetitive block
.macro_on	enables macro-procedure expansions
.macro_off	disables macro-procedure expansions
.include	includes another file
.mwarning	generates an assembler warning message
.merror	generates an assembler error message

6.12.1 .macro

.macro macro-name [formal-arg [, formal-arg] ...] Syntax:

where: is the macro-procedure name. It may be any legal macro-name

assembler symbol.

formal-arg is a macro-variable defining a formal argument.

Description: .macro directive begins the macro-procedure definition. The macro-procedure associates a macro name with a sequence of state-

ments which follow the .macro directive, up to the .endif directive.

Example: .macro clear_array size, base_reg

> Defines a macro procedure named clear_array with two formal arguments size and base_reg.

6.12.2 .endm

Syntax: .endm [macro_name]

where: .endm ends the macro-procedure definition.

Description: The .endm directive marks the end of the macro-procedure definition.

macro_name is an optional specification for the name of the macro to be

ended.

Example:

.macro clear-array size, base-reg # defines clear-array

. # macro statements

.endm clear-array # ends the definition of clear_

6.12.3 .if

Syntax: .if if_condition

where: if condition is an arithmetic macro-expression.

Description: The .if directive begins a conditional macro assembler statement.

if_condition is a condition to be tested during macro processing phase. If found to be true, the statements following it (until a corresponding .elseif, .else or .endif directive) are processed by the macro pro-

cessor.

Example: .if $\{reg_num\} > 5$

> 5, r{reg_num} movqd .elsif $\{reg_num\} > 3$ movgd 3, r{reg_num} .else

movqd 1, r{reg_num}

.endif

If reg_num holds the value 6 this is expanded to

movqd 5, r6

if reg_num holds the value 4 this is expanded to

movqd 3, r4

and if reg_num holds the value 0 this is expanded to

movqd 1, r0

6.12.4 .elsif

Syntax:

.elsif elsif_condition

where:

elsif_condition is an arithmetic macro-expression.

Description:

In a conditional block, if the if_condition is found to be false, the elsif_condition arguments are evaluated until one is found to be true. If the elsif_condition is found to be true, the corresponding elsif_conditional_body statements following the elsif_condition are pro-

cessed.

6.12.5 .else

Syntax: .else else_conditional_body

 $else_conditional_body$ where:

> consists of valid assembly language statements, directives, macro-procedure calls and macro-assembler directives, repetitive blocks and macro-procedure

definitions.

Description: In a conditional block, if the previously specified if_condition or

elsif_condition is found to be false, then the else_conditional_body state-

ments (following the elsif_condition) are processed.

6.12.6 .endif

Syntax: .endif

Description: Ends an .if conditional macro-assembler statement.

6.12.7 .repeat

Syntax: .repeat [iteration_count [, iteration_var]]

where: iteration_count specifies the number of iterations.

> is a macro-variable name used as an iteration index. iteration_var

Description:

The .repeat directive begins a macro repetitive block, which ends with a .endr directive. The number of repetitions is determined by the iteration_count argument. Repetitive blocks may appear inside a macro-procedure definition, in conditional blocks, and may be nested without limit.

If given, the *iteration_var* argument holds a string representing the current iteration number for each iteration. After the repetitive block has been processed, it holds the iteration_count value. If the iteration_count argument is evaluated as a negative or zero value, the statements in the block are read textually without being processed until an .endr directive is reached. If the iteration count argument is not given, then the repetitive block is processed repeatedly until an .exit directive is processed (see section 8.9.3).

Example:

generates code that clears r0 through r7.

6.12.8 .irp

Syntax:

.irp iteration_var, iteration_list

where:

iteration_var

is a macro-variable name to be used as an iteration

variable.

iteration_list

is a macro-list.

Description:

The .irp directive begins a special macro repetitive block, which ends with a endr directive. For each element in the iteration_list argument, the macro-processor assigns its string value to iteration_var, and process the code between the .irp statement and the corresponding .endr statement. If the *iteration_list* argument is an empty macro-list, the statements in the block are read textually without being processed. After the repetitive block has been processed, iteration_var contains the last element of iteration list.

Example:

```
.irp
       reg, [r0,r1,r2,r3,r4,r5,r6,r7]
  movad
                 0, {req}
.endr
```

generates code that clears registers r0 through r7.

6.12.9 .endr

Syntax: .endr

Description: The .endr directive ends a macro repetitive block.

6.12.10 .exit

Syntax: .exit

Description:

Terminates the processing of the current repetitive block that begins with either a .repeat or .irp directive. Statements following this directive are read textually without being processed, until an .endr statement is encountered.

Example:

```
x := 1
.repeat
       .if
              \{x\} > 30
              .exit
       .endif
       .byte {x}
      x := \{ \{x\} * 2 \}
.endr
```

will generate the code

```
.byte
     1
.byte
      2
.byte 4
.byte 8
.byte 16
```

6.12.11 .macro_on and .macro_off

Description: The .macro_on and .macro_off directives enable and disable macro-procedure expansions, respectively, in selective parts of the source text.

Example:

```
addd
                   op1,op2
.macro
  bsr
         count additions
.macro_off
  addd
             {op1}, {op2}
.macro_on
.endm
```

the following macro-procedure call:

```
addd
       r1, r2
```

will generate:

```
count additions
bsr
addd
       r1, r2
```

6.12.12 .include

Syntax: .include included_file

is an existing file name where: included_file

The .include directive allows for the inclusion of text from another Description:

file as part of the file being assembled.

Example: .include filehdr.h

NOTE: If the *included_file* does not contain the full directory path of the file to be included, the assembler will search for it in either the current directory, or in a directory specified with the -MI invocation

option (macro include directory).

6.12.13 .mwarning

Syntax: .mwarning warning_message

The .mwarning directive generates an assembler warning message.

Example: xx := 222

.mwarning current value of "xx" is : {xx}.

.mwarning is used to write the current value of macro-variable xx to the listing output. The assembler will issue the following warning message:

Assembler (Macro-Processor): "filename.s" , line 2 , WARNING: current value of "xx" is : 222

6.12.14 .merror

Syntax: .merror error_message

Description: The directive .merror generates an assembler error message.

Example:

```
.merror
Wrong value used for addr "address"
```

The assembler will issue the following error message:

Assembler (Macro-Processor) Error: *filename.s*, line 1, statement is ==> .merror *err* Wrong value used for addr *address*<== ERROR: Wrong value used for addr *address*

6.13 PROCEDURE SUPPORT DIRECTIVES

The procedure support directives enable the definition of assembly procedures and an easy interface with other assembler or HLL procedures. The assembler procedure handling conforms to the GNX standard calling convention.

The procedure support directives are as follows:

Directive	Function
.proc	defines an ordinary procedure
.proct	defines a trap procedure
.proci	defines an interrupt procedure
.var	starts definition of local variables for procedure
.begin	starts the body of the procedure
.endproc	ends the procedure definition
.call	calls an assembler or an HLL procedure

6.13.1 .proc

Syntax:

.proc

Description:

The .proc directive starts an ordinary procedure definition. It marks both the definition point of the procedure and the beginning of the parameter block definition.

Example:

p1: .proc # define procedure, p1

. # procedure body

.endproc # ends procedure body

6.13.2 .proct

Syntax:

.proct

Description:

The .proct directive starts the definition of a trap procedure. The

body of a trap procedure is exited via the rett instruction.

Example:

trap_proc:

.proct

define trap procedure

.begin

starts body

.

trap procedure body

.endproc

exit via rett

6.13.3 .proci

Syntax:

.proci

Description:

The .proci directive starts the definition of an interrupt procedure.

The body of an interrupt procedure is exited via the reti instruction.

Example:

int_proc:

.proci

defines interrupt procedure

.begin

interrupt procedure body

starts body

.

.endproc

exit from int_proc here is t

the reti instruction

6.13.4 .var

Syntax: .var [reglist]

where: reglist is a list of the registers to be saved upon procedure

entrance and restored upon procedure exit. The registers are specified within brackets, and seperated by

commas.

Description: The .var directive starts the local variable block definition. It also

ends the parameter block definition started with the .proc, .proct or

.proci directives.

Example:

p1: .proc # starts definition of procedure, p1

par1: .blkd # a double-word parameter

.var [r4,r5] # starts local variable block description

var1: .blkd # a double-word variable
var2: .blkw # a two-byte variable
 .begin # starts procedure body

. # implied saving r4 and r5

•

. # procedure body

.

.endproc # ends procedure body

restoring r4 and r5 implied

6.13.5 .begin

Syntax:

.begin

Description:

The .begin directive begins the procedure body. It also ends the vari-

able block definition.

The .begin directive develops into an enter sequence for entering the procedure body, saving registers specified with the .var directive; and allocates stack area for the local variables.

Example:

```
p1:
       .proc
        .var [r2]
                        # a double-word variable
var1:
        .blkd
                        # a double-word variable
var2:
        .blkd
                        # starts procedure body
        .begin
                        # saves r2
                        # allocates 8 byte stack area for var1 and var2
                        # procedure body
        .endproc
                        # ends procedure body
```

6.13.6 .endproc

Syntax: .endproc[return_value[:return_size]]

where: return_value is an optional value to be returned from the procedure.

return_size is an optional size specification for the return_value. It

can be either of the specifications: b, w, d, f or l.

Description: The .endproc directive ends the procedure definition. It also marks the end of the procedure body and develops into an exit sequence from

it.

The exit sequence may prepare a return value; it releases stack area allocated for local variables; restores saved registers; and returns from the procedure using <code>cxp</code>, <code>rett</code> or <code>reti</code>, depending on the procedure type.

Example:

```
p1:
        .proc
                         [r3,r4,r5]
        .var
var1:
        .blkw
        .begin
                                     # starts procedure body
                                     # procedure body
        .endproc
                         var1:d
                                     # ends procedure body
                                     # prepares return value var1 in r0
                                     # releases stack area for var1
                                     # restores r3, r4, r5
                                     # returns to caller through the
                                        ret instruction
```

6.13.7 .call

Syntax: .call proc_name [param_1:x:y, ... param_n:x:y]

where: proc_name is the name of the procedure to be called.

param is an actual parameter for the called procedure.

x,y are size specifications for the actual and formal param-

eters, respectively. They can be any of the following

specifications: b, w, d, f, or l.

Description: The .call directive calls the procedure $.proc_name$ with the specified

parameters param_1 through param_n, adhering to the GNX standard

calling convention.

Example: .call cproc, r3:d, \$50:d

Calls procedure cproc with two double-word parameters: r3 and the immediate value: 50.

PROCEDURE SUPPORT

7.1 INTRODUCTION

A procedure is a sequence of instructions that can be called from several different places in a program. After a called procedure has finished executing, it returns control to the caller.

Assembly procedures can be defined and called within assembly code. Symbolic parameters and local variables may be defined and used within each assembly procedure, enabling easy, maintainable, and well structured assembly programming. The GNX Assembler conforms to the standard GNX calling convention, thus making the interface with high-level-language written code easy.

7.1.1 Procedure Operation

The following steps are performed in the call and execution of an assembly procedure:

- 1. The caller pushes parameters onto the stack.
- The caller passes execution control to the first instruction of the procedure.
- 3. The procedure saves the contents of the specified general purpose registers and allocates storage for the local variables on the stack.
- 4. The procedure's code is executed.
- 5. The procedure stores a possible return value in r0 or f0.
- 6. The procedure releases the storage allocated for local variables, restores the contents of the saved general purpose registers by popping them off the stack, and returns control to the caller.

7.2 PROCEDURE DEFINITION

Syntax:

```
procedure: procedure_head
          [parameter_block]
                         [reglist]
          [local_var_block]
          .begin
          [procedure_body]
          .endproc
                            [return value:[return size]]
```

where:

procedure

is an assembly label defining the procedure name.

Should appear within a text section.

If a double colon (::) is used instead of a single colon (:),

the procedure is defined as global.

procedure_head

begins the procedure definition. The directives .proct or .proci should be used for defining either an ordinary procedure, a trap pro-

cedure, or an interrupt procedure, respectively.

parameter_block

is a definition of the procedure's formal parameters. It consists of storage allocation statements of the form:

[param_name :] .blkx [block_size]

.blkx can be any storage allocation directive (.blkb,

.blkw, .blkd, .blkf, or .blkl).

.var

is a directive that specifies the beginning of the local

variable block.

reglist

is an optionally specified list of general purpose registers to be saved upon entering the procedure and

restored upon exiting.

local_var_block

is a definition of the procedure's local variables. It consists of storage allocation statements of the form:

[var_name :] .blkx [block_size]

.blkx can be any storage allocation directive (.blkb,

.blkw, .blkd, .blkf, or .blkl).

.begin sta	rts the	procedure	body.	It	generates	an	enter
------------	---------	-----------	-------	----	-----------	----	-------

sequence for register saving and local variables

storage allocation.

assembly statements that constitute the actual proprocedure_body

cedure code to be executed.

ends the procedure body. It generates an exit sequence .endproc

for releasing local variables, restoring saved registers,

and exiting the procedure.

return_value is an optional return value to the procedure.

return size is an optionally specified size for return_value. It can be

one of the following specifications: b, w, d, f, or l.

7.3 PROCEDURE TYPES

Three types of procedures are supported by the GNX assembler:

Ordinary procedures and functions

- Trap handler procedures
- Interrupt handler procedures

For each procedure type, a different exit instruction is generated when the .endproc directive is encountered.

Ordinary procedures or functions are specified by the .proc directive. They should be called with the bsr instruction. The exit sequence uses the ret instruction. When the assembler is invoked using the modularity option, the procedures should be called using the exp instruction, and the exp instruction is used instead of the ret instruction.

The trap handler procedure is specified by the .proct directive. The exit sequence uses the rett instruction.

The interrupt handler procedure is specified by the .proci directive. The exit sequence uses the reti instruction.

The GNX calling convention defines standards for using registers within different procedure types. These standards are discussed in detail in Section 7.7.

7.4 CALLING A PROCEDURE

A procedure can be called using the .call directive.

Syntax:

.call proc_name [,actual_param [:x[:y]],...]

where:

proc_name

is the name of the procedure to be called.

actual_param

is an actual value that is passed to the called procedure. It is any legal assembly expression. Each parameter can be either an integer or a floating-point.

х

is a size specification for an actual parameter. It can be either **b**, **w** or **d** for integer values; and either **f** or **l** for floating-point values.

tor mouning point (ar

y

is a size specification for the formal parameter as appears in the procedure definition. It can be either b, w or d for signed integer parameters; either ub, uw or ud for unsigned integer parameters; and either f or l for floating-point parameters.

For both integer and floating-point parameters, the size of the actual parameter must not be greater than the size of the formal parameter.

Description:

The .call directive develops into a calling sequence that prepares parameters on the stack and calls the procedure. A more detailed description follows below.

7.4.1 The Calling Sequence

In the normal calling sequence, parameters are pushed on top of stack (tos) using the mov instructions, the procedure is called using a call instruction, and on the return from the call the parameters are released from the stack using the adjsp instruction.

This sequence is generated when either optimization is off, or when optimization is on but the .call directive appears outside a procedure definition.

Example:

```
The call
```

```
.call cmul, opd1:b:d, opd2:f:1
```

develops into

```
movfl opd2, tos
                         # prepare opd2
                         # prepare opd1
movxbd opd1, tos
                         # call cmul
       cmu1
adispb $-12
                         # release parameter storage from stack
```

7.4.2 Optimizing the Calling Sequence

The generated calling sequence can be optimized using the assembler optimization option (-O on UNIX, /OPTIMIZE on VMS). Optimized code is generated based on the location of the .call directive in your program code.

When the .call directive appears inside a procedure definition, a special scratch area is allocated on the top of stack upon entrance to the procedure containing the call. The .call directive moves parameters into the special scratch area using mov instructions and calls the procedure. The scratch area is released only upon exit from the procedure containing the call. This reduces the number of adjsp instructions normally generated for each procedure call to a minimum, thereby improving performance.

Example:

The call

```
.call cmul, opd1:d, opd2:d
```

develops into

```
# at this point, scratch area of at least 8 bytes
# should be allocated on top of stack.

movd opd2, 4(sp) # prepare opd2
movd opd1, 0(sp) # prepare opd1
bsr cmul # call cmul
# scratch area should be released from the top
# of stack later on.
```

Note: Use of the debug invocation option (-g on UNIX, /DEBUG on VMS) suppresses procedure optimization since there is no frame when optimization is on.

7.4.3 Passing Parameters

Parameters are prepared on top of stack, from right to left (i.e., last specified actual parameter is innermost from top of stack). Parameters are prepared on the stack according to the parameters' sizes as specified with the .call directive. No implicit stack alignment is done by the assembler. If the formal parameter size (y) is not specified, it is assumed to always be the same as the actual parameter size (x). When no size is specified for a parameter, the default \mathbf{l} is used for immediate floating-point values; the default \mathbf{d} is used for any other value.

Example:

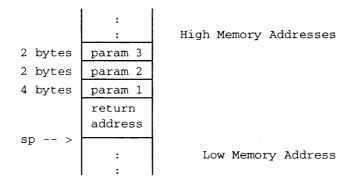
The call

```
.call cproc, var1:d, var2:w, var3:b:w
```

develops into

```
movxbw var3, tos # push var3 on top of stack
movw var2, tos # push var2 on top of stack
movd var1, tos # push var1 on top of stack
bsr cproc
```

After cproc is called using the bsr instruction, the stack layout is



You must ensure type and size consistency between actual parameters specified for the .call directive and the corresponding formal parameters in the procedure definition. Further, you must verify that when interfacing HLL written procedures, integer parameters are double-word aligned, and float parameters are 8-byte aligned, as defined by the standard GNX calling convention (see Appendix E).

Example:

Calling the HLL printf procedure:

```
print_byte:
               .proc
byte_param:
               .blkb
                            # a one byte parameter
               .begin
                            # printf expects aligned parameters
               .call _printf, $format_string: d, byte:b:ud
               .endproc
               .data
format_string: .ascii "%d\n\0"
```

7.4.4 The Call Instruction

The call instruction generated for the .call directive is dependent on the assembler invocation line. If the modularity option is specified (-X on UNIX, /MODULAR on VMS), the exp instruction is generated. Otherwise, the bsr instruction is generated.

Example:

The call

.call cproc

normally uses the bsr instruction

bsr cproc

When using 32000 modularity, the .call directive uses the cxp instruction

cxp cproc

7.5 THE PARAMETER BLOCK

The parameter block defines formal parameters for the procedure. It consists of storage allocation statements. Each statement either defines a parameter or is an alignment statement.

Syntax for parameter definition:

param_name : .blkx [expression]

Syntax for an alignment statement:

{.blkx, .align, .space} [expression]

where: param_name is an assembly label defining a parameter name.

.blkx can be any storage allocation directive (.blkb,

.blkw, .blkd, .blkf, or .blkl).

Description: Parameter definitions and alignment statements constitute the parame-

ter block. All parameter definitions and alignment statements must be specified as one contiguous block between the <code>.proc</code> and the following procedure directive (the <code>.var</code> or <code>.begin</code> directives). This block should

not be broken by any other segment.

Each parameter has a size and type associated with it, based on the storage allocation directive specified. The following storage allocation directives are used:

- .blkb specifies a one byte integer.
- .blkw specifies a two byte integer.
- .blkd specifies a four byte integer.
- .blkf specifies a four byte (single-precision) floating-point.
- .blkl specifies an eight byte (double-precision) floating-point.

Example:

```
par1:
       .blkw
                    # 2-byte integer parameter named par1.
                    # align par1 to double-word.
       .align
                    # 4-byte floating-point parameter named par2.
par2:
       .space 4
                    # align par2 to quad-word.
                    # 4-byte integer parameter named par3.
       .blkd
par3:
ERROR in line number 441 incorrect number of fields
line is: .if
```

7.5.1 Parameter Allocation

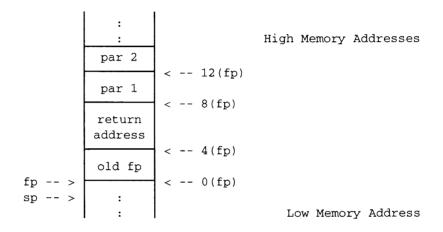
Parameters are allocated on the stack by the caller; the right parameter is located intermost from the top of stack. The assembler addresses the parameters as either sprelative or fp-relative addresses.

Normally, the assembler uses the fp-relative addressing mode. When invoked with the optimization option (-O on UNIX, /OPTIMIZE on VMS), the assembler uses the sprelative addressing mode since the frame is not used. When the debug option (-g on UNIX, DEBUG on VMS) is used together with the optimization option, procedure optimization is suppressed and the fp-relative addressing mode is used.

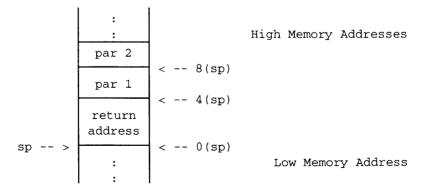
Example:

For the procedure definition

par1 is normally addressed as 8(fp). The stack layout is



When procedure optimization is on, par1 is addressed as 4(sp). The stack layout is



Refer to Section 7.9 for more details on stack usage.

7-10 PROCEDURE SUPPORT

7.5.2 Parameter Alignment

You must ensure type and size consistency between formal parameter definitions and the corresponding actual parameters as specified in the procedure call.

The assembler does not implicitly align each of the procedure parameters. When interfacing HLL code, it is your responsibility to align integer parameters to double-word and floating-point parameters to eight byte addresses on the stack, as defined by the GNX standard calling convention (see Appendix E).

Example:

Calling an assembly procedure from a C module

```
c = ' \setminus 1';
short
        s = 2;
        i = 3;
int
      f = 4.0;
float
double d = 5.0
c_func ( )
         asm_proc (c,s,i,f,d);
}
```

The corresponding assembly procedure definition is

```
_asm_proc::
                 .proc
par_c:
                 .blkd
                                 # aligned to double-word
par_s:
                 .blkd
                                 # aligned to double-word
par_i:
                                 # aligned to double-word
                 .blkd
                                  # aligned to long float
par_f:
                 .blkl
par_1:
                 .blkl
                                 # aligned to long float
                 .var
                 . . .
                 .begin
                 any user code
                 .endproc
```

7.5.3 Parameter Block Size

After a parameter block has been defined, the parameter block size value is available through the predefined variable param size. This value can be used throughout the procedure's definition, starting with the .var directive through the .endproc directive.

7.5.4 Parameter Scope

Parameters can only be referenced within the body of the procedure in which they are defined. Procedure parameters need not be uniquely named among different procedures.

7.6 THE VARIABLE BLOCK

The variable block defines the local variables for the procedure. It consists of storage allocation statements. Each statement defines a parameter or is an alignment statement.

Syntax for variable definition:

.blkx [expression] var_name:

Syntax for an alignment statement:

{.blkx, .align, .space} [expression]

where: is an assembly label that defines the local variable var_name

name.

.blkxcan be any storage allocation directive (.blkb,

.blkw, .blkd, .blkf, or .blkl).

Description: Variable definitions and alignment statements constitute the variable

block. All variable definitions and alignment statements must be specified as one contiguous block between the .var and the .begin directives. This block should not be broken by any other segment. If

the procedure has no variables, the .var directive can be omitted.

Each variable has a size and type associated with it, based on the storage allocation directive specified. The following storage allocation directives are used:

- .blkb specifies a one byte integer.
- .blkw specifies a two byte integer.
- .blkd specifies a four byte integer.
- .blkf specifies a four byte (single-precision) floating point.
- .blkl specifies an eight byte (double-precision) floating point.

Example:

```
var1:
        .blkw
                      # 2-byte integer variable named var1.
        .align 4
                      # align to double-word.
var2:
        .blkb
                      # 1-byte integer variable named var2.
        .align 4
                      # align to double-word.
        .blkf
                      # 4-byte floating-point variable named var3.
var3:
```

7.6.1 Variable Allocation

Local variables are allocated on the stack upon entering the procedure body; the first variable is located intermost from the top of stack. The assembler addresses them as either sp-relative or fp-relative addresses.

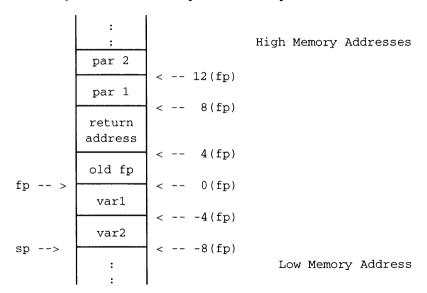
Normally, the assembler uses the fp-relative addressing mode. When invoked with the optimization option (-O on UNIX, OPTIMIZE on VMS), the assembler uses the sprelative addressing mode since the frame is not used. When the debug option (-g on UNIX, DEBUG on VMS) is used together with the optimization option, the procedure optimization is suppressed and the fp-relative addressing mode is used.

Example:

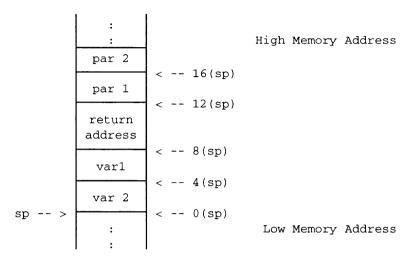
For the procedure

p1: .proc
par1: .blkd
par2: .blkd
 .var
var1: .blkd
var2: .blkd
 .begin
 .endproc

var1 will normally be addressed as -4(fp). The stack layout will be



When the procedure optimization is on, var1 will be addressed as 4(sp). The stack layout will be



Refer to Section 7.9 for more details.

7.6.2 Variable Alignment

The assembler does not implicitly align each of the procedure variables. It is your responsibility to align local variables according to your target bus width in order to achieve better performance at run time. However, the whole variable block is always double-word aligned.

Note that the assembler assumes the stack is properly aligned upon entering a procedure. Therefore, you must ensure the proper alignment of parameters before entering the procedure.

Example:

```
.var
var1
        .blkw
                        # allocates 2 bytes for var1
var2:
       .blkb
                        # allocates 1 byte for var2
        .begin
```

The complete variable block will occupy 4 bytes since it is double-word aligned.

7.6.3 Variable Block Size

After a variable block has been defined, the variable block size value is available through the predefined variable var_size. This value can be used throughout the procedure's body, starting with the .begin directive through the .endproc directive.

7.6.4 Variable Scope

Variables can only be referenced within the body of the procedure in which they are defined. They need not be uniquely named among different procedures.

7.7 REGISTER USAGE

There is no special support for the usage of registers within a procedure. Registers may be used throughout the procedure, provided they are used consistently, and saved and restored when necessary.

When using the GNX standard calling convention, certain rules apply for the use of registers. Volatile registers (r0-r2, f0-f3) can be freely modified within an ordinary assembly procedure; non-volatile registers (r3-r7, f4-f7) should be saved when a procedure is entered if they are to be modified. This also means that before calling a procedure that conforms to the GNX calling covention:

- 1. You should save volatile registers whose values you wish to keep, since they may be changed in the called procedure.
- 2. You do not need to save non-volatile registers, since they are guaranteed to be saved in the called procedure.

Both volatile and non-volatile registers should be saved when entering a trap or an interrupt procedure if they will be modified within the procedure (see Appendix E for a complete description of the GNX calling convention).

You should save registers when entering a procedure, and restore them when exiting a procedure, by using the *reglist* option of the .var directive.

Syntax:

.var [reglist]

where: reglist is a list of registers to be saved upon procedure

entrance (.begin) and to be restored upon procedure exit (.endproc). The registers are specified within

brackets, and separated by commas.

Description:

The assembler uses the enter or save instruction for saving registers and the exit or restore instruction for restoring registers, depending on the assembler invocation options (for details see Sections 7.8.1 and 7.8.3).

Example:

For the following assembly procedure

```
Preg: .proc
.var [r4,r5]
.begin
addd r0,r1
subd r1,r4
muld r0,r5
.endproc
```

r4 and r5 are saved when the .begin directive is encountered, and restored when the .endproc directive is encountered. The actual code is

```
enter [r4,r5], $0  # save r4,r5
addd     r0,r1
subd     r1,r4
muld     r0,r5
exit [r4,r5]  #restore r4,r5
```

7.8 THE PROCEDURE BODY

The procedure body is constructed from assembly statements between the .begin and .endproc directives:

```
.begin

[procedure_body]

.endproc [return_value[:return_size]]
```

7.8.1 Entering a Procedure Body

The .begin directive starts the procedure body. It develops into an enter sequence that saves the registers specified with the .var directive and allocates space for local variables on the stack. In the case of procedure optimization, the enter sequence allocates an additional scratch area on the stack for optimization purposes (as described below).

The assembler generates different enter sequences depending on the specified invocation options. Normally, the assembler generates an enter sequence that enables using the frame within the procedure body. Local variables are allocated on the frame and the *reglist* registers are saved on the stack using the enter instruction.

Example:

In the assembly procedure p1

```
p1: .proc
par1: .blkd
.var [r4]
var1: .blkd  # local variable var1
.begin
addr var1,r4
.endproc r4:d
```

the .begin directive develops into

```
enter [r4],$4  # allocate stack frame area for var1  # and save register r4
```

When invoked with the optimization option, the assembler does not use the frame. Rather, the *reglist* registers are saved using the save instruction, and local variables are allocated using the adjsp instruction. In addition, if the procedure contains calls to other procedures using the .call directive, the same adjsp instruction allocates an additional scratch area for passing parameters to the subsequent calls.

Example:

In the assembly procedure p2

```
p2:
         .proc
        blkd
par1:
                     [r4]
         .var
var1:
         .blkd
         .begin
         addr
                     var1, r4
         .call
                    p1, par1:d, r4:d
         .endproc
                     var1:d
```

The begin directive develops into

```
save
        [r4]
                # save register r4
adispw $12
                # allocate stack area for var1 (4 bytes) and scratch
                  area for passing the 2 parameters to p1 (8 bytes)
```

7.8.2 Within a Procedure Body

The procedure body should contain assembly statements for execution. Such statements can symbolically reference the procedure's parameters and local variables. They can also reference global symbols. No symbolic reference is allowed to local parameters or variables of a different procedure.

Both symbolic references to parameters and local variables are interpreted as references to their addresses on the stack. These addresses may be fp-relative or sp-relative (see Sections 7.5.1 and 7.6.1).

When procedure optimization is on, the assembler assumes a fixed stack-pointer value throughout the procedure body. This value is used for referencing parameters and local variables as sp-relative addresses. Therefore, when using the optimization option. you should not alter the stack-pointer value within the procedure body (by using either the adjsp, save, restore, enter, exit instructions or the tos adressing mode).

Registers can be used throughout the procedure body as described in Section 7.7.

Transferring control from one procedure to another should be done using the .call directive. Nested procedure definition is illegal. The procedure body may be broken up by other segments.

7.8.3 Exiting a Procedure Body

The . endproc directive is provided for exiting a procedure.

Syntax:

.endproc [return_value [:x[:y]]

where: . endproc marks the end of procedure body and exits from it.

return_value is an optional value to be returned from the procedure.

x is a size specification for the source of the return value.

It can be either b, w or d for integer values; and either

f or I for floating-point values.

is a size specification for the destination of the return value. It can be either b, w or d for signed integer values; either ub, uw or ud for unsigned integer values;

and either f or I for floating-point values.

For both integer and floating-point values, the source size must not be greater than the destination size.

Description:

y

The .endproc directive ends the procedure body. It develops into an exit sequence for releasing the stack storage that was allocated upon procedure entrance. The .endproc directive also restores saved registers and returns from the procedure.

If a return_value is specified, a code preparing the return value precedes the exit sequence. The return value is prepared either in r0, f0, or 10 according to the standard calling convention. Integer values are returned in r0. Floating-point values are returned either in f0 or 10.

Note that registers are restored after the *return_value* is prepared. Therefore, the return value will be lost if r0 is one of the restored registers (e.g. specified in *reglist* with the .var directive). Also note that when a floating point value, beeing a part of a HLL expression, is returned as a single-precision value in f0, it is expanded to a double-precision value by the HLL code after returning from the assembly procedure.

The assembler generates different exit sequences depending on the specified invocation option. Normally, the assembler prepares *return_value* in r0, f0, or 10 restores saved registers and releases the frame using the exit instruction, and returns from the procedure using a return instruction.

The return instruction generated for the exit sequence is dependent on the procedure type and the assembler invocation options. The ret instruction is generated for ordinary non-modular procedures. The rxp instruction is generated for ordinary modular procedures. The rett instruction is generated for trap procedures. The reti instruction is generated for interrupt procedures.

Example:

In the assembly procedure p1

```
p1:
        .proc
        .blkd
par1:
        .var
                  [r4]
var1:
        .blkd
                              # local variable var1
        .begin
        addr
                  var1,r4
        .endproc r4:d
```

the .endproc directive develops into

```
movd
        r4, r0
                        # prepare return value r4 in r0
                        # restores r4 and releases frame
exit
        [r4]
                        # returns to caller
ret
```

When invoked with the optimization option, the assembler prepares return_value in r0 or f0, releases the allocated stack storage (including both the local variables and the scratch area storage) using the adjsp instruction. The assembler restores saved registers using the restore instruction, and returns from the procedure using the return instruction.

Example:

In the assembly procedure p2

The .endproc directive develops into

7.9 STACK USAGE

Normally within a procedure body the stack layout will be

1		Ī			
	:				
	:		High	Memory	Address
	caller				
parameters	last arg	positive			
	1	offsets of			
	first arg	fp			
	[mod/psr]	-			
return block	return pc				
	saved fp				
fp >	-	< 0(fp)			
-F	first local var	(
local	:	negative offsets			
variables	:	of fp			
	last local var	-			
	saved registers				
sp >					
	:		Low	Memory	Address
	:				

Parameters are prepared before calling the procedure, and are referenced within the procedure body as fp-relative addresses (offset (fp), offset being positive).

The return block is created by the call, save and adjsp instructions. When Series 32000 modularity is used or in cases of trap or interrupt procedures, the mod and psr values (which are a total of four bytes), are pushed on the stack.

The procedure enter sequence save registers on stack. Local variables are allocated on the stack by the enter sequence, and are referenced within the procedure body as fprelative addresses (offset (fp), offset being negative).

When procedure optimization is on, the stack layout will be

	:
	:
	caller
parameters	last arg
	1
	first arg
	[mod/psr]
return block	return pc
	saved registers
	first local var
local	l
variables	1
	last local var
	scratch area
sp >	
	:
	:

The frame is not used in this layout. Parameters are prepared before calling the procedure and are referenced within the procedure body as sp-relative addresses.

The return block is created by the call, save and adjsp instructions. When Series 32000 modularity is used or in cases of trap or interrupt procedures, the mod and psr values (which are a total of four bytes), are pushed on the stack.

The procedure enter sequence saves registers on stack. Local variables are allocated on the stack by the enter sequence, and are referenced within the procedure body as sp-relative addresses.

The scratch area is a special stack storage. It is allocated once upon entering the procedure body, and released when the procedure body is exited. The scratch area is used for passing parameters to other procedures called with the <code>.call</code> directive. Therefore an area does not have to be allocated and released each time a subsequent procedure is called.

7.9.1 Sample Assembly Procedure

The procedure

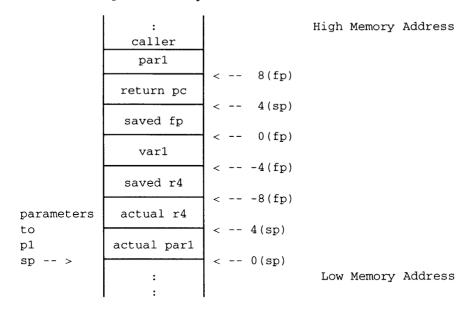
```
xproc: .proc
        .blkd
par1:
        .var [r4]
        .blkd
var1:
        .begin
        addr var1, r4
        .call p1, par1:d, r4:d
        .call p2, $100:d
        .call p3, $20:d, r0
        .endproc var1:d
```

will normally expand to

```
enter
       [r4], $4
                       # save r4, allocate frame
addr
       -4(fp), r4
movd
       r4, tos
                       # push r4
movd
       8(fp), tos
                       # push par1
bsr
       p1
                       # call p1
adjspb $-8
                       # releases parameter area of par1
                        # push immediate value 100
movd
       $100, tos
                        # call p2
bsr
       p2
adjspb $-4
                        # release parameter area of p2
movd
       r0, tos
                        # push r0
movd
       $20, tos
                        # push immediate value 20
                        # call p3
bsr
       p3
adjspb $-8
                        # release parameter area of p3
     r0, -4(fp)
                        # update var1
addd
       -4(fp), r0
                        # prepare return value of r1
movd
exit
       [r4]
                        # restore r4, release frame
                        # return
        $0
ret
```

In this example, an adjsp instruction is generated for every procedure called with parameters within the xproc procedure.

Just before the bsr to p1 the stack layout will be

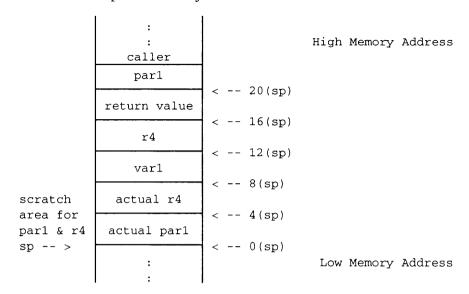


When procedure optimization is on, the procedure will expand to

```
xproc:
       .proc
par1:
        .blkd
        .var [r4]
var1:
        .blkd
        save
                [r4]
                                 # save r4
        adjspw $12
                                 # allocate var1 and scratch area on stack
        addr
                8(sp), r4
                r4, 4(sp)
                                 # pass r4 to p1
        hvom.
                20(sp), 0(sp)
                                 # pass par1 to p1
        movd
        bsr
                p1
                                 # call p1
                $100, 0(sp)
                                 # prepare immediate value 100
        Dvom
                                 # call p2
        bsr
                p2
        movd
                r0, 4(sp)
                                 # prepare r0
                                 # prepare immediate value 20
                $20, 0(sp)
        movd
                                 # call p3
        bsr
                p3
        addd
                r0, 8(sp)
                                 # update var1
                                 # prepare return value of var1
        movd
                8(sp), r0
        adjspw $-12
                                 # restore stack area
        restore [r4]
                                 # restore r4
                $0
                                 # return
        ret
```

In this example, adjsp instructions are generated only for the entrance to and exit from the xproc procedure.

Just before the bsr to p1 the stack layout will be



MACRO AND CONDITIONAL ASSEMBLER

8.1 INTRODUCTION

The GNX macro-assembler makes writing assembly programs easier. It eliminates the need to rewrite similar assembly source code repeatedly, and simplifies program documentation. The conditional assembler feature allows for the inclusion or deletion of optional assembly statements. Other macro-assembler features help minimize programming errors and speed the development process.

The macro-assembler is automatically invoked by the assembler.

The macro-assembler described in this chapter is a completely new element for the GNX Version 4 Assembler. It is characterized by powerful and flexible features. This new macro-assembler is not compatible with the previously supplied macro-assembler (from Version 2.0 and up).

For compatibility purposes, the Version 2 macro-assembler is still supported in this release (but will be obsolete in Version 5). However it must now be invoked by the -MC invocation option for the UNIX environment, and by the MCOMPATIBILITY invocation option for the VMS environment. See Appendix F for details.

8.1.1 Overview of the Major Macro-Assembler Features

The GNX macro-assembler supports the following features:

• Macro-procedures ("macros")

A macro-procedure is equivalent to the common term "macro". For example, for the following macro-procedure:

```
.macro move_bytes source, dest, length
        [r0,r1,r2]
save
movd
        ${length},r0
addr
        {source},r1
addr
        {dest},r2
movsb
restore [r0,r1,r2]
.endm
```

the macro-procedure calls:

```
move_bytes aa,12(-8(fp)),1024
move_bytes 0(fp)[r7:b],0(r5),512
```

will generate the code:

```
save
        fr0,r1,r21
movd
        $1024.r0
addr
        aa,r1
        12(-8(fp)),r2
addr
movsb
restore [r0,r1,r2]
        [r0,r1,r2]
save
movd
        $512,r0
addr
        0(fp)[r7:b],r1
addr
        0(r5), r2
movsb
restore [r0,r1,r2]
```

This feature is fully described in Section 8.10.

• Conditional Code Generation

Code may be generated according to conditions tested in the macro-assembly phase. For example the sequence:

```
.if (STR_EQ [(GNX_FPU), ns32381])
    logbf f1, f2
.else
    movf f2, tos
    movf f1, tos
    bsr _sqrtf
    adjspb $-8
    movf f0, f2
.endif
```

will generate code using the logbf opcode if the predefined variable GNX_FPU holds the value 32381. Otherwise a calling sequence to the subroutine _sqrtf will be generated.

This feature is fully described in Section 8.8.

Macro Variables

String values may be assigned to macro-variables. These variables may be later utilized in place of the string value. For example:

```
base_reg:= r0
movqd 0, 0((base_reg))
```

is equivalent to:

```
movqd 0, 0(r0)
```

This feature is fully described in section 8.4.

• Repetitive Code Generation

This feature allows for the easy repetition of sequences of statements, by specifying either:

- the number of repetitions, as for example

```
.repeat 3, index
.align
       4
.word
        {index}
.endr
```

which is equivalent to the code

```
.align
.word
        1
.align 4
.word
        2
.align
        4
.word
        3
```

- or a repetition list

```
.irp
        val, [25,3,1989]
.align
.word
        {val}
.endr
```

which is equivalent to the code

```
.align
.word
       25
.align
       4
.word
       3
.align
.word
       1989
```

This feature is fully described in section 8.9.

Text Inclusion

Text from another file may be included as part of the file being assembled. For example:

```
.include
           useful.definitions
```

will place code that is the contents of file useful.definitions.

This feature is fully described in section 8.12.

Listing of Expanded Code

A listing output may be produced to display all expanded code. The listing output can be generated after either the macro-processing phase or after the second phase of the assembly process.

This feature is fully described in section 8.3.

• User Error and Warning Messages

Error and warning messages can be issued by the user. For example, given the following macro:

```
.macro check_reg_number reg_number
.if (reg_number) > 7
    .merror invalid register number specified.
.endif
.endm
```

the call:

```
check_reg_number 10
```

will result in the error message:

```
Assembler (Macro-Processor) Error:

"filename.s", line 4, statement is ==> .merror invalid register number specified<==
... from line 9: while calling "check_reg_number" with "ARG_LIST"=(10)
```

 ${\bf ERROR:} \quad \text{invalid register number specified}$

These features are fully described in section 8.13.

Arithmetic Operations and Expressions

Arithmetic operations and expressions (including arithmetic comparisons) can be performed on constants and variables.

For example, assuming the macro-variable \times holds the string value 100, the statement:

```
result:= \{(x) * (\{x\} - 1)\}
```

is processed by the macro-assembler so that the macro-variable result will hold the string value 9900.

Arithmetic operations and expressions are fully described in section 8.5.

Built-in Macro Functions

Built-in macro-functions provide the following capabilities:

1. Manipulation of strings. For example

```
{SUB_STR[abcde, 2, 3]}
```

is equivalent to the string bcd.

2. Manipulation of macro-lists (special strings used for implementing complex data structures). For example:

```
reg_list:=(sublist[[R1,R5,R7],2,2])
```

sets reg_list to hold R5 and R7.

- 3. Integer and floating-point conversions.
- 4. Manipulation of NS32000 instruction operand strings. For example

```
{OP_INDEX_REG[xx+9(sp)[r3:b]]}
```

is evaluated as a string specifying the index register r3.

8.2 THE MACRO-PROCESSING PHASE

Assembly source text is processed by the assembler in two distinct phases: the macroprocessing phase and the assembly phase.

The macro-processing phase involves the reading and processing of source text statement by statement. Strings between braces ({}) are handled and replaced with the appropriate value. If the resulting statement is a macro-directive statement or a macro-procedure call it is acted upon. All other statements are not processed by the macro-processor and are passed directly to the assembly phase.

The assembly phase is performed in two passes and generates the appropriate output files.

A more detailed explanation of the various stages of the macro-processing follows below.

A string between braces is handled as follows:

- · A macro-variable name is replaced with the current value of the variable. For example, if the variable a holds the value xxy 100, then {a} is replaced by xxy 100.
- An arithmetic macro-expression is evaluated and replaced with the result. For example, $\{100*(10+10)\}$ is replaced by 2000.
- A built-in macro-function call is evaluated and replaced by the result. For example, {STR_LEN[abcde]} is replaced by 5.
- All other braced strings cause an error message to be issued.

Pairs of braces may be nested, in which case the string contained by the inner pair of braces is evaluated and replaced first.

For example, assuming the macro-variable op holds the value r2 ,then the following statement

```
movd $0,r{ (SUB_STR[ {op}, 2, 1]) + 4}

will be replaced by

movd $0,r6

- First, {op} is replaced by r2.

- Then, the function call {SUB_STR[r2, 2, 1]} is replaced by 2.

- Finally, {2 + 4} is arithmetically evaluated and replaced by the resulting string 6.
```

Braces are not processed in the macro-processing phase if they appear within either an ascii constant (such as " $\{1+1\}$ ") or a character constant (such as ' $\{'\}$).

A statement followed by a backslash (\) before a carriage-return (<CR>) is concatenated with its previous statement. The statements are then treated as a single statement (any number of lines may be concatenated in this way). This does not apply to comments. Comments will be terminated by a carriage return (<CR>) even if preceded by a backslash (\). This feature may be used in macros for breaking complex expressions into several lines. All error messages refer to the first concatenated statement.

Macro-directives and macro-procedure calls are handled as follows:

- When the opcode field is the name of a previously defined macro-procedure, the statement is considered a macro-procedure call.
 The statements in the macro-procedure body are processed, as if they were encountered at this point, after matching the actual arguments with the formal arguments of the macro-procedure.
- When the statement is of the form "symbol := value", the statement is considered a
 macro-variable assignment.
 The variable statement on the left side of the := is assigned the value specified on
 the right side.
- When the opcode field is a .macro directive, the statement is considered a macro-procedure definition.
 The statements following the .macro directive, but before the .endm directive, are read textually without being processed and are stored internally.
- When the opcode field is an .if directive, a conditional block is began.

 Statements following a true clause are processed; statements following an untrue clause are read textually without being processed and are discarded.
- When the opcode field is a .repeat or a .irp directive, a repetitive block is begun. The statements of the block are repetitively processed, according to the
- 8-6 MACRO AND CONDITIONAL ASSEMBLER

operands of the .repeat or .irp directive.

 When the opcode field is a .include directive, the specified file is read and processed

8.3 INVOCATION

Several aspects of macro-processing can be controlled by assembler invocation options. The following table presents these specific options:

FLAG (VMS)	FLAG (UNIX)	DEFINITION
/MCOMPATIBILITY /MDEFINE= (name[=def][,]) /MLIBRARY= (libname[,])	-MC -MDname or -MDname=def -MLfilename	Invokes the Version 3 macro-assembler. Defines name to macro assembler as if by macro assignment statement. Includes macro library file.
/MINCLUDE= (directory[,])	-MI <i>dir</i>	Specifies an include search directory.
/MONLY	-MO	Invoke only macro-processing phase.
/MPRINT=filename	-MPfilename	Prints the macro-processing output.

When the -MC option (/MCOMPATIBILITY on VMS) is used, version 4 macro-processing is suppressed. The old, version 3, macro-assembler is used instead. If this option is specified, it may not be combined with the other macro options described here.

The -MD option (MDEFINE on VMS) assigns an initial value to a macro variable.

The -ML option (/MLIBRARY on VMS) includes an already existing macro-library. A macrolibarary is any valid assembly file using the Version 4 macro-assembler features; as described in Section 8.12 for the included file of the .include directive.

The -MI option (/MINCLUDE on VMS) sets a search directory for included files. The assembler searches for .include files which do not begin with a slash (/) (or an open bracket ([) on VMS), in the directory of the specified input file first, then in the directory named in this option.

The -MO option (MONLY on VMS) invokes only the macro-processing phase of the assembler.

The -MP option (MPRINT on VMS) causes the assembler to print the macro-processor's output to filename. If filename is not given, the output is written to standard output on UNIX, or a .mac file on VMS.

8.4 MACRO VARIABLES

Macro-variables are variables that are active only during the macro-processing phase.

The name of a macro-variable may be any assembly symbol as defined in section 2.5, *i.e.* a sequence of letters, digits, underscores (_) and periods (.). The first character may not be a digit. A period (.) should not be used as the first character of the variable name since it may be confused with a directive name.

The initial value of any macro-variable is the empty string, unless it has been assigned a value on the invocation line (see section 8.3) through the -MD macro invocation option (/MDEFINE on VMS). Generally a macro-variable is assigned a value by the user through a macro-variable assignment statement.

The value of an undefined variable is the empty string.

Syntax: $macro_var := [value]$

Description: This assigns the value of the macro variable value to macro_var, after strip-

ping leading and trailing blanks. If value is omitted, an empty string is

assigned to macro var.

A macro-variable is substituted with its current value when its name is enclosed within braces.

Syntax: { macro_var }

Examples:

1. AAA := 5+5

assigns the string value 5+5 to the macro-variable AAA.

2. XXX := 7 XXX := {XXX}+1

assigns the string value 7+1 to the macro-variable XXX.

3. XXX := 7 $XXX := (\{XXX\} + 1\}$

assigns the value 8 to the macro-variable XXX.

4. VAR_NAME:= XXX {VAR_NAME} := 7

assigns the value 7 to the macro-variable XXX.

```
5. EEE := eee
   FFF := fff
   LLL := [ ddd, {EEE}, {FFF}, ggg]
```

assigns the value of the macro-list [ddd, eee, fff, ggg] to the macro-variable LLL.

8.5 ARITHMETIC MACRO-EXPRESSIONS

An arithmetic macro-expression is a string whose contents are a legal combination of integer constants, arithmetic operators, comparison operators and parentheses. This string can be evaluated as an integer value.

Examples of various arithmetic macro-expressions are:

- 1. 1000
- 2. 20+8*(3/2)
- 3. assuming that the value of a is 50 and that the value of b is +, then:

```
{a} {b} 27
```

is also a legal arithmetic macro-expression (equivalent to 50 + 27).

When an arithmetic macro-expression is enclosed between braces or used in an arithmetic context (for example, the clause of a .if / .elsif directive or as the first operand of a .repeat directive), it is evaluated by the macro-processor and substituted with a string representing its value. This string contains an integer constant in signed decimal notation with no leading blanks. Arithmetic macro-expressions are evaluated and converted by the macro-assembler to a 32-bit signed integer representation. All arithmetic operations are performed on 32-bit signed integer operands, and also return a 32-bit integer value.

Each arithmetic macro-operator in a macro-expression has a level of precedence. This determines the macro-expression's order of evaluation. Table 8-1 lists all the macrooperators and their precedence for evaluation.

The user must follow these rules when writing arithmetic macro-expressions:

- 1. All unary operators must precede a single term and cannot be used to separate two terms.
- 2. All binary operators must separate two terms. For example, the macroexpression 8*4 is legal, but 8**4 is illegal.

Table 8-1. Macro Operator Precedence

PRECEDENCE	OPERATOR	NAME	DESCRIPTION OF OPERATIO		
Unary Operator					
1 1	- ~	Unary minus Unary complement	Two's complement (= negation). One's complement.		
Binary Operator					
2	*	Multiply	Multiply 1st term by 2nd term.		
2	/	Divide	Divide 1st term by 2nd term.*		
2	%	Modulus	Remainder from 1st term divided by 2nd term.**		
2	<<	Shift left	Shift 1st term by 2nd term; emptied bits are zero-filled.		
2	>>	Shift right	Shift 1st term by 2nd term; emptied bits are zero-filled.		
2	~	Logical OR /	Bit-wise OR of 1st term and one's		
		complement	complement of 2nd term.		
3	& &	Logical AND	Bit-wise AND of 1st and 2nd terms.		
3	1	Logical OR	Bit-wise OR of 1st and 2nd terms.		
3	^	Logical XOR	Bit-wise XOR of 1st and 2nd terms.		
4	+	Add	Add 1st and 2nd terms.		
4	-	Subtract	Subtract 2nd term from 1st term.		
5	=	Equal	1 if 1st and 2nd terms are equal, 0		
5	<>	Not Equal	1 if 1st and 2nd terms are not equal, 0 otherwise		
5	>	Greater Than	1 if 1st term is greater than 2nd term, 0 otherwise		
5	<	Less Than	1 if 1st term is less than 2nd term, 0 otherwise		
5	>=	Greater or Equal	1 if 1st term is greater than or equal to 2nd term, 0 otherwise		
5	<=	Less or Equal	1 if 1st term is less than or equal to 2nd term, 0 otherwise		

^{*} Rounds toward 0, e.g., -7/3 = -2 and 7/3 = 2 ** e.g., -7/3 = -1 and 7/3 = 1.

- 3. Compound macro-expressions are valid. A macro-expression may be constructed from other macro-expressions using unary and binary operators. For example, the two individual macro-expressions (A)+1 and (B)+2 may be combined with a multiply operator and parentheses to form the single macro-expression $(\{A\}+1)*(\{B\}+2)$. Note that the parentheses override the default precedence rules.
- 4. Evaluation of a macro-expression is governed by three factors:
 - Parentheses macro-expressions enclosed in parentheses are evaluated first. For example, $\{8/4/2\}$ is evaluated as 1, but $\{8/(4/2)\}$ is evaluated as 4.
 - Precedence Groups an operation of a higher precedence group is evaluated before an operation of a lower precedence group whenever parentheses do not otherwise determine the evaluation order. For example, $\{8+4/2\}$ is evaluated as 10, but $\{8/4+2\}$ is evaluated as 4.
 - Left to Right Evaluation macro-expressions are evaluated from left to right whenever parentheses and precedence groups do not determine evaluation order. For example, {8*4/2} is evaluated as 16, and {8/4*2} is evaluated as4.

8.6 MACRO LISTS

A macro-list is a sequence of strings separated by commas and enclosed between brackets. Each string in the macro-list is called an element. An element of a macro-list may itself be a macro-list, allowing for multilevel macro-lists.

Macro-lists are useful for implementing macro data-structures (such as arrays, records, stacks) in conjunction with built-in functions that perform macro-list manipulations, such as search, insertion and deletion of elements (see Section 8.16). Some examples of various types of macro-lists are:

Examples:

1. []

a macro-list with no elements

2. [xx, yy]

a macro-list with two elements: xx and yy.

3. [a,,]

a macro-list with three elements: a and two empty strings.

4. [[r1,r2],100]

a macro-list with two elements, a macro-list with two elements and the string 100.

5. [12[r2:w], @xx]

a macro-list with two elements.

8.7 BUILT-IN MACRO FUNCTIONS

The macro-assembler provides built-in functions to manipulate macro-strings, arithmetic constants, macro-lists and assembly operands.

The general syntax for calling a macro-function is:

Syntax: {macro_func param_list }

where: *macro_func* is the name of the function

param list is a macro-list in which each element is a parameter to

the function.

Leading and trailing blanks of parameters are stripped before processing the macrofunction. The macro-function call is then evaluated and replaced by the result of the function call.

Example: The macro-function call

```
{SUB_STR[ abcde , 3 , 2]}
```

is replaced by the string cd.

Below is a list of available built-in functions. The macro-list and operand functions are advanced features of the macro-assembler and therefore may not be necessary for all users. For a detailed description of these functions see Sections 8.15 through 8.18.

String Functions:

```
• {STR_LEN[string]}
```

- {STR_EQ[string1, string2]}
- {SUB_STR[string, start [, length]]}
- {STR_FIND[string, substring]}

Macro-List Functions:

```
• {LIST_GET[ list, element_number ]}
• (SUB_LIST[ list, start [, length ]])
• {LIST_FIND[ list, string ]}
• {LIST_REPL[ list, element_number, string ]}
• {LIST_INS[ list, string, element_number ]}
• {LIST_DEL[ list, element_number ]}
• {LIST LEN[ list ]}
```

Data Conversion Functions:

```
• {CNV_HEX[integer_constant]}
• {CNV_HEXF[constant]}
• {CNV_HEXL[constant]}
```

Instruction Operand Functions:

```
• {OP_TYPE[operand]}
• {OP REG[operand]}
• {OP_DISP1[operand]}
• {OP_DISPSIZE1[operand]}
• {OP_DISP2[operand]}
• {OP_DISPSIZE2[operand]}
• {OP_VAL[operand]}
• {OP_VALSIZE[operand]}
• {OP_LIST[operand]}
• {OP_IS_INDEXED[operand]}
• {OP_INDEX[operand]}
• {OP_INDEX_BASE[operand]}
• {OP_INDEX_REG[operand]}
• {OP_INDEX_SCALE[operand]}
```

8.8 CONDITIONAL ASSEMBLY

Sequences of statements may be generated according to conditions tested during the macro-processing phase.

8.8.1 Conditional Block

where:

if_condition and elsif_condition(s) are arithmetic macro-expressions.

Description:

A condition evaluated by the macro-assembler as a non-zero value is considered to be true. See Section 8.5 for details on macro-expression evaluation

In a conditional block the *if_condition* argument is evaluated first, and only if found to be true the statements in *if_conditional_body* are processed. If the *if_condition* is found to be false, the *elsif_condition(s)* arguments are evaluated until one of them is found to be true, in which case the corresponding *elsif_conditional_body* statements are processed. Otherwise, if an .else statement has been specified, the *else_conditional_body* statements are processed.

The types of statements that are allowed in *conditional_bodies* are valid assembly language statements, directives, macro-procedure call and macro-assembly directives, with all the conditional blocks, repetitive blocks and macro-procedure definitions being complete.

```
Example:
```

```
.if \{reg_num\} > 5
   movqd 5, r(reg_num)
.elsif \{reg_num\} > 3
   movqd 3, r(reg_num)
   movqd 1, r(reg_num)
.endif
```

If reg_num holds the value 6 this is expanded to

5, r6 movad

if reg_num holds the value 4 this is expanded to

movqd 3, r4

and if reg_num holds the value 0 this is expanded to

movqd 1, r0

8.9 REPETITIVE DIRECTIVES

The basic constructs of a repetitive block are:

```
.repeat [ iteration_count [, iteration_var ] ]
repetitive_body
.endr
and
.irp iteration_var, iteration_list
repetitive_body
.endr
```

Repetitive blocks may appear inside a macro-procedure definition, in conditional blocks, and may be nested without limit.

The types of statements allowed in a repetitive block are valid assembly language statements, directives, macro-procedure calls, macro-assembly directives (except the .macro and the .endm directives) with all conditional blocks and repetitive blocks being complete.

8.9.1 .repeat Directive

Syntax: .repeat [iteration_count [, iteration_var]]

where: iteration_count specifies the number of iterations.

iteration_var is a macro-variable name used as an iteration index.

Description:

The *iteration_count* argument is evaluated by the macro-processor. If its value is positive, the code following the .repeat statement through the corresponding .endr statement, is processed *iteration_count* amount of times.

If given, the *iteration_var* argument holds a string representing the current iteration number for each iteration. It receives values from 1 to *iteration_count*. After the processing of the repetitive block has been completed, it holds the *iteration_count* value.

If the *iteration_count* argument is evaluated as a negative or zero value, the statements in the block are read textually without being processed until an .endr directive is reached.

If the iteration_count argument is not given, then the repetitive block is

processed repeatedly until an .exit directive is processed (see Section 8.9.3).

Examples:

```
1.
                       8, i
     .repeat
                       0, r\{\{i\} - 1\}
       movqd
     .endr
```

generates code that clears r0 through r7.

```
2.
     .repeat 4
       nop
     .endr
```

generates 4 consecutive nop instructions.

8.9.2 .irp Directive

Syntax: .irp iteration var, iteration list

where: iteration var is a macro-variable name to be used as an iteration

variable.

iteration list is a macro-list.

Description: For each element in the iteration_list argument, the macro-processor

assigns its string value to iteration_var, and process the code between

the .irp statement and the corresponding .endr statement.

If the iteration_list argument is an empty macro-list, the statements in the block are read textually without being processed.

After the processing of the repetitive block has been completed,

iteration_var contains the last element of iteration_list.

Example: reg, [r0,r1,r2,r3,r4,r5,r6,r7]

0, {reg} movqd

.endr

generates code that clears registers r0 through r7.

8.9.3 .exit Directive

Syntax: .exit

Description: Terminates the processing of the current repetitive block. Statements

following this directive are read textually without being processed, until

an .endr statement is encountered.

```
Example: x:=1
```

will generate the code

```
.byte 1
.byte 2
.byte 4
.byte 8
.byte 16
```

8.10 MACRO PROCEDURES (MACROS)

Use of a macro-procedure makes it possible to associate a macro name with a sequence of statements. This sequence can be generated by specifying the macro name in the opcode field, optionally with arguments.

The macro-procedure directives (.macro and .endm) in this version are not compatible with the GNX-assembler version 3.0 However, old code can be assembled using the -MC invocation option (/MCOMPATIBILITY on VMS) (see Section 8.3 for more details).

8.10.1 Macro Procedure Definition

```
Syntax: .macro macro-name [formal-arg [ , formal-arg ] ... ]

macro-procedure-body

.endm [macro-name]
```

is the macro-procedure name. It may be any legal where: macro-name

assembler symbol.

formal-arg is a macro-variable defining a formal argument.

macro-procedure-body

are the statements to be inserted into the assembler code when the macro-procedure is called.

Description: The statements of the macro-procedure body are read textually without being processed and are stored internally.

Within a macro-procedure body, other macro-procedure definitions are not allowed and all conditional and repetitive blocks must be complete. If macro-name is given in the . endm directive, it must be the same macro-name as given in the corresponding .macro directive.

A macro-procedure can only be defined once in an assembly file and its definition must precede any call to it.

The formal arguments in the .macro directive specify the names of the macrovariables to be assigned values according to the actual arguments, when the macroprocedure is called and expanded. The specification of formal arguments in the definition of a macro-procedure is optional.

```
Example:
```

movqd

movqd

movqd

0, 0(r4)

0, 4(r4)0, 8(r4)

```
.macro
         clear_array
                          size, base_reg
    # clears an array of 'size' double-words whose
    # base address is in 'base reg'
 .repeat {size}, elem_num
   clear_elem {elem_num}, {base_reg}
 .endr
 .endm
 .macro
        clear_elem
                          elem_num, base_reg
    # clears element number 'elem_num' of
    # an array whose address is in 'base_reg'
movqd
         0, {4 * ({elem_num} - 1)}({base_reg})
 .endm
clear_array 3, r4
will expand to
```

8.10.2 Macro Procedure Call and Expansion

Syntax: macro-name [actual-arg [, actual-arg] ...]

Description: A macro-procedure is called by specifying its name in the opcode field of

the statement, provided it has already been defined. The name of the invoked macro-procedure may be followed by a sequence of actual argu-

ments separated by commas.

When a macro-procedure call is processed, the current value of each macro-variable specified as formal argument is *saved*, and the macro-variable is assigned the value of its corresponding actual argument instead.

The body of the called macro-procedure is read from storage and processed as if it were inserted instead of the macro-procedure call statement. This is called macro-procedure expansion.

A macro-variable specified as a formal argument for the macro-procedure may be used in the macro-procedure body as any other macro-variable.

The number of actual arguments and the number of formal arguments do not have to correspond. If there are more formal arguments than actual arguments, the unmatched formal arguments will be assigned the value of an empty string. If there are more actual than formal arguments, the unmatched actual arguments can be accessed by using the predefined macro-procedure ARG_LIST. See the following section for more details on ARG_LIST.

8.10.3 Predefined Macro Procedure Variables

Two macro-variables, ARG_COUNT and ARG_LIST, are predefined macro-procedure variables. When a macro-procedure is called and expanded, their current values are saved, and they are assigned new values according to:

- 1. ARG_COUNT is assigned the number of arguments actually passed to the macro-procedure.
- 2. ARG_LIST is assigned the value of a macro-list, whose elements are the actual arguments to the macro-procedure. The first element of ARG_LIST will always be the first actual argument.
- 3. ARG_LABEL is assigned the value of the label of the macro-procedure invocation. It is assigned a value only if a label appears on the same line as a macro invocation.

These predefined variables cannot be specified as formal arguments.

Example:

"print_i_call" creates a calling sequence for the subroutine "print integers" by pushing its parameters, and the number of parameters on the stack.

```
print_i_call
.macro
.irp
          arg, (ARG_LIST)
        {arg},tos
byzom
.endr
           ${ARG_COUNT}, tos
movd
bsr
           print_integers
           ${-4*({ARG_COUNT}+1)}
adjspd
.endm
```

The following call:

```
print_i_call
               $100, xx, 0(r3)
```

will generate

```
$100, tos
movd
        xx, tos
movd
        0(r3), tos
movd
        $3, tos
movd
bsr
        print_integers
adjspd $-16
```

8.11 .macro_on and .macro_off Directives

The .macro_on and .macro_off directives enable and disable macro-procedure expansions, respectively, in selective parts of the source text. This is useful when macro-procedure names contradict opcode mnemonic or assembler directives. Thus, if for example opcode addd is redefined as a macro-procedure without the using the .macro off directive (as shown below), it would develop into an infinite sequence of recursive macro-procedure calls. However, the .macro_off directive allows disabling of macro-procedure expansions. As can be seen for:

```
.macro
           addd op1,op2
 bsr
        count_additions
.macro_off
 addd
           {op1}, {op2}
.macro_on
.endm
```

the following macro-procedure call:

```
addd
        r1, r2
```

will generate:

```
bsr
       count_additions
addd
       r1, r2
```

8.12 TEXT INCLUSION

This feature allows for the inclusion of text from another file as part of the file being assembled. The inclusion of text can also be specified from the invocation line by use of the -ML macro-library option (/MLIBRARY on VMS).

Syntax: .include included_file

where: included_file is an existing file name

Description:

An .include directive causes the macro-processor to process statements from the file named included_file before processing the statements following the .include directive in the original file.

By default, if the *included_file* argument does not start with a /, only the directory in which the source file resides is searched. Additional directories for the included file argument can be searched as specified on the invocation line using the macro Include Search Directory option (-MI on UNIX, /MINCLUDE on VMS).

Included files may contain any valid assembly directives and statements, macro-procedure call or macro-assembly directives (in particular .include directives), macro-procedure calls or macro-assembly directives, with all conditional blocks, repetitive blocks and macro-procedure definitions being complete.

Example: .include filehdr.h

8.13 MACRO WARNING AND ERROR MESSAGES

The directives .mwarning and .merror generate assembler warning and error messages.

8.13.1 .mwarning Directive

Syntax: .mwarning

Description: When a statement with a .mwarning directive is processed by the

macro-processor, a warning message with the source file name, the current line number and warning_message is displayed on the assembler listing output (or written to the standard error file, if no listing out-

put has been requested in the invocation line).

Example: xx = 222

.mwarning current value of "xx" is : {xx}.

In this example the .mwarning directive may be used to write the current value of macro-variables on the listing output. The assembler will issue the following warning message:

Assembler (Macro-Processor): "filename.s", line 2 , WARNING : current value of "xx" is : 222

8.13.2 .merror Directive

Syntax: .merror error_message

Description: When a statement with a $\mbox{.merror}$ directive is processed by the macro-

processor, an error message with the source file name, the current line number and *error_message* is displayed on the listing output (or written to the standard error file, if no listing has been requested in invocation line). The assembly process that follows is terminated after the macroprocessing phase is completed, and the second phase, the assembly

phase, is suppressed.

```
Example:
```

```
.merror
```

Wrong value used for addr "address"

The assembler will issue the following error message:

```
Assembler (Macro-Processor) Error:

'f.s', line 1, statement is ==> .merror Wrong value used for addr 'address' <==
ERROR: Wrong value used for addr 'address'
```

8.14 LISTING CONTROL

Macro processor expansions can be output in two ways. After the macro processing phase, expansions can be output to the assembler. After the full assembly process is completed, a complete assembly listing file can be produced.

To display macro processor expansions after the macro processing phase, invoke the assembler with the -MP option (/MPRINT on VMS). The display will contain the expansions of the macro processor as assembly statements, with other non-macro assembly statements. See 8.3 for full details on the -MP option.

To list macro processor expansions after the full assembly process, invoke the assembler with the -L option (/LIST on VMS). This option will produce a complete listing. When the -L option is used, the .list and .nolist directives can be used to select parts of the assembly source file to be listed. In addition, qualifiers can be used with these directives to include or exclude certain levels of macro expansions. .list turns the qualifiers ON and .nolist turns them OFF.

The qualifiers are:

mac source -

When *mac_source* is ON, the assembler lists user source lines, before any macro expansions or macro substitutions have been done. The default setting is ON.

mac expansions -

When mac_expansions is ON, the assembler lists user source lines, after all macro substitutions have been performed on them. The default setting is OFF.

mac_directives -

When *mac_directives* is ON, the macro directives also appear in the source listing. The default setting is ON.

It is not necessary to include the .list directive to use the default settings of the qualifiers. The -L option automatically produces a list and assumes the default qualifier settings.

For source level debugging, use the default settings of the qualifiers to produce a listing in which the displayed lines correspond to the line numbering recognized by the debugger.

For assembly level debugging, set mac_source and mac_directives OFF and mac_expansions ON to produce a listing in which the displayed lines correspond to the actual generated code.

When both mac_source and mac_expansions are OFF, no listing is produced. This combination is equivalent to .nolist with no parameters.

It is not advisable to use the mac_source option when both mac_directives and mac_expansions are OFF. This combination will produce output which is difficult to read.

In the default setup, the expansions of macro procedure calls, .repeat, and .irp blocks, are not listed.

```
Example : (Default)

mac_source= ON

mac_expansions= OFF

mac_directives= ON
```

This source file:

```
.macro zero_reg regno
movqd 0, r{regno}
.endm

lab1:
    zero_reg 0
.repeat 7, i
zero_reg {i}
.endr
```

Produces this listing:

```
GNX Assembler Version X.XX
                               date
                                       Page: 1
##### File "list1.s" #####
     1
                                          .macro
                                                   zero_reg regno
     1
                                                   0, r{regno}
                                         movad
     1
                                          .endm
     4
     5
        T00000000
                               lab1:
        T00000000 5f00
                                          zero_reg
     7
                                          .repeat
                                                    7, i
     7
                                          zero_req {i}
     7
        T00000002 5f085f10
                                          .endr
                    5f185f20
                    5f285f30
```

5f38

When mac_expansions is ON, and mac_source and mac_directives are both OFF, only the output of the macro processing phase, as passed on to phase-1 of the assembler, is listed.

Example:

mac_source= OFF mac_expansions= ON mac_directives= OFF

This source file:

```
.list
         mac_expansions
.nolist
         mac_source mac_directives
.macro
         zero_reg regno
movqd
         0, r{regno}
.endm
```

lab1:

zero_reg 0 7, i .repeat zero_reg {i} .endr

Produces this listing:

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File "list2.s"

1	1			.list	mac_exp	expansions	
2	2			.no	list	mac_source	
mac_dir	ectives						
6							
7	T00000000		lab1:				
8	T00000000	5f00		movqd	0, r0		
9	T00000002	5f08		movqd	0, r1		
9	T00000004	5f10		movqd	0, r2		
9	T00000006	5f18		movqd	0, r3		
9	T00000008	5f20		movqd	0, r4		
9	T0000000a	5f28		movqd	0, r5		
9	T0000000c	5 f 30		movqd	0, r6		
9	T0000000e	5f38		movqd	0, r7		

When both mac_source and mac_expansions are ON, each source line expanded by the macro assembler is printed twice: first as it appears in the source, and then as it appears after the expansion.

Example:

```
mac_source= ON
mac_expansions= ON
mac_directives= OFF
```

This source file:

```
.list mac_expansions
.macro zero_reg regno
movqd 0, r{regno}
.endm
```

lab1:

```
zero_reg 0
.repeat 7, i
zero_reg {i}
.endr
```

Produces this listing:

```
GNX Assembler Version X.XX date Page: 1
```

File "list3.s"

```
1
                                     .list
                                               mac_expansions
2
                                      .macro
                                               zero_reg regno
2
                                     movqd
                                               0, r{regno}
2
                                      .endm
5
6
   T00000000
                        lab1:
7
                                     zero_reg 0
7
                                     movqd
                                               0, r{regno}
7
   T00000000 5f00
                                     movqd
                                               0, r0
8
                                     .repeat 7, i
8
                                     zero_reg {i}
8
                                     zero_reg 1
8
                                     movqd
                                               0, r{regno}
8
   T00000002 5f08
                                     movqd
                                               0, r1
8
                                     zero_reg {i}
8
                                     zero_reg 2
8
                                     movqd
                                               0, r{regno}
8
   T00000004 5f10
                                     movqd
                                               0, r2
8
                                     zero_reg {i}
8
                                     zero_reg 3
```

```
8
                                              0, r{regno}
                                     movad
8
   T00000006 5f18
                                     movad
                                              0, r3
8
                                     zero_reg {i}
8
                                     zero_reg 4
8
                                     movqd
                                              0, r{regno}
8
   T00000008 5f20
                                     movad
                                              0, r4
8
                                     zero_reg {i}
8
                                     zero_reg 5
8
                                     movad
                                              0, r{regno}
8
   T0000000a 5f28
                                     movqd
                                              0, r5
8
                                     zero reg {i}
8
                                     zero_reg 6
8
                                             0, r{regno}
                                     movqd
8
   T0000000c 5f30
                                              0, r6
                                     movqd
8
                                     zero_reg {i}
8
                                     zero_reg 7
8
                                              0, r{regno}
                                     movqd
8
   T0000000e 5f38
                                     movad
                                              0, r7
8
                                    .endr
```

After expansion of a macro or a .repeat/.irp block has started, it cannot be reversed. However, it is possible to expand only one level by starting a macro or .repeat/.irp block with mac_expansion ON, and switch it OFF inside a block. Only the outer level will be expanded.

mac_expansions

Example:

This source file:

```
.macro
                     zero_reg regno
                     0, r{regno}
          movqd
          .endm
lab1:
          zero_reg 0
                     7, i
          .repeat
                     \{i\} = 2
              .nolist mac_expansions
          .endif
          zero_reg {i}
           .endr
```

.list

Produces this listing:

```
GNX Assembler Version X.XX date Page: 1
##### File "list4.s" #####
     1
                                        .list
                                                 mac_expansions
     2
                                        .macro
                                                  zero_reg regno
     2
                                                  0, r{regno}
                                        movad
     2
                                        .endm
     5
     6
       T00000000
                                lab1:
     7
                                        zero_reg 0
     7
                                        movqd 0, r{regno}
     7
       T00000000 5f00
                                        movqd
                                                 0, r0
     8
                                        .repeat
                                                 7, i
     8
                                        .if
                                                  \{i\} = 2
     8
                                        .if
                                                  1 = 2
     8
                                        .endif
     8
                                        zero_reg {i}
     8
                                        zero_reg 1
     8
                                        movad
                                                 0, r{regno}
       T00000002 5f08
     8
                                        movqd
                                                  0, r1
     8
                                        .if
                                                 \{i\} = 2
     8
                                        .if
                                                 2 = 2
     8
                                           .nolist mac_expansions
     8
                                        .endif
     8
       T00000004 5f10
                                        zero_reg {i}
     8
                                        .if
                                                 \{i\} = 2
     8
                                        .endif
     8
       T00000006 5f18
                                        zero_reg {i}
     8
                                        .if
                                                 \{i\} = 2
     8
                                        .endif
     8
       T00000008 5f20
                                        zero_reg {i}
     8
                                        .if
                                                  \{i\} = 2
     8
                                        .endif
     8
       T0000000a 5f28
                                        zero_reg {i}
     8
                                        .if
                                                  \{i\} = 2
     8
                                        .endif
     8
       T0000000c 5f30
                                        zero_reg {i}
     8
                                        .if
                                                 \{i\} = 2
     8
                                        .endif
     8
       T0000000e 5f38
                                        zero_reg {i}
     8
                                        .endr
```

8.15 STRING FUNCTIONS

The macro-assembler provides a set of built-in functions to manipulate strings: string length, string comparison, substring extraction, and substring search.

Characters in strings are counted starting number 1. For example, in the string abcde, a is character number 1, b is character number 2, and so on.

8.15.1 StringLength

Syntax: {STR_LEN[string]}

Description: Evaluates as the number of characters in string.

Examples:

- 1. (STR_LEN[abcd]) is evaluated as 4.
- 2. (STR_LEN[ab cd]) is evaluated as 5.
- 3. (STR_LEN[]) is evaluated as 0.

8.15.2 String Comparison

Syntax: {STR_EQ[string1, string2]}

Description: Evaluates as 1 if string1 and string2 are the same, and as 0 if they are

different.

```
Example: .macro addd3 src1, src2, dest
```

```
.if {ARG_COUNT} = 2
addd (src1), (src2)
.elsif (STR_EQ[(src2), {dest}])
addd (src1), (src2)
.elsif (STR_EQ[(src1), {dest}])
addd (src2), (src1)
.else
movd (src1), (dest)
addd (src2), {dest}
.endif
.endm
```

8.15.3 Substring Extraction

Syntax: {SUB_STR[string, start [, length]]}

Description:

Extracts a substring of the string argument from position start. Generally, length is taken to be substring size. If the length argument is omitted or is greater than the remaining length of the string argument, then the length of the substring is the remaining length of the string.

The function call will be evaluated as an empty string when:

- start is less than or equal to zero.
- *start* is greater than the length of the string.
- *length* is less than or equal to zero.

Examples:

- 1. (SUB_STR[abcdefgh, 2, 3]) evaluates to bcd.
- 2. (SUB_STR[abcdefgh, 3]) evaluates to cdefgh.
- 3. (SUB_STR[abcdefgh, 1000, 3]) evaluates to an empty string.

8.15.4 Substring Search

Syntax: {STR_FIND[string, substring]}

Description:

Evaluates as the position of the first character of substring in its first occurrence in string. If substring is not found, the value of the function is 0.

Examples:

```
1. {STR_FIND[abcdefgh,cde]}
```

evaluates to 3.

2. (STR_FIND[abcabc,c])

evaluates to 3.

3. {STR_FIND[abcdefgh, zz]}

evaluates to 0.

8.16 MACRO-LIST FUNCTIONS

A macro-list is a string that contains substrings separated by commas and that is enclosed between brackets. Each of these substrings is called an element of the macrolist. See Section 8.6 for more details about macro-lists.

The macro-assembler includes a set of built-in functions to process macro-lists that allow creation and manipulation of array-like and other complex structures (stacks, queues, etc ...). The built-in functions are: sub-list extraction, retrieval, search, insertion and deletion of elements into/from lists. Another built-in function returns the number of elements in a macro-list.

Elements in macro-lists are counted starting from the left with number 1. For example, in the macro-list [aa, bb, cc, dd], element number 1 is aa, element number 2 is bb, and so on.

8.16.1 GetElement From List

Syntax: {LIST_GET[list, element_number]}

Evaluates as the element whose number is specified by *element_number*. Description:

Example: (LIST_GET[[a,b,c,d],2]) is evaluated as the string b.

8.16.2 Sublist Extraction

Syntax: {SUB_LIST[list, start [, length]]}

Description: Evaluates as a macro-list of *length* elements from the *list*, starting at element number start. If length is omitted or is greater than the number of remaining elements, all remaining elements are included in the sub-

list.

In the following cases, the function call is evaluated as an empty macro-list []:

- start is less than or equal to zero.
- *start* is greater than the number of elements in *list*.
- length is less than or equal to zero.

Examples:

- 1. $(SUB_LIST[[a,b,c,d,e,f,g,h],2,3])$ is evaluated as [b,c,d].
- 2. (SUB_LIST[[a,b,c,d,e,f,g,h],3]]) is evaluated as [c,d,e,f,q,h].
- 3. (SUB_LIST[[a,b,c,d,e,f,g,h],1000,3]) is evaluated as [].

8.16.3 Find An Element In List

Syntax: {LIST_FIND[list, string]}

Description: Evaluates as the position (element number) of the first occurrence of

string as an element of list. If string is not an element of list, the func-

tion call is evaluated as 0.

Example: After the assignment:

```
dummy_list:=[hhh,r1,ii,x,hh,x]
```

then:

- (LIST_FIND[(dummy_list),r1]) is evaluated as 2.
- (LIST_FIND[(dummy_list),yyy]) is evaluated as 0.
- (LIST_FIND[(dummy_list),x]) is evaluated as 4.

8.16.4 Replace An Element In A List

Syntax: {LIST_REPL[list, element_number, string]}

Description: Evaluates as list after replacing the element, whose number is specified

> by *element_number*, with the given *string*. This macro-function is useful, when a macro-list is handled as an array, for assigning a value to a

specified element in a macro-list.

Example: dum_list:=[xx,yy,zz]

dum list:={LIST REPL[{dum list},2,aa]}

The second element of dum_list has been "assigned" (replaced with) the string aa, and dum_list now holds the value [xx,aa,zz].

8.16.5 Insert An Element Into A List

Syntax: {LIST_INS[list, string, element_number]}

Description: Evaluates as list after inserting string as an element before the element

specified by element_number.

Example: list1:=[aa,bb,cc]

list2:={LIST_INS[{list1},dd,3]}

list2 holds the value [aa, bb, dd, cc].

8.16.6 Delete An Element From A List

Syntax: {LIST DEL[list, element number]}

Description: Evaluates as list after removing the element whose number is specified

by element_number.

Example: list1:=[aa,bb,cc]

list2:={LIST_DEL[(list1),2]}

list2 holds the value [aa,cc].

list1 remains to hold the original value [aa, bb, cc].

8.16.7 Number Of Elements In A List

```
Syntax:
             {LIST_LEN[list]}
```

Evaluates as the number of elements in *list*. Description:

```
Example:
              vars_list:=[-12(fp), -16(fp), -20(fp), r0, r1[r4:b], r2]
              {LIST_LEN[{vars_list}]} evaluates to 6.
```

8.16.8 Example of Macro-List Function Usage

Included here is an example showing the capability of the different macro-list functions. A stack-list is implemented using the macro-list functions. We define a set of macro-procedures: PUSH, POP, TOP, RESET.

```
.macro
        PUSH
                  list_name, element
                # pushes an element into a stack list
    (list_name):=(LIST_INS[{{list_name}}), {element}, 1])
                # {list_name} evaluates to the NAME of the list.
                # ({list_name}) evaluates to its VALUE.
.endm
        POP
                  list_name,el_var_name
.macro
                # returns the first element of a list, and remove that
                # first element from it.
    (el_var_name):=(LIST_GET[((list_name)),1])
    (list_name):=(LIST_DEL[{{list_name}},1])
.endm
        TOP
                  list_name,el_var_name
.macro
                # returns the last element of a list.
    (el_var_name):=(LIST_GET[{(list_name}),1])
.endm
.macro
        RESET
                    list_name
                # assign a empty list value [] to the list.
    {list_name}:=[]
.endm
```

In the following sequence of macro-procedure calls, the values of the variables after each call are specified in the comments.

var:=								
RESET	stack1							
RESET	stack2							
		#	value of :					
		#	stack1	1	stack2	1	var	
		#	=====	1	=====	1	===	
		#	[]	1	[]	1	empty stri	ng
PUSH	stack1,aa	#	[aa]	I	[]	ı	empty stri	ng
PUSH	stack1,bb	#	[bb,aa]	١	[]	1	empty stri	ng
PUSH	stack1,cc	#	[cc,bb,aa]	١	[]	ı	empty stri	ng
POP	stack1,var	#	[bb,aa]	ı	[]	١	cc	
PUSH	stack2, (var)	#	[bb,aa]	ł	[cc]	ı	cc	
TOP	stack1,var	#	[bb,aa]	1	[cc]	I	bb	
RESET	stack1	#	[]	1	[cc]	ı	bb	

8.17 DATA CONVERSION FUNCTIONS

The macro-assembler provides a set of built-in functions to convert strings representing assembly numerical constants (as defined in Section 2.4) into hexadecimal digit strings. These are integer hexadecimal, float hexadecimal or long float hexadecimal.

8.17.1 ConvertTo Integer Hexadecimal

Syntax: {CNV_HEX[integer_constant]}

Description: Evaluates as a string of 8 hexadecimal digits representing the constant

in hexadecimal integer format. The integer_constant may be specified in

any of the integer notations.

Example:

Given the definition

const := 1024

then {CNV_HEX[{const}]} is evaluated as X'00000400.

8.17.2 Convert To Float Hexadecimal

Syntax: {CNV_HEXF[constant]}

Description: Evaluates as a string of 8 hexadecimal digits representing the constant

in float-hexadecimal format. If constant is not a single precision floating

point constant, it is first converted to this representation.

Examples:

```
1.
    {CNV_HEXF[{5-4}]}
   is evaluated as f'3f800000.
```

```
2.
     {CNV_HEXF[1.0e0]}
   is evaluated as f'3f800000.
```

```
3.
    {CNV_HEXF[1'3ff0000000000000]}
    # long representation of 1.
```

is evaluated as f'3f800000.

8.17.3 Convert To Long Float Hexadecimal

Syntax: {CNV_HEXL[constant]}

Description: Evaluates as a string of the 16 hexadecimal digits representing the con-

stant in long hexadecimal-decimal format. If constant is not a long float-

ing point constant, it is first converted to this representation.

Examples:

```
    (CNV_HEXL[{5-4}])
        evaluates to e'3ff000000000000.
    (CNV_HEXL[1.0e0])
        evaluates to e'3ff000000000000.
    (CNV_HEXL[f'3f800000])
        # single precision float representation of 1.
        evaluates to e'3ff0000000000000.
```

8.18 INSTRUCTION OPERAND FUNCTIONS

The macro-assembler includes a set of built-in functions for processing instruction operands, including recognition of operand type and extraction of subfields from operands strings. These functions provide for ease in using the diversity of operands types and addressing modes provided by the NS32000 architecture and the GNX assembler.

For example, given an operand string specifying a memory location, another operand string can be created which points to the double word next to that location (.i.e "location+4"). If the operand is a symbol, a leading 4+ string can be concatenated to the operand string. If the operand has been specified with a leading @ (absolute addressing mode), 4+ can be inserted after the @ . However with many other operand notations adding such an offset to the location is not as simple. Therefore some convenient built-in functions are provided which recognize the notation (type) in which the operand has been specified, and extract subfields in operand strings.

8.18.1 Recognize The Type Of An Operand

Syntax: {OP_TYPE[operand]}

Description: Evaluates as a string describing the NS32000 type of operand, or as

an empty string if the string is not a legal NS32000 operand.

A list of possible operands types are:

```
EXPR
                                : any legal combination of symbols,
                                 constants and arithmetic operators
                                 optionally followed by a displacement
                                 size specification (:b,:w,:d).
                                 examples:
                                              xx:b
                                              12
                                              ss+3+(kk-9):d
            GREG
                                : r0,r1 ...
            FREG
                               : f0,f1,...
            LREG
                               : 10.11....
            PREG
                               : processor register : upsr,cfg,sp ..
            MREG
                               : mmu register : tear,mcr ...
            REG REL
                               : expression1(register)
            MEM_SPACE
                               : expression1(fp),
                                 or expression1(sp), or expression1(sb)
            EXPL PC REL
                               : %expression1
            EXPL SB REL
                               : ^expression1
            MEM REL
                               : expression2(expression1(fp)),
                                 or expression2(expression1(sp)),
                                 or expression2(expression1(sb))
            ABS
                                : @expression1
            IMM
                               : $expression1
            EXT_1
                                : expression2(expression1(ext))
            EXT 2
                                : expression1(ext)
            DREF_SYM
                                : expression2(expression1)
            TOS
            REG_LIST
                                : register list [r0,r1,..]
                                : options list [cc,f,..]
            OPT_LIST
1. \{OP_TYPE[12(sp)]\}
   is evaluated as MEM_SPACE.
2. {OP_TYPE[@xx+121]}
   is evaluated as ABS.
3. {OP_TYPE[12(param+12)]}
   is evaluated as DREF_SYM.
```

NOTE: The OP_TYPE built-in macro-function can not always provide the definite addressing mode that will be used for the operand. Information returned by this function is just the most accurate conclusion that can be drawn about the nature of the operand, through scanning the operand string and without any knowledge of the context in which the operand appears or of the type of the user-symbols (e.g. labels) involved in the operand. Since this knowledge is mandatory for determining the exact addressing mode in which the operand will be encoded, and since the macro-processing phase is done prior to the assembly phase, this information is unavailable during the macro-processing phase.

8.18.2 Operand Subfields

The following are the various operand subfield functions

• Syntax: {OP_REG[operand]}

Description: If the operand is a register, it is evaluated as that register. If the

operand has a base register, it is evaluated as the base register.

No register is returned if the operand is a register list.

Example: {OP_REG[xx:w(yy+8(sp))]}

is evaluated as sp.

• Syntax: {OP DISP1[operand]}

Description: If the operand contains at least one displacement field, with or

without a displacement size specification, the function call is evaluated as the innermost displacement string without the displacement size specification. Otherwise the empty string is

returned.

Note that when the operand type is DREF_SYM, the intermost dis-

placement string is returned.

Example: {OP_DISP1[xx:w(yy+8(sp))]}

is evaluated as yy+8.

• Syntax: {OP_DISPSIZE1[operand]}

Description: If the innermost displacement string has a size specified, that size

specification is returned. Otherwise, the empty string is

returned.

Example: {OP_DISPSIZE1[xx:w(yy+8(sp))]}

evaluates to an empty string.

• Syntax: {OP_DISP2[operand]}

Description: If the operand contains two displacement fields (in MEMORY

RELATIVE addressing mode and in some EXTERNAL addressing mode notations), it is evaluated as the string of the outermost dis-

placement without the displacement size specification.

Note that when the operand type is EXT_3, the outermost dis-

placement string is returned.

Example: (OP_DISP2[xx:w(yy+8(sp))])

is evaluated as xx.

• Syntax: {OP_DISPSIZE2[operand]}

Description: If the operand contains two displacement fields (in MEMORY

RELATIVE addressing mode and in some EXTERNAL addressing mode notations), it is evaluated as the displacement size

specification of the outermost displacement field.

Example: {OP_DISPSIZE2[xx:w(yy+8(sp))]}

is evaluated as :w.

• Syntax: {OP_VAL[operand]}

Description: If the operand is EXPR, ABS, IMM, EXPL PC REL, or

EXPL_SB_REL, it is evaluated as the expression without the size

or any preceding literals.

Example: {OP_VAL[\$yy+8]}

is evaluated as yy+8.

• Syntax: {OP VALSIZE[operand 1}

Description: If the operand is EXPR, ABS, IMM, EXPL_PC_REL or

EXPL_SB REL, it evaluates to its specified size.

Example: {OP_VALSIZE[\$yy+8:b]}

is evaluated as .b

• Syntax: {OP LIST[operand]}

Description: If the operand is a register list (general purpose registers between

[]) or an option list (either cfg or cinv option list between []), it is

evaluated as the list after sorting of its elements.

Examples:

1. {OP_LIST[[r4,r6,r2,r0]]}

is evaluated as a macro-list with the registers which appear

in the list after sorting : [r0,r2,r4,r6]

2. {OP_LIST[[i,f,c]]}

is evaluated as [c,f,i].

• Syntax: {OP_IS_INDEXED[operand]}

Description: If the operand has a scaling index it evaluates to the boolean

value 1: otherwise it evaluates to the boolean value 0.

Example: {OP IS INDEXED[r0[r2:d]]}

is evaluated as the boolean value: 1.

• Syntax: {OP INDEX[operand]}

Description: If the operand is a scaled indexed operand, it is evaluated as the

scaling index string, including the index register, the index scale specification (:b, or :w, or :d, or :q, or an empty string) and the

enclosing brackets.

Example: {OP_INDEX[xx+9(sp)[r1:b]]}

is evaluated as the index specification string: [r1:b].

• Syntax: {OP_INDEX_BASE[operand]}

If the operand is a scaled indexed operand, it is evaluated as the Description:

operand string without the index mode specification string.

Example: {OP_INDEX_BASE[xx+9(sp)[r1:b]]}

is evaluates as the "base" of the operand, that is, the operand

string without index specification string: xx+9 (sp).

• Syntax: {OP_INDEX_REG[operand]}

Description: If the operand is a scaled indexed operand, it is evaluated as a

string specifying the index register.

Example: {OP_INDEX_REG[xx+9(sp)[r1:b]]}

it is evaluated as the index register r1.

• Syntax: {OP_INDEX_SCALE[operand]}

Description: If the operand is a scaled indexed operand, it is evaluated as a

string specifying the index mode scale specification (:b, or :w, or

:d, or :q, or an empty string).

Example: {OP_INDEX_SCALE[xx+9(sp)[r1:b]]}

is evaluated as the scale specification: b.

The following table defines the subfields that are relevant to various operand types.

Table 8-2. Relevant Operand Subfields

TYPE	REG	DISP1	SIZE1	DISP2	SIZE2	VAL	VALSIZE	LIST	INDEX
EXPR						+	+		+
GREG	+								+
FREG	+								
LREG	+				,				
PREG	+								
MREG	+								
REG_REL	+	+	+						+
MEM_SPACE	+	+	+						+
EXPL_PC_REL						+	+		+
EXPL_SB_REL						+	+		+
MEM_REL	+	+	+	+	+				+
ABS						+	+		+
IMM						+	+		
EXT_1		+	+	+	+				+
EXT_2		+	+						+
EXT_3		+	+	+	+				+
TOS									+
REG_LIST								+	
OPT_LIST								+	

The following example illustrates use of the OP_TYPE and of the subfield functions.

The macro-procedure warn_same_req receives an operand string as an argument, and issues a warning message when the operand has scaled indexing and the index register is the same as the base register.

```
.macro warn_same_reg
                               operand
          {OP_IS_INDEXED[{operand}]}
              reg : = {OP_REG[{operand}]}
             scaling_reg : = {OP_INDEX_REG[{operand}}}
              .if (STR_EQ[{reg}, {scaling_reg}])
                   .mwarning base register and index register are
                              the same in {operand}
              .endif
       .endif
.endm
```

NOTE: It is not necessary to check types of operands. Registers will be empty if operands are irrelevant.

The following example shows a possible usage of the "warn_same_reg" macro-procedure. The macro-procedure "warn_same_reg" is invoked from another macro-procedure, "movd", which first performs a check on both its operands and then actually issues a "movd" instruction.

```
.macro
           movd
                   source, dest
   warn_same_reg {source}
   warn_same_reg {dest}
   .macro_off
       # cancel definition of "movd" as a macro-procedure,
       # to avoid infinite recursive calls
       # "movd" is now considered to be an instruction,
       # and not a macro-procedure.
   movd {source}, {dest}
   .macro on
       # restore macro-procedure "movd" definition.
.endm
movd
        12(r1)[r1:b],r2[r2:q]
       # 2 warning messages are issued, one for each operand.
       # ".... WARNING .... base register and index register are
       # the same in 12(r1)[r1:b]".
       # ".... WARNING .... base register and index register are
       # the same in r2[r2:q]".
       # the instruction "movd 12(r1)[r1:b], r2[r2:q]" is also
       # generated.
movd
       0(r3)[r3:q],r2
       # a warning message is issued for the first operand.
       # ".... WARNING .... base register and index register are
       # the same in 0(r3)[r3:q]".
       # the instruction movd 0(r3)[r3:q],r2 is also generated.
        r1[r3:w],@aaa
byom
       # no warning messages are issued.
       # the instruction "movd r1[r3:w], @aaa" is generated.
```

8.19 PREDEFINED MACRO VARIABLES

Several variables are predefined by the GNX macro-assembler to hold the values of several target specification parameters. These parameters are either set in the .gnxrc file or as invocation switches to the assembler.

The predefined variables are:

Variable	Target Specification
GNX_OS	os
GNX_CPU	cpu
GNX_MMU	mmu
GNX_FPU	fpu
GNX_COMMTYPE	commtype
GNX_BYTESEX	bytesex
GNX_BUSWIDTH	buswidth

The MAC_DEBUG predefined variable is set to "1" if the assembler is invoked with the "-g" ("/DEBUG") option. It is set to "0" otherwise. This can be used to add special testcode during the debugging phase.

The MAC_COMMENT predefined variable is set to the "#" character. It allows user macros to add comments to the output when the macro assembler is used as a macro preprocessor only. (i.e. when the assembler is invoked with the "-MO" and "-MP" flags on UNIX, or "/MONLY" and "/MPRINT" on VMS.)

	•	
		•

INVOCATION AND OPERATION

9.1 INTRODUCTION

The GNX Assembler generates object code from Series 32000 assembly language source files and optionally produces a listing file and debugging information. Each assembly source file produces one Series 32000 software module, consisting of a text (code) section and an initialized data section. The module is suitable for execution on Series 32000-based systems after the appropriate linking process.

This chapter describes the input and output files used by the GNX Assembler, the GNX Assembler invocation, the assembler listing file, symbol table listing, the crossreference table, assembly errors, and the GNX Assembler limitations.

9.2 INPUT AND OUTPUT FILES USED/GENERATED BY THE GNX ASSEMBLER

The files used as input and those generated as output by the assembler are shown in Figure 9-1 and described below.

Source file — Input. The source file is a text file containing the source program to be assembled.

Object file — Output. The object file contains the relocatable object code and data produced by the assembler, as well as optional debugging information. When no filename for the object file is given, the default name is the name of the source file with the .s suffix, if any, stripped off and a .o suffix appended. For example, if the source file is named build.s, the name of the object file will be build.o. The object file is suitable for use as input to the linker, 1d (native), or nmeld (cross-support).

Listing file — Output. The listing file, created with the -L option (/LIST on VMS), contains the program listing produced by the assembler. On UNIX, the default listing file is the standard output (stdout); on VMS it is filename.lis. If a filename parameter is specified with the listing option, the filename is the listing output.

Macro-processor output — Output. Contains the macro-processor output. For details see Section 8.14.

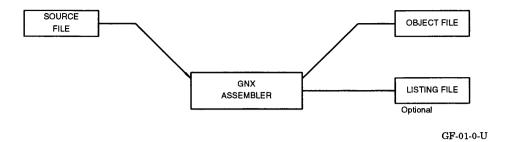


Figure 9-1. Input and Output Files for the GNX Assembler

Temporary files used by the GNX Assembler during the assembly process are as follows:

DOS:	al xxxxx	temporary files for listing
	am xxxxx	temporary source file for listing
	at xxxxx	temporary file
	asxxxxx	temporary files for pre-processing
	axxxxxx	temporary files for cross-referencing
UNIX:	/+/	temporary files for listing
UNIA.	/tmp/aslstxxxxx	temporary mes for fisting
	/tmp/amlstxxxxx	- · · · · · · · · · · · · · · · · · · ·
	/tmp/asxxxxxx	temporary file
	/tmp/astxxxxxx	temporary files for pre-processing
	/tmp/asmdxxxxx	temporary files for macro definitions
	/tmp/asma <i>xxxxxx</i>	temporary files for macro arguments
	/tmp/asxxxxxxx	temporary files for cross-referencing
VMS:	aslstxxxxxx.tmp	temporary files for listing
	amlstxxxxxx.tmp	temporary source file for listing
	asxxxxxx.tmp	temporary file
	astxxxxxx.tmp	temporary files for pre-processing
	asmdxxxxxx.tmp	temporary files for macro definitions
	-	
	asmaxxxxxx.tmp	temporary files for macro arguments
	asxxxxxxx.tmp	temporary files for cross-referencing

Where xxxxx is replaced by the current process ID.

The creation of temporary files can cause a file I/O operation failure if there is limited space in the directory. The default location for temporary files can be changed on UNIX/MS-DOS by using the TMPDIR enironment variable.

9.3 GNX ASSEMBLER INVOCATION

The GNX Assembler is invoked from the shell by entering the as command or the nasm command (under X-support), optionally followed by flags and an output filename, followed by a source filename. The following is the assembler syntax:

{as | nasm} [options] sourcefile

The source filename and the flags may appear in any order with the exception of the -c option which must come before the -D, -U, or -I options. Only one source filename is permitted. See Table 9-2 for a list of the optional flags, their syntax, and their definition.

Examples:

- 1. nasm
- 2. nasm myfile.s
- 3. nasm -L myfile.s
- 4. nasm -L -o myfiledebug.o myfile.s
- 5. nasm -L myfile.s > myfile.lis
- nasm -Lmyfile.lis myfile.s

Example 1 does not specify any filename or switch. The assembler will wait for input from stdin.

Example 2 will assemble the source file myfile.s and generate an object file with the default name myfile.o. No listing file will be produced.

Example 3 will generate both an object file, myfile.o, and a listing file from the source file myfile.s. The listing file will be output to stdout.

Example 4 will generate the object file myfiledebug.o from the source file myfile.s. Because the -L option is specified, a listing will be produced on stdout.

Examples 5 and 6 will generate a listing file from the source file myfile.s and output it to myfile.lis.

9.3.1 Target Machine Specification

The assembler provides a way for the user to tune the code for a specific target system by specifying its CPU, FPU and MMU. This tuning is performed by setting permanent defaults using the GNX Target Setup (GTS) facility, or by specifying <code>/TARGET(-K)</code> on the command line.

Table 9-1 lists the possible target selection parameters. The values for the CPU, FPU and MMU can either be the complete device name e.g., NS32GX320 or NS32381, or the last characters of the device name, e.g. GX320 or 381. The absence of an FPU on the target system can be indicated by specifying the parameters emulation (emu) or nofpu. See the Series 32000 Support Libraries Manual for details on the floating-point emulation library (libHfp). The absence of an mmu is indicated by specifying the parameter nommu. The existence of mmu on a the specified CPU is indicated by using the parameter onchip (or mmu_onchip).

CPU (C)	FPU (F)	MMU (M)
[NS32]CG16	nofpu	nommu
[NS32]CG160	emulation	onchip
[NS32]AM160		
[NS32]FX164		
[NS32]FX16	[NS32]381	[NS32]382
[NS32]GX32	[NS32]181	[NS32]082
[NS32]GX320	[NS32]081	
[NS32]532	[NS32]580	
[NS32]332		
[NS32]032		
[NS32]016		
[NS32]008		

Table 9-1. Target Selection Parameters

Example:

The following example specifies an NS32GX320 CPU, an NS32381 FPU, and a buswidth of 4 bytes (the default).

UNIX

```
as -KCGX320 -KF381 temp.s (native-support) or nasm -KCGX320 -KF381 temp.s (cross-support)
```

VMS

NASM /TARGET=(CPU=GX320,FPU=381) TEMP.S

Table 9-2. Optional Flag Syntax Sheet 1 of 2

FLAC	EV AC	DENIMINAN
FLAG VMS	FLAG UNIX	DEFINITION
, <u> </u>	MS-DOS	
/DISPLACE-	-d1 -d2 -d4	Sets the default displacement size to byte
MENT= {BYTE		(d1), word (d2), or double-word (d4). The
WORD DOUBLE}		default is double-word (d4).
/M4	-m	Runs the m4 macro pre-processor on the input to the assembler.
/CPP	− c	Runs the C compiler pre-processor (cpp) on the input to the assembler.
*	-R	Deletes (unlinks) input file after assembly. Off by default.
/NODATA	-r	Incorporates the data segment into the text segment. Off by default.
/SAVESYM	-s	Saves compiler-generated labels in the symbol table of the object file.
/VERSION	-V	Writes the version number of the assembler to stderr (UNIX) or SYS\$OUTPUT (VMS).
/VMEM	-v	Uses virtual memory for intermediate storage rather than a temporary disk file.
/AMODE = SB	–A s	Overrides default addressing modes. The
		s or SB causes all references to symbols of
		type data to use the Static Base Register
/LIST	-L[filename]	Relative addressing mode. If filename is given, produces the listing in
[=filename]	-L[filename]	that file.
		If filename is not given, then on UNIX the
		listing is produced in the stdout file; on VMS in the .lis file.
/NOSDI	_n	Disables displacement size optimization.
/OBJECT=object	−o objfile	Leaves the output of the assembly on the file objfile. On UNIX, by default, the out-
		put filename is formed by removing the s
		suffix, if any, from the input filename and
		adding a .o suffix. On VMS, by default,
,		the output filename is formed by replac-
		ing the extension with a .obj extension.
*	–t	Causes the assembler to show all the util-
		ities it calls. This option is useful for trac-
		ing all processes executed by the assembler.
	@ filename	Reads options from file filename.
		(MS-DOS only)

Table 9-2. Optional Flag Syntax Sheet 2 of 2

FLAG VMS	FLAG UNIX MS-DOS	DEFINITION
/NOWARNING	-w	Supresses assembly warning messages.
. ,	ŕ	Produces a symbol table listing entitled "Symbol Table Dump." On VMS, if <i>filename</i> is not given, the output filename is formed by replacing the extension with a .map extension.
/XREF [=filename]		Produces a cross-reference listing entitled "Cross-Reference Table". On VMS, if <i>filename</i> is not given, the output filename is formed by replacing the extension with a .xrf extension.
/[NO]OPTIMIZE	-O	[Do not] perform procedure optimizations.
/DEFINE= ("name[=def]",)		Defines <i>name</i> to <i>cpp</i> , as if by "#define." If no definition is given, <i>name</i> is defined as 1. The –c (or /CPP for VMS) option must precede this option.
/UNDEFINE= ("name"[,])	-Uname	Removes initial definition of a predefined <i>name</i> . Cpp supplies initial definition of 1 for predefined names (e.g., NS32000, VMS, UNIX). The -c (or CPP for VMS) option must precede this option.
/INCLUDEDIR= (directory[,])	–Idir	Searches "#include" files that do no begin with / (or [for VMS) in the directory of the filename argument first, then the directory named in this option, then the directories on a standard list. The -c (or /CPP for VMS) option must precede this option.
/DEBUG	-g	Produces additional line number information for symbolic debugging.
/MODULAR	-X	Sets the 32000 modularity.
/TARGET= (parameter[,])	-Kparameter	Allows the user to specify the CPU, FPU, and MMU of the user's target system. The parameter is in the form Ccpu, Ffpu, Mmmu, or Bbuswidth on UNIX and in the form CPU=cpu, FPU=fpu, MMU=mmu, and BUSWIDTH=buswidth on VMS.
/Moption	-Moption	Macro specific option. These options are /MCOM-PATIBILITY (-MC), /MDEFINE (-MD), /MLI-BRARY (-ML), /MINCLUDE (-MI), /MONLY (-MO), and /MPRINT (-MP).**
* This flag is not a ** Refer to Section	vailable for V	/MS.

^{*} Refer to Section 8.3 for a detailed description.

9.3.2 Assembler Symbolic Debugging

When invoked with the -g option (DEBUG option on VMS), the assembler generates a line number entry in the object file for every source line of the input assembly file where a breakpoint can be inserted. The information from the line number entries allows the user to reference the line numbers when using a software debugger, such as DBUG.

Each assembly procedure defined using the GNX Assembler Procedure Support causes the generation of appropriate symbolic information for the debugger. This symbolic information includes the same information generated by the GNX compiler for HLL procedures. Therefore, it is possible to stop in the procedure, reference its variables by name, and receive information on variable types.

Code segments, which are not part of such procedures are grouped by the assembler to form dummy procedures. Dummy procedures start at the first non procedural statement and end at the last non procedural statement of the assembly source file. The name of the dummy procedure is of the form .Xbasename number, where basename is the source file name without the .s or .asm suffix; and number is the file segment number.

Every assembler label with a storage allocation directive (e.g. .double, .blkd) is given a type based on the storage allocation. The types are assigned as follows:

Storage Allocation Directives	Corresponding Type
.byte, .blkb	unsigned char
.word, .blkw	short int
.double, .blkd	int
.float, .blkf	float
.long, .blkl	double
.ascii	char

When the .ascii directive is used or when a repetitive factor is specified for any other storage allocation directive, the associated label is considered an array of the corresponding type.

Each procedure defined using the GNX Assembler Procedure Support will also be given a type based on the return value specified by the .endproc directive. If the return value is omitted, a default int or float will be assigned. The types are assigned as follows:

Return Value Modifer	Procedure Type
b	char
w	short int
d	int
f	float
1	long
ub	unsigned char
uw	unsigned short
ud	unsigned int

If the input source file contains . 1n directives, no symbolic debugging information will be prepared by the assembler; instead, information from the .1n directive will be used to generate the line number entry.

9.4 ASSEMBLER OUTPUT LISTINGS

Figure 9-2 shows a sample assembly language program. The listing produced when the program is assembled is shown in Figure 9-3. Figure 9-4 is an annotated version of Figure 9-3.

```
.set
               p_start, 8
        .dsect param_list, p_start
        .blkd
vname:
num:
        .blkd
        .text
indirect_add:
       enter
               [r4], 0
               0(vname(fp)), r4
       movd
        addd
               num(fp), r4
       movd r4, 0(vname(fp))
       exit
              [r4]
       ret
```

Figure 9-2. Sample Assembly Program

```
GNX Assembler Version X.XX
                                date
                                              Page: 1
##### File "examp1.s" #####
        A******
     1
                   00000008
                                         .set
                                                 p_start, 8
     2
                                         .dsect
                                                 param_list, p_start
     3
        A0000008
                                         .blkd
                                vname:
     4
        A000000c
                                num:
                                         .blkd
     5
                                         .text
     6
       T00000000
                                 indirect_add:
     7
        T00000000 821000
                                         enter
                                                 [r4], 0
       T00000003
                  17810800
                                                 0(vname(fp)), r4
     8
                                         movd
     9
        T00000007
                   03c10c
                                         addd
                                                 num(fp), r4
    10
       T0000000a 17240800
                                                 r4, 0(vname(fp))
                                         movd
        T0000000e 9208
    11
                                         exit
                                                 [r4]
    12
        T00000010
                  1200
                                                 0
                                         ret
```

Figure 9-3. GNX Assembler Listing File

1 2 GNX Assembler Version X.XX date Page: 1 3 ##### File "examp1.s" ##### 4 5 7 6 1 A***** 00000008 p_start, 8 .set .dsect param_list, p_start 3 A00000008 .blkd vname: 4 A000000c num: .blkd 5 .text 6 T00000000 indirect_add: 7 T00000000 821000 énter [r4], 0 8 T00000003 17810800 movd 0(vname(fp)), r4 9 T00000007 03c10c addd num(fp), r4 10 T0000000a 17240800 r4, 0(vname(fp)) movd 11 T0000000e 9208 exit [r4] 12 T00000010 1200 ret 0 Callouts 1 to 7: 1 Version number of a tool Listed file page number 3 Source file name. Will reflect included files. 4 Source file line number. 5 Address of the current line. Preceded by letter representing the section of address. 6 Code or value of source line. 7 User source line itself.

Figure 9-4. GNX Assembler Listing File (Annotated Version)

Figure 9-5 shows a sample assembly language program containing floating-point instructions. The listing produced when the program is assembled with a request for libHfp emulation is shown in Figure 9-6. For a detailed description of the libHfp interface, Refer to Chapter 6 of the Series 32000 GNX-Version 4 Support Libraries Reference Manual.

```
.data
fp_var: .blkf
         .text
lab1:
        enter
                 [],0
addf
        f0, f2
addl
        14, 16
movf
        f2, fp_var
exit
        []
ret
        0
```

Figure 9-5. Sample Assembly Program With Floating Point Instructions

```
##### File "examp2.s" #####
    1
                                         .data
     2
       D00000000 00000000
                                fp_var: .blkf
     3
                                         .text
     4 T00000000
                                lab1:
     5 T00000000
                   820000
                                         enter
                                                 [],0
       T******
                                         addf
                                                 f0, f2
        T00000003
                   e7adc000 ***
                                        addr
                                                 F2___, tos
                   0000
        T00000009
                   d7adc000 ***
                                                 F0___, tos
                                        movd
                   0000
        T0000000f
                   02ffffff ***
                                                 addf___
                                        bsr
     7 T******
                                                 14, 16
                                         addl
        T00000014
                   e7adc000 ***
                                         addr
                                                 F6___, tos
                   0000
        T0000001a d7adc000 ***
                                                 F4_{+4}, tos
                                        movd
                   0004
        T00000020
                   d7adc000 ***
                                                 F4___, tos
                                        movd
                   0000
        T00000026
                   02ffffff ***
                                         bsr
                                                 addl___
       ጥ******
                                                 f2, fp_var
                                         movf
        T0000002b
                   57adc000 ***
                                                 F2___, fp_var
                                         movd
                   0000c000
                   003c
     9 T00000035 9200
                                                 []
                                         exit
    10 T00000037 1200
                                         ret
                                                 0
```

Figure 9-6. GNX Assembler Listing File With libHfp Interface

Note that emulated instructions are marked with ***.

A sample program with one error is shown in Figure 9-7. When the program is assembled, the error is flagged as shown in Figure 9-8. Assembly errors are discussed in Section 9.5.

```
main::
        enter
                 []
        addr
                msq, tos
        isr
                _printf
        adispb $-4
        exit
                 []
        ret
                 0
        .data
        .ascii "Hello, world\n\0"
msa:
```

Figure 9-7. A Sample Program Containing Errors

```
GNX Assembler Version X.XX
                               date
                                             Page: 1
##### File "examp3.s" #####
     1
                                 _main::
     2
                                          enter
                                                  []
"examp3.s", line 2: Too few operands specified, 2 operands expected.
     3
                                          addr
                                                  msq, tos
     4
                                          jsr
                                                  _printf
     5
                                          adjspb $-4
                                          exit
                                                  []
     6
     7
                                                  0
                                          ret
     9
                                          .data
    10
                                          .ascii "Hello, world\n\0"
                                 msq:
ERRORS DETECTED : 1.
```

Figure 9-8. GNX Assembler Listing File With Error Mesage

9.4.1 Assembler Symbol Table Listing

The symbol table listing will be entitled "Symbol Table Dump." It will be preceded by a formfeed, and will be output to the specified file. If no output file is specified for it, the symbol table will be output either to stdout (On UNIX/MS-DOS systems), or to the .MAP file (On VMS systems).

Figure 9-9 shows a sample symbol table source file, and Figure 9-10 shows a sample symbol table listing.

```
.set x, 10
bsr foo
movd foo, r0
foo:
    .globl blap
movd blap, r0
```

GF-09-0-U

Figure 9-9. Sample GNX Assembler Symbol Table Source File

```
GNX Assembler Version X.XX date Page: 1
Symbol Table Dump

Symbol Value Section
blap 0X0 undefined, external
foo 0X8 .text
```

GF-10-0-U

Figure 9-10. Sample GNX Assembler Symbol Table Listing

The symbols are listed in the order in which they are encountered. The first column of the output is the name of the symbol, the second column is the value (in hexadecimal) of the symbol, and the last column is the name of the section to which it belongs.

9.4.2 Cross-Reference Table Listing

The cross-reference listing will be entitled "Cross-Reference Table". It will be preceded by a formfeed, and will be output to the specified file. If no output file is specified for it, the cross reference will be output either to stdout (On UNIX/MS-DOS systems), or to the .XRF file (On VMS systems).

Figure 9-11 shows a sample cross-reference source file, and Figure 9-12 shows a sample cross-reference table listing.

```
.set x, 10
      bsr foo
      movd foo, r0
foo:
      .globl blap
      movd blap, r0
```

GF-11-0-U

Figure 9-11. Sample GNX Assembler Cross-Reference Source File

```
GNX Assembler Version X.XX date
                                              Page: 1
Cross Reference Table
blap
      5+
                    4^
foo
      2
              3
      1-
х
```

GF-012-0-U

Figure 9-12. Sample GNX Assembler Cross-Reference Table Listing

Symbols will be listed in alphabetical order. The numbers listed beside the line numbers are the source lines where the symbol appears. A heside a line number indicates that the symbol is declared on that line. A + beside a line number indicates that the symbol is imported/exported (declared with a .glob1 directive) on that line. Abeside a line number indicates that the symbol is set (or reset with a .set directive) on that line.

9.5 GNX ASSEMBLER ERRORS

When the assembler finds an error, it provides an error message through standard error. If the -L option flag on UNIX/MS-DOS systems (or /LIST on VMS) has been selected, the assembler includes the error message in the listing file following the line containing the error. Most errors will inhibit the assembler from generating any further object code (refer to Figure 9-8).

9.6 GNX ASSEMBLER LIMITATIONS

This section contains a list of limitations of the GNX Assembler.

Expression:

Expressions are calculated as 4-byte integers. High order bytes/bits are filled with zero.

Line:

The length of the input line is limited to 64K characters.

Range of values:

The range of values for displacements is:

byte displacement:

-64 to 63

word displacement:

-8192 to 8191

double-word displacement: -536870912 to 536870911

ie:

-(2**29) to (2**29 - 1)

The range of values for floating-point constants is:

single precision:

1.17549436 x 10**-38 to 3.40282346 x 10**38 and

 $-1.17549436 \times 10**-38$ to $-3.40282346 \times 10**38$

double precision:

2.2250738585072014 x 10**-308 to 1.7976931348623157 x 10**308 and $-2.2250738585072014 \times 10**-308$ to $-1.7976931348623157 \times 10**308$

The range of values for integer constants is:

byte constants:

-128 to 255

word constants:

-32768 to 65535

double-word constants: -2147483648 to 2147483647

ie:

-2**31 to (2**31-1)

Section:

The length of a section name as specified with the $\,$.section directive must be up to 8 characters.

The number of sections are limited to 10 sections.

- By default, the first 5 sections are: .text, .data, .bss, .link, and .static.
- If there are module table entries there is a .mod section.
- If there are .ident directives there is a .comment section.
- Therefore, there are only 3 to 5 sections that can be defined by the user in the assembly source level.

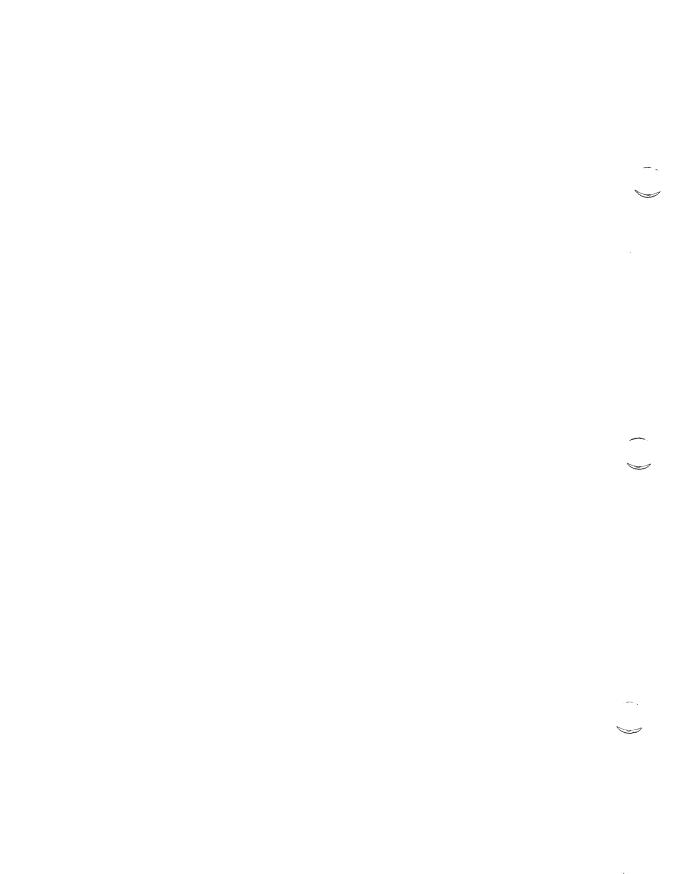
String:

The string length is limited to 256 characters.

Symbol name:

The length of a symbol name in the Cross-reference Table (-x flag on UNIX/MS-DOS or /XREF qualifier on VMS) is truncated to 14 characters.

The length of a symbol name in the Symbol Table Dump (-y flag on UNIX/MS-DOS or /MAP qualifier on VMS) is truncated to 14 characters.



Appendix A

DIRECTIVE SUMMARY

The following is a comprehensive summary of the GNX Assembler Directives.

SYMBOL GENERATION .set symbol, expression sets symbol to the value and type specified by expression. Scope is local.

DATA GENERATION

[label] .ascii string generates a string constant. string specifies constant value.

[label].byte([[repetition-factor]]{expression | string}),,, generates byte constant or string. expression string specifies constant repetition-factor specifies number of occurrences of value.

[label] .word([[repetition-factor]] {expression | string}),,, generates word expression constants. specifies constant value.

[label].double([[repetition-factor]]{expression | string}),,, generates double-word constants.

[label] .float([[repetition-factor]]expression),,, generates single-precision floating-point constants.

[label].long([[repetition-factor]]expression),,, generates double-precision floating-point constants.

[label] .field([subfield-length]subfield-value),,, generates bit fields. subfield-length specifies length of field. subfield-value specifies field value.

[label] .xpd expression	generates external procedure descriptor. expression specifies an external function name.
[label] .xdd expression	generates external data descriptor. <i>expression</i> specifies a double-word value.
STORAGE ALLOCATION	
[label] .blkb [expression]	allocates consecutive bytes of memory for storage. <i>expression</i> specifies the number of bytes.
[label] .blkw [expression]	allocates consecutive words of memory for storage. <i>expression</i> specifies the number of words.
[label] .blkd [expression]	allocates consecutive double-words of memory for storage. <i>expression</i> specifies the number of double-words.
[label] .blkf [expression]	allocates consecutive double-words for single-precision floating-point storage. <i>expression</i> specifies the number of double-words.
[label] .blkl [expression]	allocates consecutive quad-words for double-precision floating-point storage. <i>expression</i> specifies the number of quad-words.
[label] .space expression	allocates consecutive bytes for storage. <i>expression</i> specifies the number of bytes.
LISTING CONTROL	
[label] .title $string$	prints the specified <i>string</i> at the top of each page of the listing file.
[label] .subtitle $string$	prints the specified <i>string</i> at the top of each page of the listing file and below the title string (if any).

MODULE TABLE DIRECTIVES

.module name [,sb=static base][,lb=link base][,pb=program base]

declares a module name, associates the text, link, and static local data segments generated by the assembly with the module name and optionally defines a module table entry. *Name* is the module name.

.modentry name [,sb=static base][,lb=link base] [,pb=program base]

defines a module table entry for a named module Name is the module name

FILE NAME DIRECTIVE

.file "symbol"

assigns the source filename *symbol* to the current assembly.

SYMBOL TABLE ENTRY DEFINITION DIRECTIVES

.def symbol specifies the start of the definition of a sym-

bol table entry for symbol.

.dim expression,,, specifies the dimensions of an array variable.

Up to four dimensions may be specified.

.line expression specifies the source file line number, expres-

sion, on which a symbol is defined.

.scl expression specifies the storage classification, expres-

sion, of a symbol.

.size expression expression specifies the size in bytes of a

symbol.

.tag symbol specifies the tag name of a structured

data type.

. type expression specifies the type, expression, of a symbol.

.val expression expression specifies the value of the symbol

that is being defined.

terminates the definition of a symbol table entry.

.endef

LINE NUMBER TABLE CONTROL DIRECTIVE

.ln expression1 [, expression2] specifies the source file line number offset

from the start of a function and an optional,

associated memory address.

MACRO DEFINITION DIRECTIVES

.macro macro-name formal-argument-list begins the definition of the macro-procedure.

end the macro-procedure definition.

.if if_condition begins a conditional macro assembler state-

ment.

.elsif elsif_condition specifies an elsif clause for the conditional

macro assembler statement.

.else else_conditional_body specifies an else clause for the conditional

macro assembler statement.

.endif ends the conditional macro assembler state-

ment.

.repeat [iteration_count[,iteration_var]]begins a macro repetitive block.

.irp iteration_var,iteration_list begins a special macro repetitive block.

. endr ends a macro repetitive block.

.exit ends the processing of the current repetitive

block.

.macro_on enables macro-procedure expansions.

.macro_off disables macro-procedure expansions.

.include included file allows for the inclusion of text from another

file.

.mwarning warning_message generates an assembler warning message.

.merror error_message generates an assembler error message.

PROCEDURE SUPPORT DIRECTIVES

.proc marks the definition point of an ordinary

procedure.

.proct marks the definition point of a trap pro-

cedure.

.proci marks the definition point of an interrupt

procedure.

.var starts the variable block definition.

.begin begins the procedure body.

.endproc ends the procedure body.

.call issues a procedure call.

Appendix B

GNX ASSEMBLER RESERVED SYMBOLS

B.1 INTRODUCTION

This appendix contains lists of the GNX-Version 4 Assembler reserved symbols (i.e., instructions, registers, directives, addressing mode indicators, flags, qualifiers, and temporary labels).

The following instructions must be lower-case. NOTE:

B.2 STANDARD INSTRUCTIONS

absb	$_{ m bgt}$	cmpmw	ibitb	movqw
absw	bhi	\mathbf{cmpmd}	ibitw	movqd
absd	bhs	cmpqb	ibitd	movsb
acbb	ble	cmpqw	indexb	movsw
acbw	blo	cmpqd	indexw	movsd
acbd	bls	${f cmpsb}$	indexd	movst
addb	\mathbf{blt}	cmpsw	insb	movsub
addw	bne	cmpsd	insw	movsuw
addd	\mathbf{br}	cmpst	insd	movsud
addcb	bicb	$\operatorname{\mathbf{comb}}$	inssb	movusb
addcw	bicw	comw	inssw	movusw
addcd	bicd	\mathbf{comd}	inssd	movusd
addpb	bicpsrb	cvtp	jsr	movxbd
addpw	bicpsrw	cxp	jump	movxwd
addpd	bispsrb	cxpd	lmr	movxbw
addqb	bispsrw	deib	lprb	movzbd
addqw	${ t bpt}$	deiw	lprw	movzwd
addqd	bsr	deid	lprd	movzbw
addr	caseb	dia	lshb	\mathbf{mulb}
adjspb	casew	divb	lshw	mulw
adjspw	cased	divw	lshd	muld
adjspd	cbitb	divd	meib	$_{ m negb}$
andb	cbitw	enter	meiw	negw
andw	cbitd	exit	meid	negd
andd	cbitib	\mathbf{extb}	\mathbf{modb}	nop
ashb	cbitiw	extw	\mathbf{modw}	notb
ashw	cbitid	extd	\mathbf{modd}	notw
ashd	checkb	extsb	movb	notd
bcc	checkw	extsw	movw	orb
bcs	checkd	extsd	movd	orw
beq	\mathbf{cmpb}	\mathbf{ffsb}	\mathbf{movmb}	ord
bfc	cmpw	ffsw	movmw	quob
bfs	cmpd	\mathbf{ffsd}	movmd	quow
bge	cmpmb	flag	movqb	quod

STANDARD INSTRUCTIONS (CONT)

rdval	sbitid	sged	slsd	\mathbf{subd}
remb	sccb	sgtb	sltb	subcb
remw	sccw	sgtw	sltw	subcw
remd	\mathbf{sccd}	$\operatorname{\mathbf{sgtd}}$	sltd	\mathbf{subcd}
restore	scsb	\mathbf{shib}	\mathbf{sneb}	${f subpb}$
ret	scsw	shiw	snew	subpw
reti	scsd	shid	sned	\mathbf{subpd}
rett	\mathbf{seqb}	shsb	setcfg	svc
rotb	seqw	shsw	skpsb	tbitb
rotw	\mathbf{seqd}	shsd	\mathbf{skpsw}	tbitw
rotd	sfcb	sleb	skpsd	tbitd
rxp	sfcw	slew	\mathbf{skpst}	wait
save	\mathbf{sfcd}	sled	smr	wrval
\mathbf{sbitb}	sfsb	${f slob}$	sprb	\mathbf{xorb}
sbitw	sfsw	slow	sprw	xorw
\mathbf{sbitd}	\mathbf{sfsd}	slod	sprd	xord
sbitib	sgeb	${f slsb}$	$\overline{\mathrm{subb}}$	
sbitiw	sgew	slsw	subw	

B.3 NS32081 FLOATING-POINT INSTRUCTIONS

absf	floorfw	movbl	negf	subf
absl	${f floorfd}$	movwl	negl	subl
addf	floorlb	movdl	roundfb	truncfb
addl	floorlw	movf	roundfw	truncfw
cmpf	floorld	movl	roundfd	truncfd
cmpl	lfsr	movfl	roundlb	trunclb
divf	\mathbf{movbf}	movlf	roundlw	trunclw
divl	movwf	mulf	roundld	truncld
floorfb	\mathbf{movdf}	mull	sfsr	

B.4 NS32181AND NS32381 FLOATING-POINT INSTRUCTIONS

absf	floorfd	movdl	negl	scalbl
absl	floorfw	movf	polyf	sfsr
addf	${f floorlb}$	movfl	polyl	subf
addl	floorld	movl	roundfb	subl
cmpf	floorlw	movlf	roundfd	truncfb
cmpl	lfsr	movwf	roundfw	${f truncfd}$
divf	logbf	movwl	roundlb	truncfw
divl	logbl	mulf	roundld	trunclb
dotf	movbf	mull	roundlw	truncld
dotl	movbl	negf	scalbf	trunclw
floorfb	movdf			

B.5 NS32580 FLOATING-POINT INSTRUCTIONS

absf	floorlb	movfl	roundfw	trucnfw
absl	floorld	movl	roundlb	trunclb
addf	floorlw	movlf	roundld	truncld
addl	lfsr	movwf	roundlw	trunclw
cmpf	macf	movwl	sqrtf	
cmpl	macl	mulf	\mathbf{sqrtl}	
divf	movbf	mull	sfsr	
divl	movbl	negf	subf	
floorfb	movdf	negl	subl	
floorfd	\mathbf{movdl}	roundfb	truncfb	
floorfw	movf	roundfd	truncfd	

B.6 NS32CG16.NS32CG160AND NS32FX16HIGH PERFORMANCE GRAPHIC INSTRUCTION

bband bbstod extbl thits movmpw bbfor bbxor movmpb sbitps bbor hitwit movmpd shits

B.7 NS32GX320 HIGH PERFORMANCE DSP INSTRUCTION

mulwd mactd cmacd cmuld

B.8 NS32532 CPU INSTRUCTION

cinv

B.9 STANDARD REGISTERS

fp r0r4 spintbase r1**r**5 upsr mod r2r6sbr3psr r7

B.10 NS32082 MMU REGISTERS

bcnt eia 0lq ptb0 sc0bpr0 msr pf1 ptb1 sc1 bpr1

B.11 NS32382MMU REGISTERS

bar bdr bear msr bmr mcr ivar0 ivar1 ptb0 ptb1 tear

B.12 NS32081 FLOATING-POINT REGISTERS

f0	f2	f4	f6
fl	f3	f5	f 7

B.13 NS32181,NS32381 AND NS32580 FLOATING-POINT REGISTERS

f0	f2	f4	f6
f1	f3	f5	f7
10	12	l4	16
11	13	l5	17

B.14 NS32532 CPU REGISTERS

bpc	dcr	ivar1	ptb0	tear
car	dsr	mcr	ptb1	usp
cfg	ivar0	msr		

B.15 STANDARD DIRECTIVES

.align	.data	.file	.sb	.text
.ascii	$.\mathbf{def}$.globl	.scl	.title
.blkb	.dim	.ident	.section	$. \mathbf{type}$
.blkw	.double	.line	$.\mathbf{set}$.udata
.blkd	$. \mathbf{dsect}$.link	.size	.val
.bss	.eject	.list	.space	.width
.byte	.endef	.ln	.static	.word
.comm	.field	.nolist	.subtitle	.xdd
		.org	.tag	.xpd

B.16 FLOATING-POINT DIRECTIVES

.blkf .blkl .float .long

B.17 MACRO DEFINITION DIRECTIVES

.macro .endm .if .else .endif .elsif .repeat .irp .endr .exit .macro_on .macro_off .include .mwarning .merror

B.18 PROCEDURE SUPPORT DIRECTIVES

.proc .proct .proci .var .begin

.endproc .call

B.19 PROCEDURE SUPPORT PREDEFINED SYMBOLS

param_size var_size

B.20 MODULARITY DIRECTIVES

.module .modentry

B.21 ADDRESSING MODE INDICATORS

ext tos

B.22 FLAGS

 $\qquad \qquad b \qquad \qquad f \qquad \qquad m \qquad \qquad u \qquad \qquad w$

\

B.23 NS32332 SETCFG FLAGS fc ff fm p B.24 NS32CG160 SETCFG FLAGS de

B.25 MODULARITY OPTION FLAGS

lb pb

B.26 NS32CG16 OPTION FLAGS

da ia -s s

B.27 SCALED INDEX QUALIFIERS

 $b \hspace{1cm} w \hspace{1cm} q \hspace{1cm} d$

B.28 NS32532 OPTION FLAGS

 $a \hspace{1.5cm} d \hspace{1.5cm} i \\$

B.29 TEMPORARY LABELS

lf 2f3f4f 5f 6f 7f8f 9f 1b 2b 3b 4b 5b 6b 7b8b 9b

Appendix C

PROGRAM EXAMPLES

C.1 INTRODUCTION

This appendix provides sample assembly programs that illustrate various features of the GNX Assembler. The programs are written in the GNX C compiler style of code generation.

C.2 FACTORIAL NUMBERS

This example illustrates procedure calls between two separately assembled software modules and an object language library module. The assembly language modules implement a factorial number algorithm; the procedure in the library prints out the result.

The two assembly language modules are main.s, which contains the procedure _main, and fac.s, which contains the procedure _fac. The procedure _main calls the external procedure _fac; an argument is passed, and a value is returned in r0.

The procedure _fac returns any factorial number that can be represented by a double-word integer. (The factorial of a number n is the product $1 \times 2 \dots \times n$.) If $_$ fac is passed as an argument whose factorial cannot be represented as a double-word integer, it returns the integer unchanged and sets the f flag of the psr. This condition is checked by the flag instruction on return to _main.

The _main makes three calls to _fac, and then calls the C Library routine _printf to print the result on standard output. The _printf is contained in the object file /lib/crt0.o.

The two assembly language modules are assembled separately and then linked with the library object module as follows:

```
as main.s
as fac.s
ld /lib/crt0.o main.o fac.o -lc
```

The module, main.s:

```
.file "main.s"
       .text
       .globl _main
       .globl _printf
                             # Import external C Library procedure.
       .globl _fac
                              # Import external procedure _fac.
       .data
print: .byte "%d %d %d\12\0" # Formatting input for _printf.
       .text
_main::
       enter [r0],0
                             # Push previous contents of r0 on stack.
      movgd 1,r0
                              # Pass input-value 1 to external
             _fac
                              # procedure _fac in r0.
      bsr
      flag
                              # Check for out-of-bounds error.
      movd r0,tos
                              # Push returned answer in r0 on stack.
      movgd 6,r0
                              # Prepare to pass input-value 6 to _fac.
      bsr _fac
       flag
      movd r0, tos
       addr @12,r0
                             # Prepare to pass input-value 12 to _fac.
      bsr
             _fac
       flag
      movd r0, tos
       addr print, tos
                             # Push formatting arguments for _printf on
                              # stack and print answers.
       bsr
             _printf
                              # Adjust stack pointer to allow for
       adjspb $-16
                              # arguments passed to _printf.
                              # Restore previous contents of r0.
       exit
            [r0]
                             # Return from _main.
       ret
```

```
The module, fac.s:
```

```
.file
                "fac.s"
        .text
        .globl
                _fac
        .data
        .double 1
q:
        .double 1
        .double 2
        .double 6
        .double 24
        .double 120
        .double 720
        .double 5040
        .double 40320
        .double 362880
        .double 3628800
        .double 39916800
        .double 479001600
        .text
_fac::
num:
       cmpd
                r0,$12
                              # Check for in-bounds (must be less than 13).
       bhi
                error
                              # If not, branch to error handler.
       movd
                g[r0:d],r0
                              # Otherwise, scale-index into the array for
                              # corresponding factorial result and
       ret
                              # move to r0.
error: bispsrb b'00100000
                              # Set the psr f bit to "1" for detection by
       ret
                0
                              # flag in calling program.
```

C.3 SQUARE ROOT CALCULATION

This example illustrates local procedure calls, i.e., calls to procedures in the same assembly file. The procedure _main calls the local procedure _sqrt and passes it to an input-value on the stack. The sqrt calculates the square root of a positive integer using a successive approximation algorithm. If sqrt is passed a nonpositive integer, the integer is returned unchanged on the stack, and the f flag of the psr is set. Otherwise, the answer (i.e., the closest integer less than or equal to the square root of the input-value) is returned on the stack and printed out using _printf.

The module sort is assembled and linked as follows:

```
as sgrt.s
   ld /lib/crt0.o sqrt.o -lc
       .file
                   "sqrt.s"
       .text
       .globl
                   _main
       .glob1
                   _printf
                              # Import external C Library procedure.
       .data
print: .byte "%d %d",0xa,0x0 # Formatting input for _printf.
       .text
_main::
       enter
                [],4
                              # Pass input-value 1 to local procedure _sqrt
       movad
                $1,tos
       bsr
                _sqrt
                              # via stack.
       flag
                              # Check for illegal negative input-value.
       movad
                $4,tos
                              # Pass input-value 4 to local procedure _sqrt
       bsr
                _sqrt
       flag
                              # Push formatting input for _printf on stack.
       addr
                print, tos
       bsr
                _printf
                              # Print formatted answers.
       adispb
                $-12
                              # Adjust stack pointer in allowance for input
                [ ]
       exit
                              # to _printf.
                              # Return from _main.
       ret
_sqrt:
       enter [r0, r1, r2],0
                              # Save contents of registers to be used
                              # on stack.
                              # Start guessing square-root as 1.
       movqd
                $1,r0
       movd
                              # Get the passed parameter on the stack.
                8(fp),r1
                              # Check for illegal negative input.
       cmpd
                r1,$0
       ble
                error
                              # If so, branch to error-handler.
                              # Otherwise, make a copy and divide the copy
loop:
       movd
                r1,r2
       divd
                r0,r2
                              # by the initial guess.
       cmpd
                r0,r2
                              # Is the answer ready yet?
       addd
                              # Sum the result and the guess.
                r0,r2
                              # Take their average.
       ashd
                $-1,r2
       movd
                r2,r0
                              # Make the next guess.
       bhi
                              # If answer not ready yet, continue.
                loop
       movd
                r0.8(fp)
                              # Otherwise, return the answer
       br
                              # and exit.
                exits
                               # Set the PSR F bit to "1" for detection by
error: bispsrb b'00100000
```

flag after return from procedure.

[r0,r1,r2]

exits: exit

C.4 ACKERMAN'S FUNCTION

This example contains an assembly language program produced by the GNX C compiler. The C program implements Ackerman's function, a well-known example of a recursive procedure that terminates for all positive integer values of its two parameters. Following the C program is the optimized assembler output from the GNX C compiler.

The program is compiled as follows:

}

```
cc -0 -S ack.c
The C program:
  main()
  {
           int i=3, j=3;
           printf("%d\n",ack(i,j));
  ack(a,b)
  int a,b;
           if (a==0)
                    return(b+1);
           else if (b==0)
                    return (ack(a-1,1));
           else
```

The optimized assembly code for the above C program:

```
.text
.data
.text
.globl
         _main
                 .file "ack.c"
         .align 4
.data
.text
.glob1
         _ack
.data
.globl
                                  # Import external C library procedure.
         _printf
.L17:
.ascii
         "%d\12\0"
                                  # Formatting input for _printf.
.text
_main:
                 [],8
                                  # Allow for the amount of data to be
         enter
         movqd
                 3,-4(fp)
                                  # pushed on stack.
                 3,-8(fp)
                                  # Allocate input-values to data storage
         movqd
                                  # area of procedure _main and push on
         movd
                 -8(fp),tos
         movd
                 -4(fp), tos
                                  # stack in preparation to call external
```

return(ack(a-1,ack(a,b-1)));

```
bsr
                 \_ack
                                  # procedure _ack.
         adjspb $-8
                                  # Adjust stack pointer in allowance for
         movd
                 r0,tos
                                  # input to _ack and push returned answer
         addr
                 .L17,tos
                                  # in r0 on stack
         bsr
                 _printf
                                  # Print answer.
         adjspb $-8
                                  # Adjust stack pointer in allowance for
         exit
                 []
                                  # input to _printf and exit _main,
         ret
                 0
                                  # adjusting stack for initial data input.
         .align 4
_ack:
                 [],0
         enter
         cmpad
                 0.8(fp)
                                  # If a is equal to 0 then,
         bne
                 .L23
                                  # add 1 to b,
         movqd
                 1,r0
         addd
                 12(fp), r0
                                  # using r0, and
         br
                 .L20
                                  # branch to exit _ack.
L2000001:
         movad
                 1,tos
                                  # Push 1 on stack as 2nd argument
                                  # to _ack.
L2000005:
         movd
                 8(fp),r0
                                  # Move a to r0,
                                  # subtract 1 and push on stack as 1st
         addr
                 -1(r0), tos
                                  # argument to _ack, then call _ack.
         bsr
                 \_ack
         adispb $-8
                                  # Adjust stack pointer in allowance for
                                  # arguments to _ack pushed on stack.
.L20:
         exit
                 []
                                  # Exit _ack.
         ret
                 0
.L23:
                                  # If a is not equal to 0 and b is equal
         cmpqd
                 0,12(fp)
                 L2000001
                                  # to 0 then branch to L2000001.
         beq
                 12(fp),r0
                                  # Else move b to r0, subtract 1 and
         movd
                                  # push on stack as 2nd argument to _ack.
         addr
                 -1(r0),tos
         movd
                 8(fp),tos
                                  # Then push a on stack as 1st argument
         bsr
                 ack
                                  # to _ack and call _ack.
                                  # Adjust stack pointer for arguments.
         adjspb $-8
                                  # Push result in r0 on stack as 2nd
         movd
                 r0,tos
         br
                 L2000005
                                  # argument to _ack in recursive call.
                                  # Branch to L2000005 for 1st argument.
```

C.5 STRING SORTING

This example implements a bubble-sorting algorithm for an array of pointers to strings. A bubble-sorting algorithm performs successive exchanges of unordered neighbors. The algorithm may be represented in C as follows:

```
string sort(e cnt,array)
char *array[];
int e_cnt;
   char *temp:
   int f. i:
   f = e cnt;
  while (f-- > 0) {
                   for (i = 0; i < f; i++) {
                            if (strcmp(array[i], array[i+1]) > 0) {
                                    temp = arrav[i]:
                                    arrav[i] = arrav[i+1];
                                    arrav[i+1] = temp;
                            }
                   }
  }
}
```

An assembly language module, sorts, implementing the bubble sort algorithm is given below. The external procedure sort performs a bubble sort on a passed string array. The maximum allowed length of a string is "max length," an imported variable. The array address ("array") and element count ("e cnt") are passed on the stack, with "e_cnt" on top.

```
.file
                 "sort.s"
         .globl max length
         .dsect args, 8
                                        # Set argument offsets from fp.
         .blkd
array:
e_cnt:
         .blkd
         .text
sort::
         enter
                 [r0,r1,r2,r3,r4,r7],0
         movd
                 e cnt(fp),r3
                                        # Set e_cnt to range-limit for loop1.
loop2:
         addqd
                 -1.r3
                                        # Set range-limit to range-limit - 1.
         cmpd
                 0,r3
                                        # Branch to p_exit if range-limit
         beq
                 p_exit
                                        # is equal to 0.
                 0,r7
                                        # For i = 0 ...
         movqd
loop1:
                 r3, r7
                                        # ... to range-limit.
         cmpd
                                        # Branch to loop2 on reaching range-limit.
         beq
                 loop2
         movd
                 max_length,r0
                                        # Set string-length limit for cmpsb.
         movd
                 0(array(fp))[r7:d],r1 # Set up array[i].
                                         # i = i + 1.
         addqd
         movd
                 0(array(fp))[r7:d],r2 # Set up array[i+1].
         movad
                 0,r4
                                         # Set up end of string.
         cmpsb
                                        # If string(array[i]) > string(array[i+1])
         bls
                 loop1
                                        # continue, otherwise branch to next pair.
                 0(array(fp))[r7:d],r0 # Get address of array[i+1].
         addr
         movd
                 -4(r0), r1
                                        # temp = array[i].
                 0(r0), -4(r0)
                                        # array[i] = array[i+1].
         movd
         movd
                 r1,0(r0)
                                        \# array[i+1] = temp.
         br
                 10001
                 [r0,r1,r2,r3,r4,r7]
p_exit: exit
```

C.6 MODULAR CODE EXAMPLE

This example shows a Series 32000 module built from a single source file.

```
# Declare the module
2
    # We specify the static and link base, the program base defaults to .text.
3
4
                                      .file
                                                "hello.s"
5
    M00000000
                1c000000
                                      .module
                                               hello, sb = .static, lb = .link
                18000000
                00000000
                00000000
7
                                      .link
                                                            # Begin link segment,
8
                                                            # 1b will point here
9
10
    L00000000
                00000000
                           printf:
                                                _printf
                                                            # Local link table entry for _printf
                                      .xpd
11
                                                            # Begin code segment,
12
                                      .text
13
                                                            # pb will point here
14
15
                            _main::
16
    T00000000
                820000
                                      enter
                                                [], 0
17
    T00000003
                e7d5c000
                                     addr
                                                msg, tos
                0000
    T00000009
                22c00000
18
                                      схр
                                                printf
                00
19
    T00000000e
                7ca5fc
                                     adjspb
                                                $-4
    T00000011
                9200
                                      exit
20
                                                []
21
    T00000013
                3200
                                      rxp
22
23
                                      .static
                                                            # Begin static segment,
24
                                                            # sb will point here
25
                            msg:
                                                "Hello, World!\012\0"
26
    S00000000
                48656c6c
                                      .byte
                 6f2c2057
                 6f726c64
                 210a00
```

Appendix D

INITIALIZATION OF INTERRUPTS

The following skeleton program illustrates a method of initializing the necessary registers and tables to process the first 10 standard interrupts in a *Series 32000* system with a single ICU. This same technique can be used to initialize the vectored interrupts when needed.

In order to load interrupt vectors at run-time, the appropriate procedure descriptors may be stored in a link table and moved into place during program initialization.

Because the offset portion of the procedure descriptor is 16 bits, the interrupt routines must be within the first 64 Kbytes (65536 bytes) of address space. Since the linker loads files in command line order, this can be accomplished by specifying the object file that contains the interrupt routines early in the load command.

```
.text
start::
#
         Initialize Intbase Register to point to the Interrupt
         Vector Table:
                               # Get address of Interrupt Vector Table.
         addr
                 intvec,r0
         lprd
                 intbase, r0 # Save it in Intbase Register.
         Code for process:
                               # Code for program.
#
         Code for interrupts:
nvi:
                               # Code for non-vectored interrupt.
                               # Code to process interrupt.
                               # Return to interrupted routine.
          reti
nmi:
                               # Non-maskable interrupt.
                               # Code to process interrupt.
          reti
                               # Return to interrupted routine.
                               # Abort interrupt.
abt:
                                         INITIALIZATION OF INTERRUPTS D-1
```

```
# Code to process interrupt.
         reti
                             # Return to interrupted routine.
ignore:
                             # Ignore state.
         reti
                             # Return to interrupted routine.
         .data
         Build Interrupt Vector Table entry by entry.
         Each .xpd directive initializes one entry in the table
         with a procedure descriptor for the appropriate entry
         point. Note that this program chooses not to use
         interrupts 3 through 10, they are set up to be
         ignored.
                             # non-vectored interrupt (always 0)
intvec:
         .xpd
                nvi
                            # non-maskable interrupt (always 1)
                nmi
         .xpd
                abt
                             # abort interrupt (always 2)
         .xpd
                             # FPU (always 3)
         .xpd
                ignore
         .xpd ignore
                             # illegal operation (always 4)
         .xpd ignore
                             # supervisor call (always 5)
                             # divide by zero (always 6)
         .xpd
                ignore
         .xpd ignore
                             # flag (always 7)
         .xpd
               ignore
                             # breakpoint (always 8)
                             # trace (always 9)
         .xpd
                ignore
                             # undefined instruction (always 10)
         .xpd
                 ignore
         11-15 reserved
         16-31 vectored interrupts
```

SERIES 32000 STANDARD CALLING CONVENTIONS

E.1 INTRODUCTION

The main goal of standard calling conventions is to enable the communication between the routines of one program consisting of different modules, even when written in multiple programming languages. The *Series 32000* standard calling conventions support various special language features (such as the ability to pass a variable number of arguments, which is allowed in C) by using the different calling mechanisms of the *Series 32000* architecture. This convention is employed only to call "externally visible" routines. Calls to internal routines may employ even faster calling sequences, by passing arguments in registers, for instance.

Basically, the calling sequence pushes arguments on top of the stack, executes a call instruction, and then pops the stack, using the fewest possible instructions to execute at the maximum speed. The following sections discuss the various aspects of the *Series 32000* standard calling conventions.

E.2 CALLING CONVENTION ELEMENTS

Elements of the standard calling sequence are:

The Argument Stack

Arguments are pushed on the run-time stack from right to left. Therefore, the first (left-most) argument is always at a constant offset from the frame pointer (fp) regardless of how many arguments have been passed. This is important because C allows a variable number of arguments. This does not mean that the actual parameters are always evaluated from right to left. Programs cannot rely on the order of parameter evaluation.

For reasons of efficiency, the run-time stack is required to be aligned to a full double-word boundary. Argument lists always use a whole number of double-words; integer and pointer values use a double-word (by extension, if necessary), floating-point values use eight bytes and are represented as *long* values, structures use a multiple of double-words.

The above conventions allow writing functions which take a variable number of arguments of unknown types, such as the printf function.

Note that the stack alignment is maintained by all of National Semiconductor's optimizing compilers through aligned allocation and de-allocation of local variables. Interrupt routines and other assembly-written interface routines are expected to maintain this double-word alignment.

The caller routine must pop the arguments off the stack, upon return from the called routine.

· Saving registers

General registers R0, R1, and R2 and floating registers F0, F1, F2, and F3 are volatile or unsafe registers whose value may be changed by a called routine These registers need not be saved upon procedure entry, nor restored before exit. If the other registers (R3 through R7, F4 through F7) are used, their value must be saved (onto the stack) by the called routine immediately upon procedure entry and restored immediately before executing the return instruction.

NOTE: Interrupt and trap service routines are required to save/restore all registers they use.

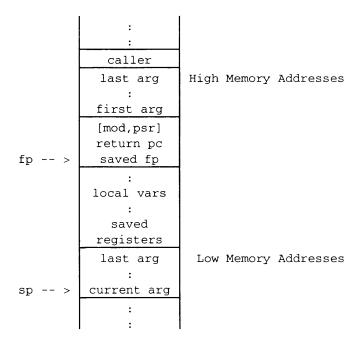
Returned Value

An integer or a pointer value that is returned from a function is returned in (part of) register R0.

A long floating-point value that is returned from a function is returned in register pair F0-F1. A float-returning function returns the value in register F0.

If a function is defined to return a structure, the calling function will pass an additional argument at the beginning of the argument list. This argument points to where the called function will return the structure. The called function copies the structure into the specified location during execution of the return statement. Note that functions which return structures must be correctly declared as such even if the return value is ignored.

When the C optimizing compiler builds an argument list, the layout of the stack looks like this:



Example: given a call to a function func (first, second, third, last):

```
i = func(1, x, *cp, j);
```

with these variable declarations:

```
float x;
register char *cp;
int j;
```

the compiler might generate the following code:

```
movd
        -8(fp),tos #last argument
movzbd
        0(r7),tos #byte argument
movfl
        -4(fp),tos #float argument
                    #first argument
movad
        1,tos
bsr
        _func
        -20
                   #pop args off stack
adjspb
        r0,r6
                   #save return value
movd
```

func might look as follows:

```
enter
        [r7,r6],12 #save regs, alloc vars
mov1
       f6,tos
                     #save floating regs f6 and f7
hvom
       8(fp),r1
                     #put first arg in temp reg
       r7,r0
                     #return value
movd
                     #restore floating regs
movl
       tos, f6
exit
        [r7,r6]
                     #restore reas
ret.
                     #do not pop off args
```

The standard calling sequence decreases the chance of an error which could destroy the stack. Maintaining the stack is crucial since the debugger cannot trace a destroyed stack, and the user must know what functions in a program are currently active.

Appendix F

COMPATIBLY-SUPPORTED MACROS

F.1 INTRODUCTION

This appendix describes the Version 2 and 3 macro-assembler. For compatibility purposes this macro-assembler is still supported in this release, but will be obsolete in Version 5. It is not compatible with the new Version 4 macro-assembler, which is described in Chapter 8.

This old macro-assembler version must be invoked by the -MC invocation option for the UNIX environment, and by the /MCOMPATIBILITY invocation option for the VMS environment.

The following sections explain the process of defining and using old macros.

F.2 DEFINITION OF TERMS

Macro Definition	A method of giving a name to a sequence of instructions. After the macro has been defined, the programmer can write the macro name instead of the sequence of instructions.
Macro Usage	The use of the macro name as an opcode, operand, directive, expression or partial expression.
Macro Expansion	The process of replacing the line containing the macro name with the sequence of instructions from the macro definition. Every formal argument in the macro definition is replaced by the actual argument specified in the macro name.
Formal Arguments	Arguments that are used throughout the sequence of instructions in the macro definition. $ \\$
Actual Arguments	Arguments specified during the actual use of the macro name. These arguments will replace the formal arguments during the macro expansion.

F.3 DEFINING A MACRO

A macro definition consists of three parts: a header, a body, and a terminator. The macro definition is written only once but can be used any number of times. A macro may not be redefined in a single assembly session.

F.3.1 The Macro Header

The header of a macro definition gives the name of the macro being defined. The header consists of the .macro directive, the name of the macro, and a list of arguments to be used in the definition. The .macro directive begins the definition of the macro. The macro definition header is followed by the body of the macro definition. The format of the macro definition header is as follows:

```
.macro macro-name formal-arguments-list
```

where formal-arguments-list is a list of formal arguments, denoted by ?n, and separated by any of the following delimiters:

```
, & [ ] ( )
```

The argument number n ranges from 1 to 9. Some examples of formal-arguments-list are

```
?1, ?2, ?3  #formal arguments are ''?1'', ''?2'', ''?3''
#delimiter is '',''
[?1], ?2, &?3& #formal arguments are ''?1'', ''?2'', ''?3''
#delimiters are ''['', '']'', '','' ''&''
```

The argument number n does not need to follow a consecutive order, so the following formal-arguments-list is also allowed:

```
?2, ?7, ?4
```

Macro names may not be the same as standard assembler mnemonics, directives, or user-defined symbols.

F.3.2 The Macro Body

The body of a macro definition consists of the statements to be inserted into the assembler source code when the macro name is used. The types of statements that are allowed in the body of the macro are current assembly language statements, directives, usage of other macros, and expressions or partial expressions. The macros being used within a macro definition body may be undefined during the time of macro definition, but they must be defined before actual expansion take place.

The body of a macro definition can be empty, i.e., it can contain no statements.

The body of a macro definition cannot contain the definition of another macro name; macro definitions may not be nested.

The formal arguments used in the body of the macro definition are of the form ?n, where n ranges from 1 to 9 as specified in the macro header. During the use of the macro name, the macro body statements are inserted in the source code at the place where the macro is used with every formal parameter being replaced by the corresponding actual parameter using a "string" substitution.

F.3.3 The Macro Terminator

A macro definition is terminated by the .endm pseudo-instruction. During a macro definition, an . endm directive must be found before another .macro directive may be used.

The format of the . endm directive is as follows:

```
.endm
```

The following are three examples of a macro definition:

```
Example 1:
           .macro store ?1, ?2, ?3
                                        # macro name is "store"
                                        # there are 3 formal arguments
           .long
                    ?1
                                        # ?1 is first argument
           .word ?3
                                        # ?3 is third argument
           .byte
                    ?2
                                        # ?2 is second argument
           .endm
Example 2:
           .macro loc
                                        # macro name is "loc"
           4(fp)
                                        # definition body is an expression
           .endm
Example 3:
           .macro fun [?1], ?2, &?3& #macro name is ''fun''
                                        #there are 3 formal arguments
                                        #first argument is delimited by ''[]''
                                        #second argument is delimited by '', ,''
                                        #third argument is delimited by ''& &''
           enter
                    [?1], ?2
                  ?3
           .byte
           exit
                    [?1]
           .endm
```

F.4 USING A MACRO

Macros can be used as directives, operands, opcodes, expressions and even partial expressions. A macro is invoked by using the macro name, followed by a list of the actual arguments to be substituted into the macro definition body if the macro has formal arguments. The format of macro usage is as follows:

macro-name actual-arguments-list

where *macro-name* is the name of a macro which has already been defined, and *actual-arguments-list* is a list of arguments and delimiters following the prototype as specified by the *formal-arguments-list* of the macro definition header. The actual arguments obtained then replace the formal arguments in the macro definition body.

F.4.1 Arguments In Macros

The arguments in the *actual-arguments-list* must be separated by delimiters as specified in the *formal-arguments-list* of the macro definition header. These actual arguments will replace the formal arguments in the order in which they are written using a "string" substitution. Actual arguments not supplied will result in missing arguments during macro expansion. The number of actual arguments associated with the use of the macro must equal the number of formal arguments specified in the macro definition.

All actual arguments will be evaluated at argument usage time, that is, during the time of the expansion of the actual arguments, as opposed to during the time the macro name is used. The actual arguments should be thought of as delimited by leading and trailing spaces so that text concatenations are not possible.

Using the macros defined in Section 8.2, the following are examples of macro usage:

```
Example 1:
    store 3.3, 2, 1

Example 2:
    movd 6, loc

Example 3:
    fun [r0,r1,r2],20, &1,2,3,4,5&
```

Expansion of the macro calls are as follows:

Example 1:

.long 3.3 # 3.3 is the first argument
.word 1 # 1 is the third argument
.byte 2 # 2 is the second argument

Example 2:

movd 6, 4(fp)

Example 3:

enter [r0,r1,r2], 20 # r0,r1,r2 is the first argument # 20 is the second argument .byte 1,2,3,4,5 # 1,2,3,4,5 is the third argument exit [r0,r1,r2]

Appendix G GLOSSARY

.gnxrc (**gnx.ini on VMS**) A GNX target specification file that is used by GNX tools to obtain the CPU, FPU, MMU, system bus-width, and OS target specifications.

Assembly Procedure A procedure defined in the assembly source. It provides for easy programming and interface with HLL written code.

Assembly Program segment Part of an assembly program that resides in a contiguous area. Every GNX assembly program produces at least three program segments in the output object file: text, data, and bss. These segments correspond to the .text, .data, and .bss sections of the COFF file. Other *Series 32000* segments or user-defined sections may be included in the assembly source file.

Assembly directive Provides the assembler with control information. Directives define labels, generate data, define procedures, control program listings, control macro-assembly, allocate storage, control linkage, define module table entries, control line number tables, control program segments, define symbol table entries, and define file names.

Assembly expression A combination of terms and operators which evaluate to a single value and type. Valid expressions include addresses and integer expressions, but not floating-point expressions.

Assembly label A user-defined symbol specified at the beginning of an assembly statement, followed by a colon (:) or a double colon (::).

Assembly statement Composed of an optional label, which is a user-defined symbol; followed by an optional instruction or directive mnemonic that is an assembler-reserved symbol; followed by optional operands that are composed of symbols, constant values, and delimiters.

Built-in Macro Functions A set of macro-assembler functions used to manipulate strings, lists, type conversions and *Series 32000* operands.

COFF Acronym for the Common Object File Format. This is the standard object file format for the Unix System V operating system, and for the GNX software tools. A COFF file contains machine code and data and additional information for relocation and debugging purposes.

Calling convention A standard GNX convention for calling procedures from either an assembly or a HLL written code. It defines the way parameters are passed, register usage and how a value should be returned.

Compound Assembly expression An expression constructed from other assembly expressions using unary and binary operators.

Conditional Macro Statement Sequences of statements specified between the .if and the .endif directives. They are generated according to a condition specified with the .if directive.

Cpp An acronym for the C preprocessor.

Cross configuration When the compilation and execution of the compiled program are done on different machines (the host and target machines are different).

DBUG GNX symbolic debugger. DBUG provides a window-oriented user interface for both X-windows and ASCII terminals. It is used for the symbolic debugging of high level and assembly language programs.

Development board The 32000 based system used for developing/running programs and user applications.

Displacement An integer constant that is specified as part of an instruction operand. Its value is an offset added to a specified base address for operand address calculation. It may be encoded as either a byte, word, or double-word.

Displacement operand A displacement size specification that determines a displacement encoding as either byte, word, or double-word.

Dummy segment Defines a symbolic offset for each of its defined labels. It does not contain generated code or data and does not allocate space. It is useful for overlaying portions of specific segments.

External symbol A symbol which is defined outside the assembled module. It can be defined either in another assembly module or in a HLL module.

Floating-point constant An immediate *Series 32000* floating-point value. Can be either a four byte single precision value or an eight byte double precision value.

Global symbols Global symbols are symbols to be used by multiple software modules, either assembly or HLL modules.

Host machine The machine on which the compiler runs.

Initialized data segment Contains initialized data, follows the .data directive, and corresponds to the .data section of the COFF file. The initialized data segment has the same functionality as initialized data in the C language. This functionality enables the start-up of a target system with an automatically initialized data area.

Instruction operand The *Series 32000* instruction operand is defined by the microprocessor architecture as one of nine possible addressing modes: register, immediate, absolute, register-relative, memory space, memory-relative, external, top-of-stack, or scaled index.

Integer constant An immediate integer value. Can be specified either in decimal, hexadecimal or octal format. Integers can be used within assembly expressions that are part of either an instruction or directive operand.

Link segment A special segment of the assembly program that corresponds to the .link section of the COFF file. The link segment defines a module's link table, thereby supporting *Series 32000* modularity. The actual link table entries are specified following the assembly .link directive.

Location counter A relocatable memory address of the current statement within the currently assembled segment.

Macro Procedure Known by the more common name: macro. Consists of legal assembly statements to be expanded on macro call, according to given parameters.

Native configuration When the compilation and execution of the compiled program are done on the same machine (the host and target machines are the same).

Object file A file that is the output of either the assembler or the compiler. It contains compiled code, data and additional control information such as relocation or symbolic information. The assembler's object file conforms to the COFF Common Object File Format.

Option The UNIX term for a parameter, specified on the command line, that is used to control the utility.

Output listing An optional assembler output of the assembled source file. It displays the original assembly source, along with additional useful information. Each source line has an annotated line number, segment type information, and the generated code or data. Macro expansions are also displayed where applicable.

Procedure Body A part of the assembly procedure support, defining the procedure code to be executed. Proper entrance and exit is ensured by beginning and ending the procedure body using the .begin and the .endproc directives, respectively.

Procedure Call A part of the assembly procedure support that calls either an assembly or a HLL procedure from an assembly code. Calling is done using the .call directive, with the operands being the procedure name and actual parameters.

Procedure Definition A part of the assembly procedure support, defining an assembly procedure. Assembly procedure is specified between .proc and .endproc directives. It consists of a procedure body and optional formal parameters, local variables, and registers to be saved.

Procedure Parameters A part of the assembly procedure defining formal parameters. Procedure parameters are defined after the .proc directive.

Procedure Variables A part of the assembly procedure defining local variables. Procedure variables are defined after the .var directive.

Qualifier The VMS term for a parameter, specified on the command line, that is used to control the utility.

Relative value A symbol or expression that specifies an address within one of the COFF sections or the corresponding assembly program segment. Because such addresses are not bound to actual memory locations until link-time, their value is relative to the base or starting address of the segment. Relative values are relocatable,

and have a relocatable entry in the generated COFF object file. They are resolved later at link-time.

Relocatable object files Output of the assembly process. Relocatable object files may be linked to create executable files for a *Series 32000* target.

Repetitive Macro Statement Sequences of statements specified between the repeat or .irp directives and the .endr directive. They are generated repeatedly according to an iteration index specified with the .repeat directive.

Return value An integer or floating-point value that is returned by a function through register R0 or F0, respectively, according to the GNX standard calling convention.

Series 32000 instruction A *Series 32000* instruction mnemonic. Should appear within a text section in order to be executed.

Source file Assembler input. The source file is a text file containing the source program to be assembled.

Static segment A special segment of the assembly program. It follows the .static directive, and corresponds to the .static COFF section. The static segment is used for defining a static base area for each module in the *Series 32000* modularity mode. The static base area maintains specific data for each module, which is considered to be part of the module's environment (i.e. it is saved when switching to another module and restored on returning to the module). The static segment is especially useful in real-time embedded applications.

Target machine The machine on which the program being compiled will run.

Text segment Contains code for execution, follows the .text directive and corresponds to the .text section of the COFF file.

Uninitialized data segment Contains uninitialized data, follows the .bss or the .udata directive. Corresponds to the .bss section of the COFF file.

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